

Tracing glacial meltwater from the Greenland Ice Sheet to the ocean using gliders

Katharine R. Hendry¹, Nathan Briggs², Stephanie Henson², Jacob Opher^{3,4},
J. Alexander Brearley³, Michael P. Meredith³, Melanie J. Leng^{5,6}, Lorenz
Meire^{7,8}

¹School of Earth Sciences, University of Bristol, Wills Memorial Building, Queens Road, Bristol, BS8 1RJ, UK

²National Oceanography Centre, European Way, Southampton, SO14 3ZH, UK

³British Antarctic Survey, High Cross, Madingley Road, Cambridge, CB3 0ET, UK

⁴School of Environmental Sciences, University of East Anglia, Norwich Research Park, Norwich, NR4 7TJ, UK

⁵National Isotope Environmental Facility, British Geological Survey, Keyworth, Nottingham, NG12 5GG, UK

⁶Centre for Environmental Geochemistry, School of Biosciences, Sutton Bonington Campus, University of Nottingham, Loughborough, LE12 5RD, UK

⁷Department of Estuarine and Delta Systems, Royal Netherlands Institute for Sea Research, Yerseke, The Netherlands

⁸Greenland Climate Research Centre, Greenland Institute of Natural Resources, Nuuk, Greenland

Key Points:

- We report bio-optical data from a glider deployment off SW Greenland
- High optical backscatter is associated with both high-chlorophyll surface waters and coastal water mass
- Meltwaters enriched in fluorescent dissolved organic matter cross the strong boundary current into the Labrador Sea

Corresponding author: Katharine Hendry, k.hendry@bristol.ac.uk

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Abstract

The Greenland Ice Sheet (GrIS) is experiencing significant mass loss and freshwater discharge at glacier fronts. The freshwater input from Greenland will impact the physical properties of adjacent coastal seas, including important regions of deep water formation and contribute to global sea level rise. However, the biogeochemical impact of increasing freshwater discharge from the GrIS is less well constrained. Here, we demonstrate the use of bio-optical sensors on ocean gliders to track biogeochemical properties of meltwaters off southwest Greenland. Our results reveal that fresh, coastal waters, with an oxygen isotopic composition characteristic of glacial meltwater, are distinguished by a high optical backscatter and high levels of fluorescing dissolved organic matter (FDOM), representative of the overall coloured dissolved organic matter pool. Reconstructions of geostrophic velocities are used to show that these particle and FDOM-enriched coastal waters cross the strong boundary currents into the Labrador Sea. Meltwater input into the Labrador Sea is likely driven by mesoscale processes, such as eddy formation and local bathymetric steering, in addition to wind-driven Ekman transport. Ocean gliders housing bio-optical sensors can provide the high-resolution observations of both dissolved and particulate glacially-derived material that are needed to understand meltwater dispersal mechanisms and their sensitivity to future climatic change.

Plain Language Summary

The Intergovernmental Panel on Climate Change Special Report on the Oceans and Cryosphere in a Changing Climate recently reported that the Greenland Ice Sheet is extremely likely to experience significant mass loss in coming decades. The freshwater from the melting ice sheet and glaciers will change the density of the surrounding seawater, with major implications for global ocean circulation and will contribute to sea level rise. The meltwater input could also change the chemistry of the ocean, but the extent to which this is the case is poorly understood. One of the challenges is to obtain high-resolution observations of ocean physical and chemical properties around Greenland. Here, we show that such observations are possible using autonomous underwater vehicles. Our results show that fresh, coastal waters, with the chemical fingerprint of glacial meltwater, can be picked out using widely available optical sensors. Reconstructions of ocean currents from the glider velocities show that these particle and organic matter rich waters can cross from the coastal waters into the open ocean, potentially influencing marine biological production on a wide geographical scale.

1 Introduction

The northern high-latitude regions are undergoing some of the fastest environmental changes seen globally in recent decades (Meredith et al., 2019). The Greenland Ice Sheet (GrIS) is experiencing significant mass loss via ice discharge at glacier fronts and surface melting (Enderlin et al., 2014; Felikson et al., 2017; van den Broeke et al., 2017; Shepherd et al., 2020). The oceans surrounding the GrIS are sensitive to the release of glacial meltwaters, as the resulting freshening may influence the density structure and stratification in regions where deep water-masses are formed (Carmack et al., 2016; Proshutinsky et al., 2015; Yang et al., 2016). Subglacial runoff is also characterised by a high concentration of organic matter and inorganic nutrients in both dissolved and particulate form, especially iron and dissolved silicon (Bhatia et al., 2013; Hawkings et al., 2014, 2017; Meire et al., 2016). Tracking these meltwaters and glacial particulate inputs is key to understanding not only physical changes in the oceans but potential shifts in regional nutrient supply and marine ecosystem structure. However, nutrients from meltwaters are trapped abiotically and biologically within fjord systems, and the extent to which glacially-derived, nutrient-rich material reaches the coastal shelf seas and crosses boundary currents into the open ocean is not sufficiently established (Hopwood et al., 2015, 2020). Fur-

75 thermore, the role of benthic cycling in supplying nutrients to fjords and glaciated margins
76 in the high-latitudes, relative to direct meltwater sources, is not fully understood
77 (Koziorowska et al., 2018; Zaborska et al., 2018; Ng et al., 2020). Recent evidence using
78 a variety of physical and geochemical approaches revealed that a significant proportion
79 of freshwater and glacially derived material extends off the southwest (SW) Greenland
80 shelf into the region of the boundary current (Hendry et al., 2019). Satellite observations
81 and ecosystem models also support a link between glacial melt and summer phytoplankton
82 blooms in this area (Arrigo et al., 2017; Oliver et al., 2018).

83 There are a number of different methodologies for tracking meltwaters and sediment
84 inputs in coastal seas. Ship-deployed sensors can be used to trace changes in physical
85 and bio-optical properties associated with meltwaters (Pan et al., 2019). Geochemical
86 methods can be used, when different inputs represent different compositional endmembers,
87 allowing relative contributions of glacial vs. non-glacial sources to be calculated by mass
88 balance. For example, dissolved oxygen concentrations, alkalinity, or oxygen isotope
89 composition ($\delta^{18}\text{O}$) of seawater can be used together with salinity variations to calculate
90 the relative contribution of meteoric sources, dominated by glacial meltwater in
91 glaciated margins, versus sea-ice to the freshwater budget (Jenkins, 1999; Meredith et al.,
92 2008; Hendry et al., 2018; Biddle et al., 2015). Remote sensing of meltwaters, and
93 their biogeochemical impacts, is also possible using satellite ocean colour algorithms in
94 combination with regional modelling (McGrath et al., 2010; Arrigo et al., 2017).

95 However, there are a number of limitations surrounding both ship-based and remote
96 sensing approaches to tracking meltwater, including ship accessibility and cost, seasonal
97 coverage, and weather dependence.

98 Autonomous, underwater gliders provide solutions to a number of these limitations.
99 These gliders are ideal for high-latitude coastal work, providing continuous, direct
100 measurements from beneath the sea-surface, including under harsh weather conditions and
101 in regions that can be inaccessible by larger ships (Fan et al., 2013; Rudnick, 2016; Kohut
102 et al., 2013; Carvalho et al., 2016). Gliders can be fitted with a wide array of sensors,
103 allowing the collection of high-resolution physical and bio-optical measurements, and -
104 when deploying multiple vehicles - can be used to obtain a more synoptic view of the
105 physical and biological processes active in the region of interest (Meyer, 2016). Here,
106 we present the first bio-optical glider observations off the SW coast of Greenland and
107 show how they can be used together with shipboard and Biogeochemical-Argo (BGC-Argo)
108 float data to track the dissolved and particulate inputs from GrIS meltwaters into the
109 Labrador Sea.

110 2 Methods

111 2.1 Field methodology

112 Two Slocum gliders (units 331 Coprolite and 439 HSB) were deployed during RRS
113 Discovery expedition DY081 on July 17th 2017 at 62.9°N, 52.6°W, approximately 40 km
114 off the Greenland shelf break, travelled North along the coast in a zig-zag pattern between
115 the shelf and deep waters, and were recovered 8 days later from 63.7°N, 53.1°W and
116 62.9°N, 52.7°W respectively on July 24th 2017 (Fig. 1, (Hendry et al., 2021)). Gliders
117 profiled from the surface to 1000 m, except during the two excursions onto the shelf,
118 once south and once north of the Godthåb Trough, where they followed the bathymetry.
119 Each glider track was divided into three on-off shelf sections to quantify the temperature,
120 salinity, chlorophyll-a (Chl a) and FDOM across the boundary current system, which
121 runs parallel to the shelf break. The mean position of each profile is shown using the
122 inverted triangles at the top of each of the section figures (Fig. 2,3 and 5). In brief, the
123 mean distance between profiles for glider 331 was 0.52 km, 0.47 km and 0.37 km for
124 sections 1,2 and 3 respectively. For glider 439, the equivalent distances were 0.56 km,
125 1.03 km and 1.37 km. Note the spacing is much closer for the shallower dives on the
126 shelf (0.1-0.2 km) compared with in the deep part of each section (3-4 km). Each of the on-shelf

127 glider profiles, generally in 100-200 m water depth, took around 10-20 minutes to com-
128 plete, while a 1000 m off-shelf profile took around 90 minutes. Each glider was fitted with
129 a pumped CTD and bio-optical sensors (WET Labs puck; for configuration see Supple-
130 mentary Information Table S1). These bio-optical sensors measure optical backscatter-
131 ing (in the form of the volume scattering function), chlorophyll fluorescence, and UV flu-
132 orescence for fluorescing dissolved organic matter (FDOM, see Supplementary Text S1),
133 a subset of coloured dissolved organic matter (CDOM).

134 Prior to deployment, a conductivity-temperature-depth (CTD) profiler and rosette
135 was deployed for calibration purposes, and salinity was calibrated against bottle mea-
136 surements (Hendry et al., 2019). Glider temperature and salinity (T and S, here corrected
137 for thermal lag) showed no significant offsets when compared to the shipboard CTD data.
138 Whilst a CTD was not deployed upon glider recovery for verification, a comparison of
139 T/S data between dive profiles from early and late in the deployment do not show any
140 significant offset (Supplementary information, Fig. S2), which strongly suggests that there
141 was no significant sensor drift during the deployment.

142 Glider data and positional information can be used to determine current veloci-
143 ties along the glider path during its mission. Calculating the full velocity field requires
144 an accurate reference velocity estimate. While the glider itself does not provide this, care-
145 ful processing of the depth-averaged velocities between pairs of glider surfacings yields
146 a depth-integrated transport field against which the geostrophic shear from the glider
147 T/S can be referenced. The depth-averaged velocities were first corrected for surface drift
148 (Merckelbach et al., 2010), and then detided using the barotropic tide solution obtained
149 from the Oregon State University Model (Egbert & Erofeeva, 2002), as instantaneous
150 velocities are heavily influenced by tidal motions not relevant to the geostrophic field.
151 To remove other sources of high-frequency variability, the detided velocities were then
152 smoothed using a Laplacian spline interpolant over 6 km, with gridding at 2 km in the
153 horizontal and 5 m in the vertical, from a baseline at 0 km oriented perpendicular to the
154 shelf break. There were typically up to 10 profiles per 2 km on the shelf, and one pro-
155 file per 2 km in the deep region offshore. This gridding allows for the removal of high-
156 frequency variability in the velocity field not associated with geostrophic transports (e.g.
157 inertial motions). Finally, the T and S fields were identically filtered before using the depth-
158 averaged velocities to reference the T- and S-derived geostrophic shear.

159 The bio-optical properties were derived using the calibration curves from the man-
160 ufacturer. The optical particle backscattering coefficient (b_{bp} , in m^{-1}) was calculated
161 by firstly correcting the volume scattering function (at an angle of 124° and at a wave-
162 length of 650 nm, in $m^{-1} sr^{-1}$) for scattering due to seawater and, secondly, integrat-
163 ing across all backward angles using an assumed angular dependency for marine parti-
164 cles (Zhang et al., 2009; Sullivan et al., 2013).

165 The chlorophyll data from each profile were dark-corrected by subtracting from each
166 value the median chlorophyll below 300m (Thomalla et al., 2017). Quenching was iden-
167 tified from all daylight profiles (from Nuuk sunrise to sunset plus 2.5 hours) and corrected
168 based on published methods (Swart et al., 2015). Briefly, the maximum Chl a: b_{bp} ratio
169 within the mixed layer, and the depth of this maximum, were found for each profile; all
170 chlorophyll data above this depth were corrected for quenching by multiplying the max-
171 imum Chl a: b_{bp} with the corresponding b_{bp} value (Supplementary Information Figure
172 S3). Note that this approach assumes that the particle population affected by quench-
173 ing has a constant Chl a: b_{bp} ratio.

174 Seawater samples were collected for $\delta^{18}O$ analysis, using standard Niskin bottles
175 attached to the CTD rosette on the RRS Discovery during expedition DY081 across a
176 grid within the glider transit area. The $\delta^{18}O$ measurements were made using the CO_2
177 equilibration method with an Isoprime 100 mass spectrometer plus Aquaprep device at
178 the British Geological Survey Stable Isotope Facility.

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2.2 Data analysis and interpretation methodology

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2.2.1 Meltwater input calculations

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We can use simple mass balance equations (Equations 1 and 2) to calculate glacial meltwater input, assuming the endmember salinity of glacial meltwater is zero (Biddle et al., 2015):

$$S_o = S_a A + S_{mw} (1 - A) \quad (1)$$

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$$A = \frac{S_o}{S_a} \quad (2)$$

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where S_o is the observed salinity, S_a is the average salinity of Subpolar Mode Water (SPMW) in the area (34.88), S_{mw} is the salinity of meltwater (0), A is the fraction of seawater, and $(1-A)$ is fraction of meltwater present. However, these calculations ignore the potential contribution of freshwater from other sources including sea ice within waters that originate in the East Greenland Current and that flow around the southern tip of Greenland (Cox et al., 2010). The contribution from non-glaciated runoff to the total freshwater flux is low and can be considered negligible (Bamber et al., 2018). Another approach to calculating the proportion of meltwater that can be used to validate the approach in Equations 1-2 is to use a mass balance calculation (Equations 3 - 5) that incorporates both salinity and oxygen isotope ($\delta^{18}\text{O}$) measurements (Meredith et al., 2008).

$$F_{spmw} + F_{me} + F_{si} = 1 \quad (3)$$

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$$F_{spmw} S_{spmw} + F_{me} S_{me} + F_{si} S_{si} = S_o \quad (4)$$

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$$F_{spmw} \delta_{spmw} + F_{me} \delta_{me} + F_{si} \delta_{si} = \delta_o \quad (5)$$

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where F_{spmw} , F_{me} , F_{si} are the calculated fractions of SPMW, meteoric and sea ice melt respectively (SPMW being the chosen ocean endmember), which sum to 1 by definition. The result is clearly dependent on the exact choice of endmembers for salinity (S_{spmw} , S_{me} , S_{si}) and $\delta^{18}\text{O}$ (δ_{spmw} , δ_{me} , δ_{si}) for the Irminger Water, meteoric and sea ice melt respectively. S_o and δ_o are the observed salinity and $\delta^{18}\text{O}$ of each sample.

Pearson correlation coefficients of the different bio-optical parameters relative to the calculated meltwater fractions were derived. Given the likelihood of autocorrelations within the timeseries datasets, the significance of the correlation coefficients were assessed taking into consideration the number of effective degrees of freedom. For N measurements, the autocorrelation, C , and the lags at which the correlations were computed, were assessed using a biased estimator by calculating the normalised cross-correlation of the parameters such that the autocorrelations at zero lag equal unity. Then the decorrelation scale, τ , and number of effective degrees of freedom, N_{eff} , were computed using Equations 6 and 7 respectively. The r values at both 95% and 99% significance levels, r_{sig} ,

213 were then computed for the given values of N_{eff} using a Gaussian error function, erf,
 214 for a given significance level (s , Equation 8).

$$\tau = \sum_{n=-N}^N C(n)\delta t \quad (6)$$

$$N_{eff} = \frac{N}{\tau} - 2 \quad (7)$$

$$r_{sig} = \text{erf}^{-1}(s) \sqrt{\frac{2}{N_{eff}}} \quad (8)$$

2.2.2 Argo float data and analytical methods

219 Fluorescing dissolved organic matter, FDOM, comprises only a subset of coloured
 220 organic matter, CDOM, which absorbs in the visible wavelengths. As the nature of or-
 221 ganic matter may vary spatially and temporally, for example as a result of differences
 222 in the relative contribution of marine versus terrestrial organic matter (Stedmon & Mark-
 223 ager, 2001) or sea-ice presence (Stedmon et al., 2007), it is non-trivial to determine to
 224 what extent FDOM measurements relate to CDOM more broadly, as assessed from ab-
 225 sorption data.

226 To assess regional significance and whether our FDOM data represents CDOM more
 227 generally, we can analyse the diffuse attenuation coefficient of downwelling light, K_d , at
 228 380, 412, and 490 nm using a spatially and temporally broader dataset from ten BGC-
 229 Argo floats in the Labrador and Irminger Seas (from Coriolis : <ftp://ftp.ifremer.fr/ifremer/argo>).
 230 Values of K_d are measured in units of inverse meters, and, in the visible wavelengths are
 231 dominated by absorption due to Chlorophyll, CDOM, and detrital matter. In order to
 232 isolate the contribution of CDOM from Chl and any phytoplankton-associated detrital
 233 matter, we used a type-I linear regression to find and remove the first-order dependency
 234 of K_d on Chl fluorescence for each float and for each wavelength of K_d , resulting in a K_d
 235 anomaly. For each float and each wavelength, the relationship between this K_d anomaly
 236 and FDOM was determined, again by type-I linear regression.

3 Results

3.1 Physical Oceanography

239 The CTD and glider T and S profiles are consistent with known regional hydrog-
 240 raphy. Coastal, surface water (in upper 100 m) that consists of modified Arctic Water/meltwater,
 241 overlies warmer North Atlantic Water (temperature $>3^\circ\text{C}$, salinity <34.5 ; Fig. 2) with
 242 a temperature maximum at approximately 400 m water depth, most likely representing
 243 the core of Irminger Water (McCartney & Talley, 1982) or upper Subpolar Mode Wa-
 244 ter (uSPMW) (Rysgaard et al., 2020). The orientation and the velocity maximum of the
 245 geostrophic current between glider sections 2 and 3 (approximately $30\text{-}40\text{ cm s}^{-1}$) are
 246 in close agreement with those calculated from CTD stations referenced to lowered Acous-
 247 tic Doppler Current Profiler (ADCP) along Godthåb Trough (Hendry et al., 2019).

248 The mass balance for the seawater samples collected during DY081 assumed end-
 249 member values that have been presented elsewhere (Hendry et al., 2019) and indicates
 250 that the surface waters over the shelf comprise up to 5-6% meteoric water, which can

251 be assumed to be dominated by glacial meltwater in this region, and a smaller propor-
252 tion of freshwater input from sea ice (<1.5%). Using the glider data only (Equations 1-
253 2), the calculated meteoric water inputs range from approximately 5% on the shelf to
254 the south of the study area, to 2-3% off the shelf (Fig. 3). The meteoric (i.e. meltwa-
255 ter) proportions calculated for the bottle samples collected on the ship within the Nuuk
256 area using the two methods (Equations 1-2 and Equations 3-5) correlate very strongly
257 ($r = 0.99$, $p < 0.001$, $n = 144$) with a Root Mean Square error (RMS) of 0.6%. These re-
258 sults indicate that our simple mass balance calculation from Equations 1-2 based on the
259 glider data are a reasonable indication of relative meltwater input.

260 3.2 Bio-optical properties

261 The chlorophyll (Chl a) fluorescence data show a strong subsurface concentration
262 maximum (Fig. 3), with typical concentrations of 4 mg m^{-3} , or greater, at 10-20 m, match-
263 ing well with bottle pigment data from DY081, with mean extracted Chl a concentra-
264 tions in the top 20 m of 5.5 mg m^{-3} (standard deviation 3.4 mg m^{-3}) (Hendry et al.,
265 2019). The shallow chlorophyll maximum is consistent with the surface water stratifi-
266 cation and relatively low light penetration (shipboard sensors indicate the 1% photosyn-
267 thetically active radiation depth of approximately 20-30 m). The optical particle backscat-
268 tering coefficient (b_{bp}) shows elevated values in the subsurface, at least $4 \times 10^{-3} \text{ m}^{-1}$
269 or more down to 20-50 m. In contrast, UV FDOM shows elevated concentrations ($>1.8 \text{ ppb}$
270 over shelf, 1.6-1.7 ppb off shelf) from the subsurface down to 100-200 m (Fig. 3), dis-
271 playing similar spatial and temporal distributions to cold, fresh surface waters. There
272 is a reduced FDOM concentration in the near surface, likely due to photo-degradation
273 (Mopper et al., 2015), which acts as a major sink of CDOM in the ocean (Fig. 3).

274 The bio-optical properties of the water show significant relationships with the pres-
275 ence of meltwater, as calculated from equations 1 and 2. The strongest correlation is ob-
276 served for FDOM, in particular between 50 and 200 m water depth (Table 1). The re-
277 lationship between meltwater percentage and FDOM breaks down at the very surface,
278 with a switch from a positive to a negative correlation at meltwater concentrations greater
279 than approximately 3.5%, as a result of FDOM breakdown by photoreactions (Mopper
280 et al., 2015). The relationship between FDOM and meltwater shows that there is a second-
281 order dependence on latitude that is consistent between the two gliders, potentially re-
282 vealing an along-shelf gradient with a higher FDOM concentration in the more northerly
283 freshwater sources (Fig. 4). The Chl a and b_{bp} observations show less significant corre-
284 lations with meltwater (Table 1), which likely reflects the multiple transported and *in*
285 *situ* sources of chlorophyll, and biological and abiological particles detected by backscat-
286 ter.

287 The relationship between K_d380 and salinity was negative for all Argo floats, with
288 correlations strongest for individual floats that encountered the greatest range of salin-
289 ities (r ranging between 0.22 and 0.87). The average regression slopes of K_d on Chl flu-
290 orescence for the Argo float data are reported in the supplementary information (Fig.
291 S8). We found significant positive relationships between our K_d anomalies and FDOM,
292 and the slope of this relationship decreased with increasing wavelength, approximately
293 following a negative exponential with coefficient -0.017, consistent with the typical spec-
294 tral absorption of CDOM (Helms et al., 2008). This finding mirrors previous broader-
295 scale findings (Organelli et al., 2017) and indicates that our FDOM data are represen-
296 tative of the broader CDOM pool, strengthening the link between our study and stud-
297 ies that only report CDOM absorption data.

4 Discussion

4.1 Factors affecting the backscatter distribution

Biological material (living and dead algal cells) is likely to contribute to the particulate material in the water column that results in the observed optical backscatter distribution, especially in the near-surface waters. There is a strong correlation between quenching-corrected Chl a and b_{bp} in surface and subsurface waters <100 m (linear correlation $r = 0.89$, $r_{sig} = 0.77$; 99% significance level; $N_{eff} = 9$). This observation is consistent with previous findings from glider data that indicate that algae contribute to the particulate load in open ocean regions of the Labrador Sea (Frajka-Williams et al., 2009) and other high-latitude regions (Cetinić et al., 2015; Carvalho et al., 2016), despite differing optical behaviours between different algal types (Schofield et al., 2015).

However, visual inspection of the glider bio-optical data suggests that the meltwater-rich shelf waters have more particulates not attributable to phytoplankton. When high Chl a datapoints are removed ($>0.2 \text{ mg m}^{-3}$), the relationship between T,S and b_{bp} shows that fresher, colder waters are generally associated with higher particulate content (Fig. 5), suggesting that particles associated with the coastal waters are likely an important source of optical backscatter. Another potential method to illustrate the abiological input of particulates is to calculate the anomaly in the relationship between chlorophyll and backscatter for the shelf regions. To do so, we constructed a linear regression model between backscatter and chlorophyll for the deep profiles only ($>900 \text{ m}$ water depth). We then used this model to calculate the expected backscatter for the shallow profiles ($<100 \text{ m}$ water depth) and associated anomaly with observations. Whilst this anomaly is centred around zero for the deeper profiles, it is offset towards positive values in shallower sites (Fig. 5), suggesting these shallower sites are characterised by a different chlorophyll-to-backscatter relationship. This different bio-optical characterisation could be driven by changes in plankton community (biological factors that could create a positive b_{bp} anomaly include: less chlorophyll per cell, greater b_{bp} per cell, or a lower ratio of autotrophic plankton to non-chlorophyll-bearing heterotrophic plankton) or because there is an additional source of particulates other than algae.

The most likely candidates for this source are sediments transported by glacial meltwater and resuspended shelf sediments. Glacial meltwaters are enriched in fine, particulate matter from a combination of subglacial weathering processes and entrainment of proximal sediments in buoyant meltwater plumes (Chu et al., 2012; Andrés et al., 2020). Satellite observations indicate that the areal extent of such sediment-enriched plumes off Greenland correlate with melt extent (Tedstone & Arnold, 2012), indicating a close association between particulate and meltwater supply. Furthermore, meltwater-derived waters have been shown in both Greenlandic and Antarctic fjords to influence backscatter in glider and ship-deployed sensor data (Holinde & Zielinski, 2015; Pan et al., 2019). However, it is also possible that the elevated backscatter is a result of sediment resuspension on the shelf, in particular in response to storm disturbance (with wind speeds up to 15 ms^{-1} during Julian Day 199) during the glider deployment, as has been observed in other studies (Glenn et al., 2008; Miles et al., 2015). This interpretation is supported by depth profiles from nearby ship-board CTD casts, which indicate an increase in turbidity in the bottom 100-150 m within the main trough that cuts across the shelf and that was occupied by the gliders (Supplementary Information, Fig. S7). The increase in backscatter anomaly and turbidity with depth (Fig. 5) suggests that there could be a contribution from resuspended material, a phenomenon also observed near the Dotson Ice Shelf in Antarctica (Miles et al., 2016).

In summary, our results indicate that there is a complex relationship between meltwater and water column b_{bp} , which is likely a result of multiple controls on backscatter from particles characterised by different optical properties and from different sources, including *in situ* algal communities and resuspension, in addition to potential glacial inputs.

4.2 Origin and fate of coloured dissolved organic matter

4.2.1 Source of FDOM in coastal waters

Below the surface mixed layer, the strongest spatial correlation with FDOM is with the prevalence of cold, fresh waters (Fig. 3 and 4), indicating that meteoric input plays a strong role in CDOM supply. However, there is also a relatively weak correlation between FDOM and Chl *a* in our data indicating, as with the optical backscatter, that *in situ* biology could be a secondary source of CDOM to the water column. For example, *Phaeocystis* blooms from the Labrador Sea have been observed to produce quantities of mucilaginous matrix that could contribute to the DOM pool either directly or via bacterial decomposition (Alderkamp et al., 2007; Wassmann et al., 1990). The weak correlation between FDOM and Chl *a* in our data likely arises because dissolved organic matter has multiple sources (terrestrial and open-ocean) and can have much longer residence time than Chl *a* in the ocean. A sedimentary source of FDOM is also possible (Luek et al., 2017). However, a sediment source is unlikely to result in a strong correlation between FDOM and meteoric water, as resuspension will show stronger associations with either tidal or wind-driven deep mixing (Crusius et al., 2017), rather than meltwater inputs.

Given the statistically significant relationship between meteoric water and FDOM sensor measurements, glacial meltwaters are a strong contender for the CDOM source, given that meltwaters contain dissolved organic carbon (Hood et al., 2015; Vick-Majors et al., 2020). However, existing field measurements indicate highly variable CDOM distributions both within and between Greenlandic fjords, potentially resulting in heterogeneous inputs from different upstream fjords, and secondary variability in the relationship between CDOM and salinity in the coastal ocean (Fig. 4). Although icebergs can release CDOM (Biddle et al., 2015), marine-terminating glacial fjords tend to have relatively low CDOM concentrations relative to land-terminating glacial fjords, which can be characterised by higher CDOM concentrations especially at the point of freshwater inflow (Lund-Hansen et al., 2010; Holinde & Zielinski, 2016). In addition, deglaciated watersheds tend to have higher dissolved organic matter concentrations than glacially-fed rivers, and are derived more from terrestrial vegetation and soils rather than *in situ* algal biomass (Pain et al., 2020), which could contribute further CDOM to the ocean. While some fjords tend to show inverse relationships between CDOM and salinity (indicating a freshwater source) others show a positive relationship (indicating a marine source) or no relationship at all (Murray et al., 2015; Mascarenhas & Zielinski, 2019). In Godthåbsfjord, a fjord system to the north of our study area fed by a large marine-terminating glacier in addition to a number of glacially-fed rivers, previous studies have revealed either a weak positive or lack of relationship between CDOM and salinity (Murray et al., 2015; Mascarenhas & Zielinski, 2019). However, further work is required to elucidate the role of photochemical reactions in shallow coastal waters, and their impact on the relationship between meltwaters and CDOM content at the fjord surface.

Arctic-derived freshwater is likely an important source of CDOM in fjords and coastal regions in Northeast Greenland as a result of continental input from large Arctic rivers and shelf-sediment interaction being transported southwards by the East Greenland Current; however, this particular input is likely diminished as the waters flow into the West Greenland Current (Stedmon et al., 2015; Murray et al., 2015; Dmitrenko et al., 2017). There could be an additional contribution from sea-ice CDOM (Norman et al., 2011; Xie et al., 2014; Gonçalves-Araujo et al., 2016), although the salinity- $\delta^{18}O$ mass balance suggests a stronger influence from meteoric waters as opposed to sea-ice melt (Hendry et al., 2019).

4.2.2 Tracing bio-optical properties across boundary currents

The glider sections bisected the West Greenland Current system three times during their deployment (Fig. 1). This system comprises a strong hydrographic front be-

403 tween the coastal water and the offshore Irminger Water or SPMW. Several previous stud-
404 ies (Prater, 2002; Rykova, 2010) have documented that this system is subject to signif-
405 icant baroclinic instability, which can lead to the formation of enclosed eddies transport-
406 ing shelf water into the ocean interior.

407 To assess qualitatively the degree to which terrestrial or shelf-derived material (e.g.
408 FDOM) interacts with this unstable current system, geostrophic velocities were calcu-
409 lated using the glider density profiles and these estimates overlain on gridded FDOM con-
410 centration fields in Fig. 6. The boundary current at our study site has two or three sur-
411 face intensified northward velocity cores in the top 200 m of the water column (Fig. 6),
412 which may either reflect eddy or meander activity of the current itself, or possibly steer-
413 ing of the current by the complex topography of Godthåb Trough, the mouth of which
414 is crossed by Section 2 (Hendry et al., 2019). Either way, while the highest FDOM con-
415 centrations are found on the shelf itself inshore of the main boundary current, there is
416 significant evidence for enhanced FDOM being present across the boundary current in
417 the top 100 m of the water column even into the deep basin of the Labrador Sea (e.g.
418 Section 3, Fig. 6c, at 35 km along the baseline). Furthermore, the significant correla-
419 tion between FDOM and calculated meltwater is maintained when the inshore profiles
420 are excluded (e.g. for profiles in water depth >900 m, $r = 0.82$, $r_{sig} = 0.62$ for 99% sig-
421 nificance for glider 331). This suggests that at least a proportion of the shelf-derived FDOM
422 is transported across the boundary current into the interior of the Labrador Sea.

423 *4.2.3 FDOM in the Labrador Sea*

424 We used BGC-Argo data from the Irminger and Labrador Seas to assess regional
425 relationships between FDOM and salinity. The BGC-Argo dataset was divided into dif-
426 ferent regions, and compared to the mean surface currents (Fig. 7). When floats enter
427 the East Greenland Current from the Irminger Sea, there is already an existing fresh-
428 water signal with fairly high FDOM and CDOM (K_d380), relative to the water just out-
429 side the current. As the floats swing around to the west coast of Greenland, they start
430 to encounter water with much lower salinity and higher FDOM. However, without any
431 float data from the east Greenland shelf, it is challenging to quantify the freshwater in-
432 puts from west Greenland relative to the inherited signal from the northern Irminger Sea
433 or the Arctic. As the floats travel north, there is a strong input of fresh, high FDOM
434 water around the margins of the Labrador Sea, with an attenuation of the signal into
435 the central Labrador Sea. Our proxy for CDOM (K_d380) tells a similar story to FDOM,
436 although not identical, with some high K_d , low FDOM measurements in the central Labrador
437 Sea.

438 *4.2.4 Outlook*

439 The Labrador Sea basin has experienced some of the largest relative increases in
440 freshwater flux from Greenland in recent decades with significant implications for deep
441 water convection and basin-wide biogeochemistry. Whilst there are several sources of fresh-
442 water input into the Labrador Sea, most (60%) of the observed increase in freshwater
443 input into the Labrador Sea basin over recent decades originates from the Greenland ice
444 sheet (Yang et al., 2016). In our study location, there is likely an accumulation of fresh-
445 water from along the West Greenland coast, in addition to input from East Greenland,
446 observed in both physical data and models (Yang et al., 2016; Luo et al., 2016) and uranium-
447 series isotope tracers (Hendry et al., 2019). This accumulated freshwater eventually en-
448 ters the Labrador Sea, over timescales of 3-12 months, via baroclinicity, eddy formation
449 and local bathymetric steering (Yang et al., 2016), in addition to wind-driven Ekman
450 transport (Schulze Chretien & Frajka-Williams, 2018; Castelao et al., 2019). Ocean glid-
451 ers with bio-optical sensors have the capability to provide the high-resolution observa-
452 tions that are required to understand these mesoscale processes, their sensitivity to fu-
453 ture climatic forcing, and their role in supplying both freshwater and glacially-derived

454 dissolved and particulate constituents to the open ocean. However, further work is re-
455 quired to make the use of bio-optical properties measured from autonomous platforms
456 for tracking meltwater off West Greenland more robust. In particular, there is an out-
457 standing question of the potential contribution of both freshwater, FDOM, and partic-
458 ulates from sources in addition to the GrIS. In particular, there is a need for better con-
459 straints on the input of FDOM from i) Arctic rivers and sea ice melt, transported via
460 the Fram Strait and East Greenland Current, and ii) sedimentary sources. More infor-
461 mation from the deployment off East Greenland of BGC-Argo floats and gliders, together
462 with further processed-based studies of shelf-sediment interactions, would help to con-
463 strain the relative inputs of FDOM from the Arctic, East and West Greenland shelves.

464 5 Conclusion

465 Bio-optical measurements from gliders can be used to infer the distribution at high
466 spatial and temporal resolution of glacial meltwaters and particle inputs, which origi-
467 nate off the glaciated margin of SE Greenland and cross the strong boundary currents
468 into the open ocean. Optical backscatter signals are a result of suspended biomass, in-
469 cluding algal cells, in addition to glacially sourced particles, which can be observed in
470 the dataset when corrected for correlation with Chl *a*. Fluorescing dissolved organic mat-
471 ter (FDOM) broadly reflects the wider coloured dissolved organic matter (CDOM) pool,
472 and shows strong spatial correlations with cold, fresh meltwaters, which comprise a sig-
473 nificant proportion of meteoric (predominantly glacial) inputs, both in our glider obser-
474 vations and in BGC-Argo float data. Further work into the relationship between the flu-
475 orescing and scattering properties of particles and dissolved constituents using ocean glid-
476 ers could provide a means to investigate the nature of glacial melt reaching the open ocean,
477 and its spatial and temporal variability in other regions.

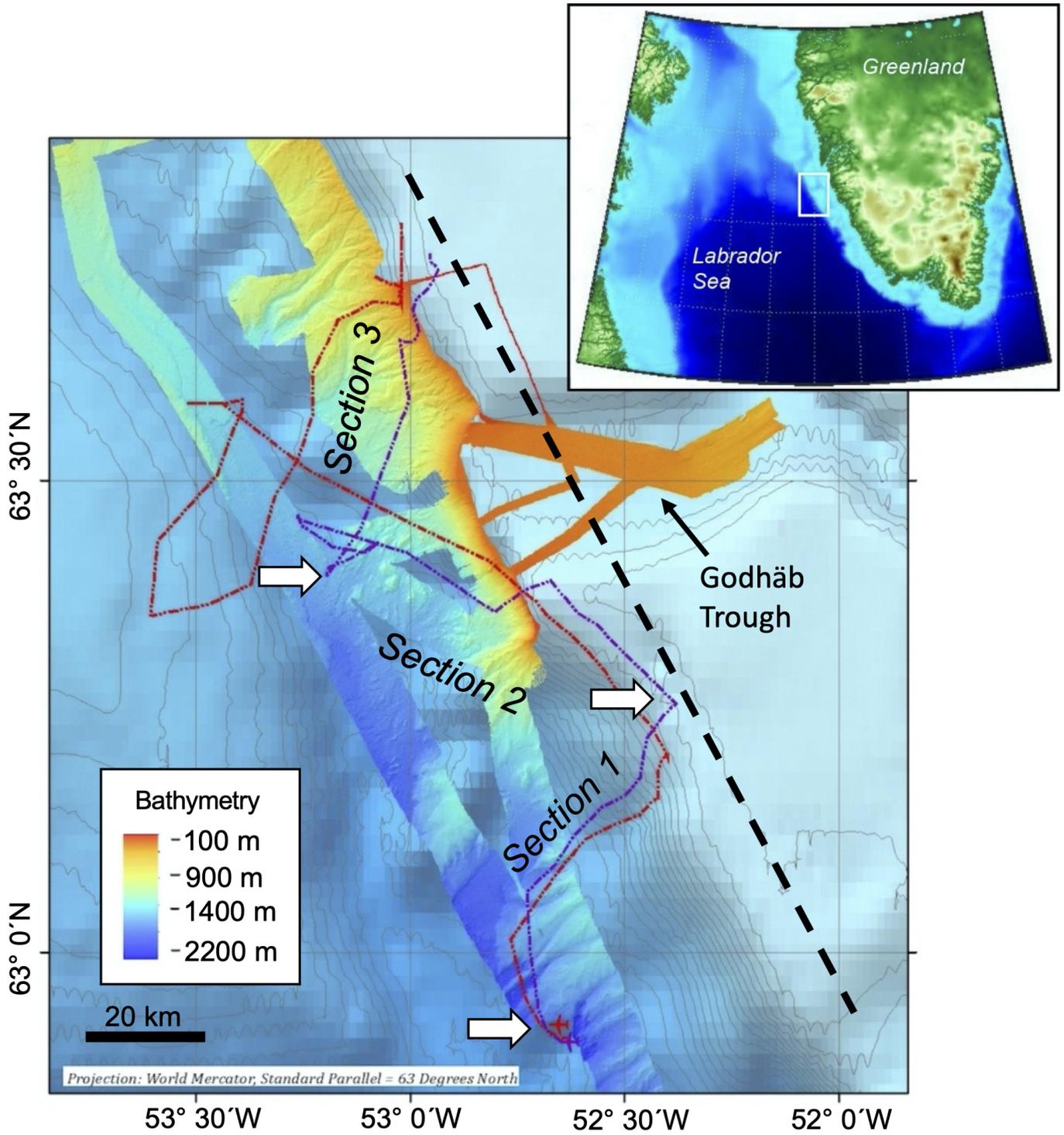


Figure 1. Map of area and glider tracks: Field study area and map of glider starting positions and tracks (dotted lines) for gliders 331 (purple) and 439 (red). Location of study area shown by white box in insert. Dashed line shows baseline used in Figure 2 for each of Section 1-3. Arrows mark the start of each section. Contoured ETOPO1 bathymetry data overlain with ship-board high-resolution bathymetry data from DY081 (Hoy et al., 2018). Produced in Mercator projection with a standard parallel of 63°N.

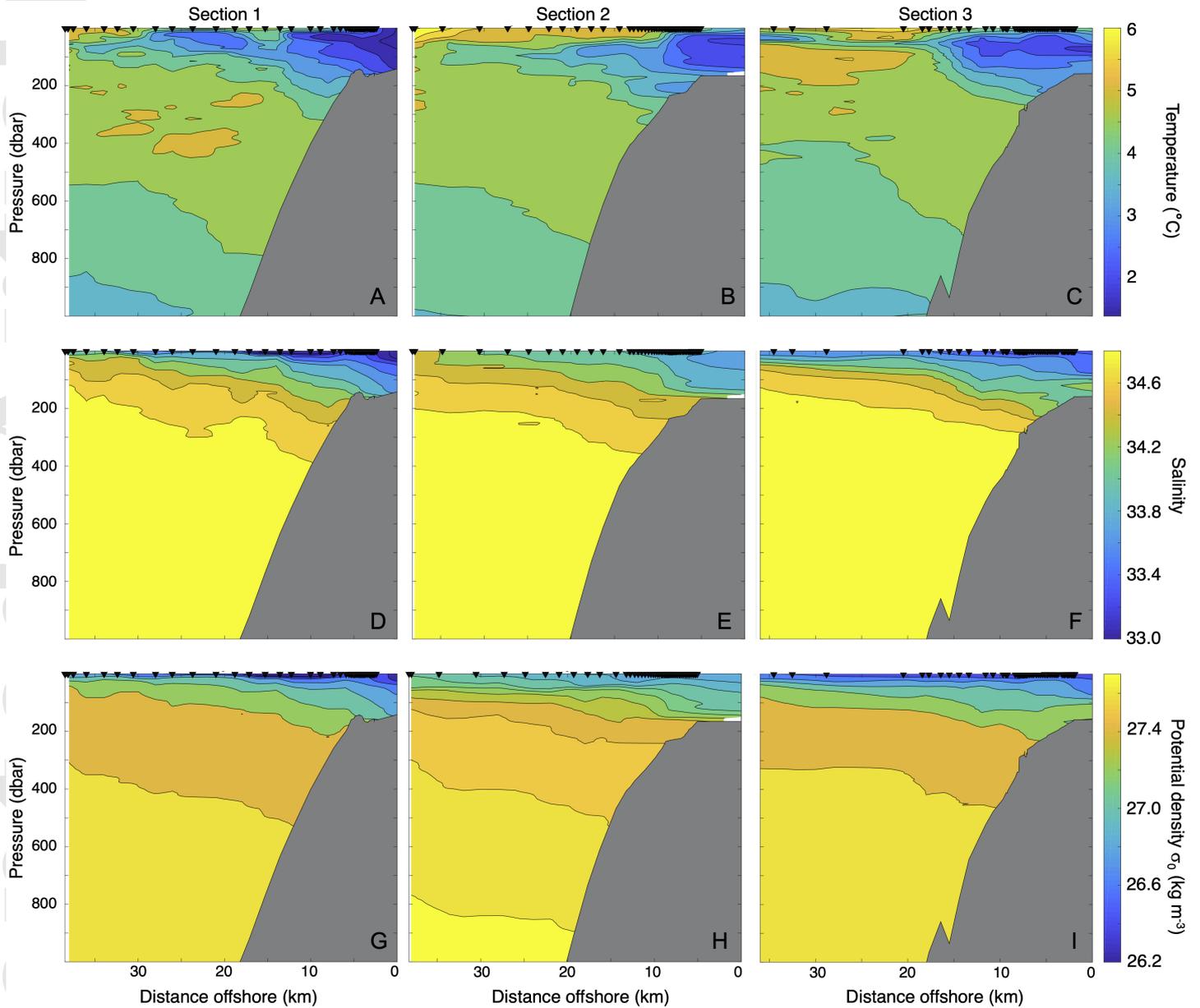


Figure 2. Temperature (A-C), salinity (D-F) and potential density (G-I) profiles from glider 331 along each section 1-3 from Figure 1. For temperature, salinity and potential density profiles of glider 439, see Supplementary Information (Fig. S1). Triangles show where the glider surfaced.

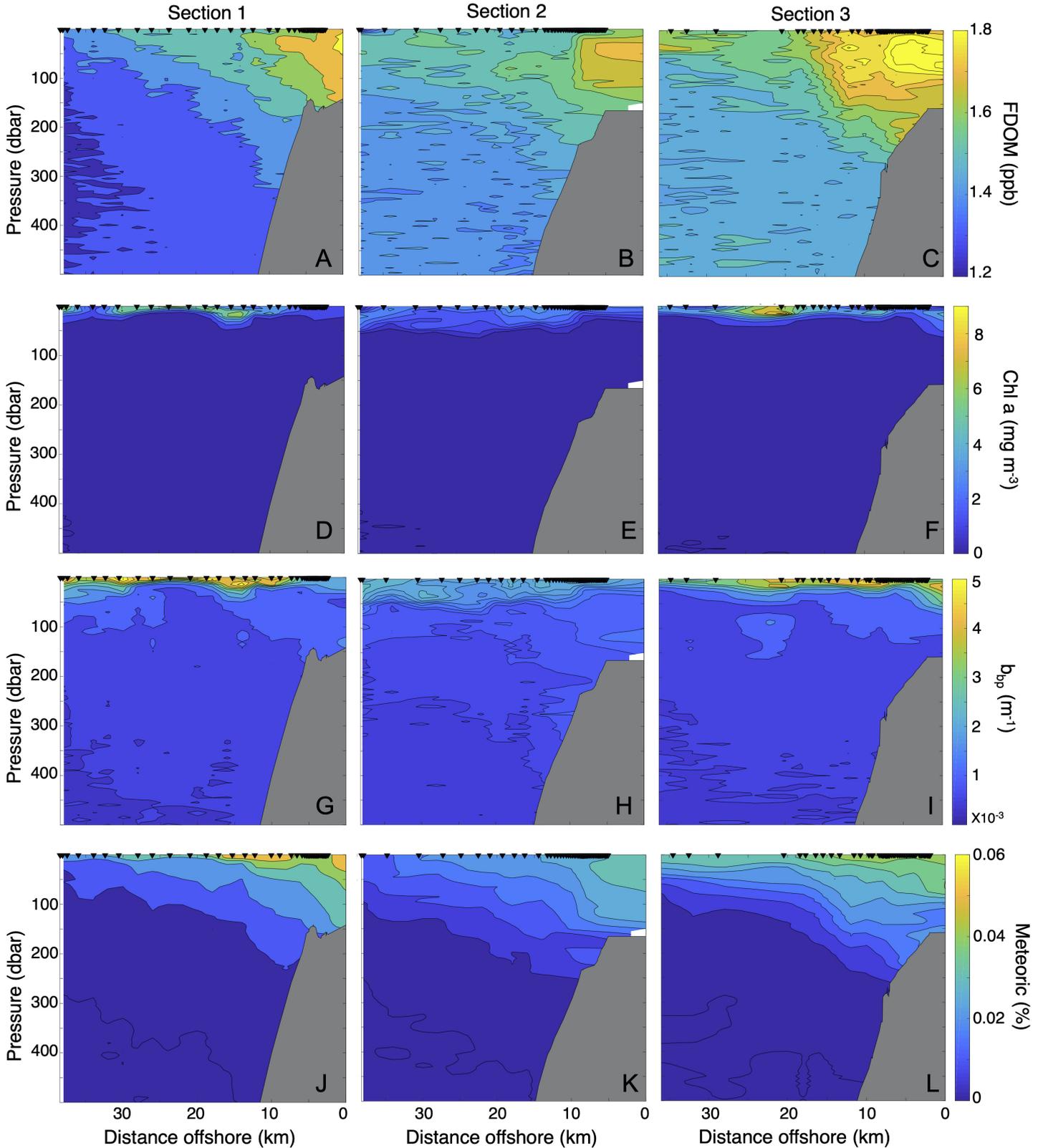


Figure 3. (A-C) FDOM, (D-F) quenching-corrected chlorophyll fluorescence, (G-I) Particulate backscattering coefficient (b_{bp}), and (J-L) calculated meltwater proportion for glider unit 331, along each section 1-3 from Figure 1. See main text for calculations. For plots of data from glider unit 439, see Supplementary Information (Fig. S4). Triangles show where the glider surfaced.

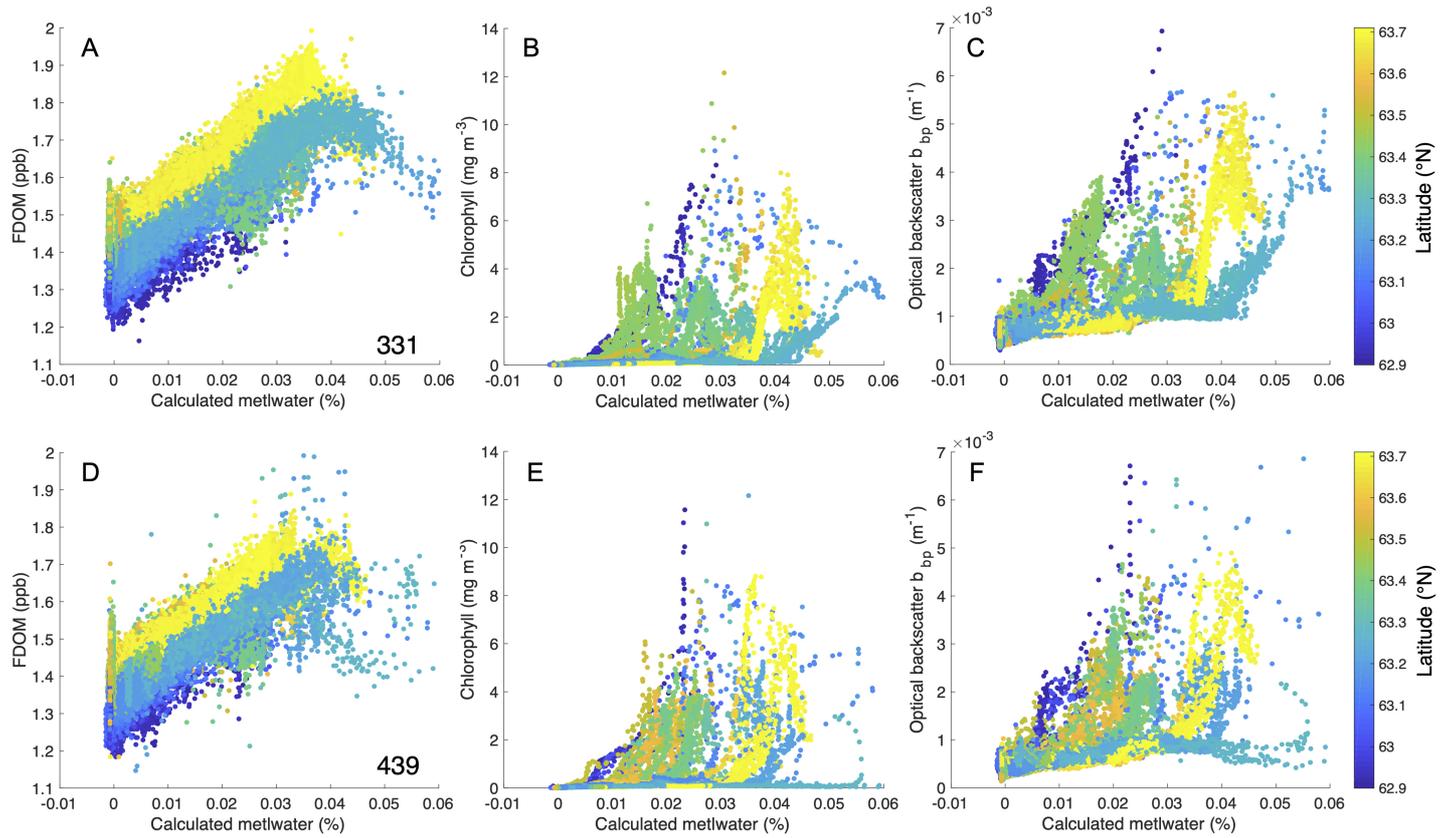


Figure 4. Correlations between calculated meltwater proportion and FDOM, quenching-corrected chlorophyll and optical backscatter for unit 331 (A-C) and unit 439 (D-F). See main text for calculations (Equations 1 and 2). Colour scale indicates latitude.

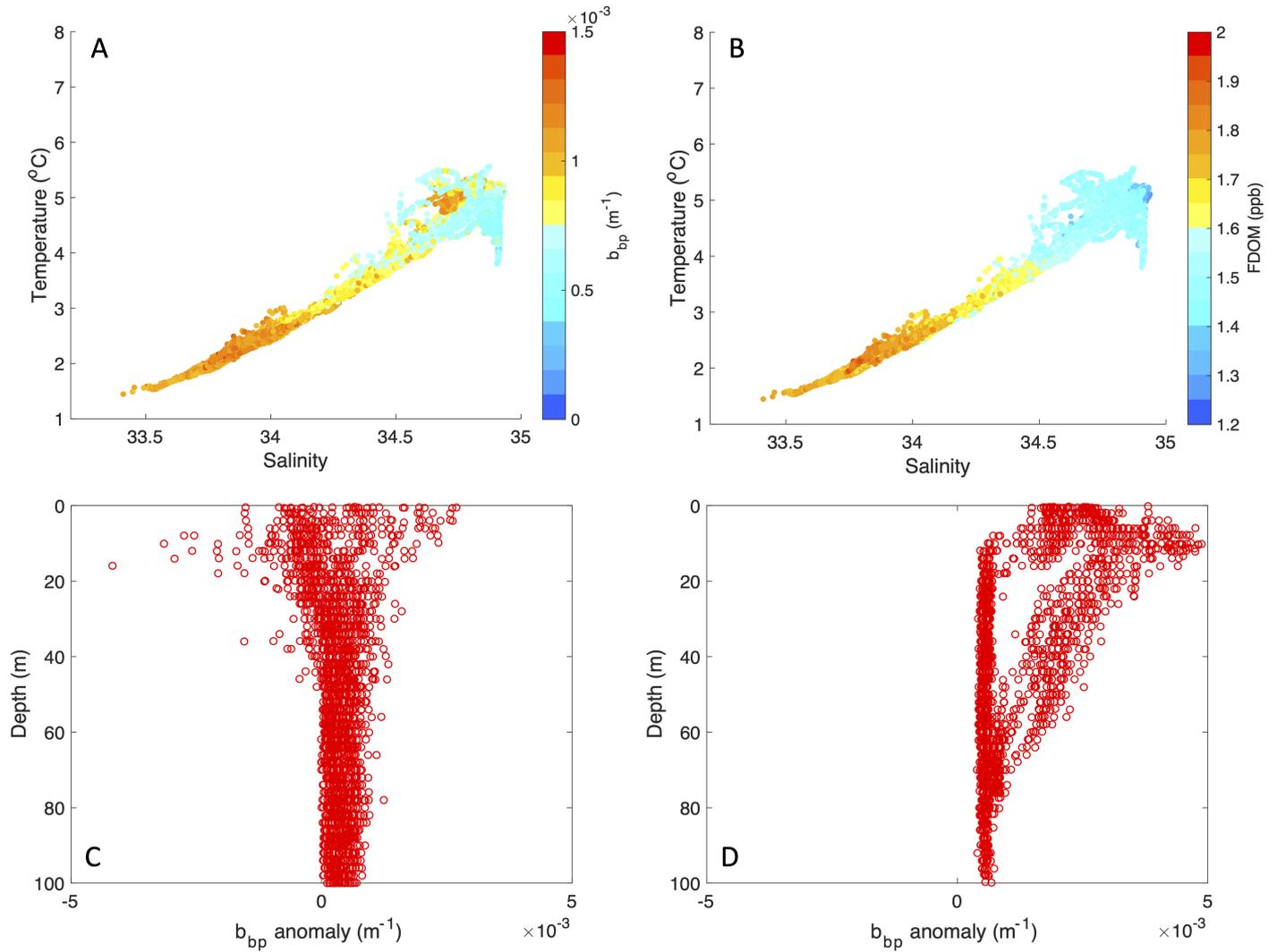


Figure 5. Cross plots for glider unit 331 of temperature and salinity, colour-scaled for b_{bp} (A) and FDOM (B), with data only from depth with uncorrected chlorophyll fluorescence <0.2 $mg\ m^{-3}$. Backscatter b_{bp} anomaly (difference between measured and predicted backscatter from correlation with chlorophyll, plotted for profiles in waters with bottom depth >900 m (C) and <100 m (D)). See main text for full calculations (Equations 1 and 2). For plots of data from glider unit 439, see Supplementary Information (Fig. S6)

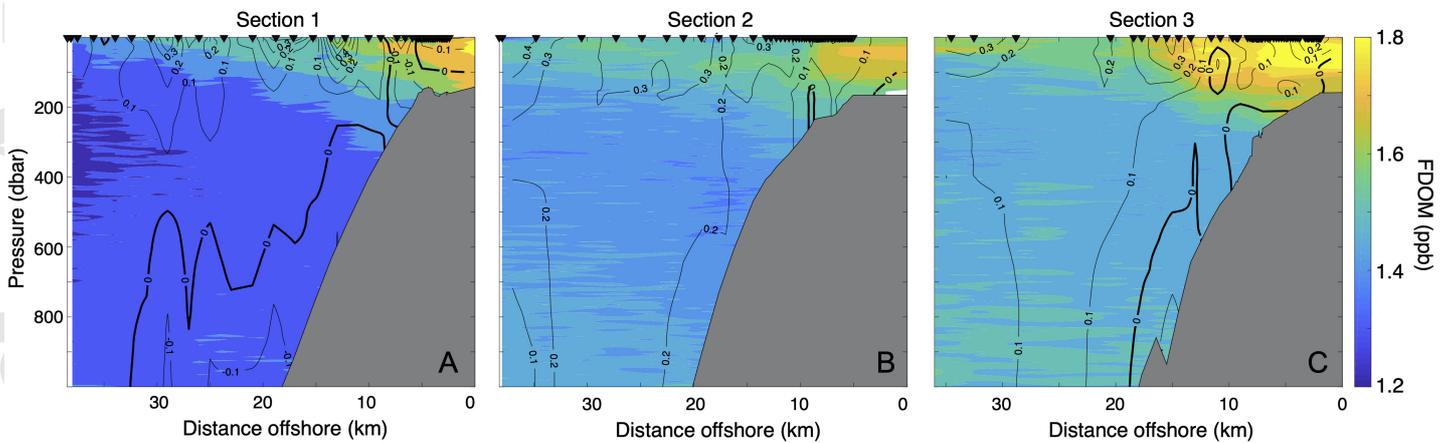


Figure 6. Gridded FDOM in colour (ppb) and velocities (in m s^{-1}) perpendicular to each glider section (shown in contours) for section 1 (A), section 2 (B), and section 3 (C) as shown in Figure 1 for glider 331 (positive northwards). For equivalent plots from glider 439, see Supplementary Information (Fig. S5).

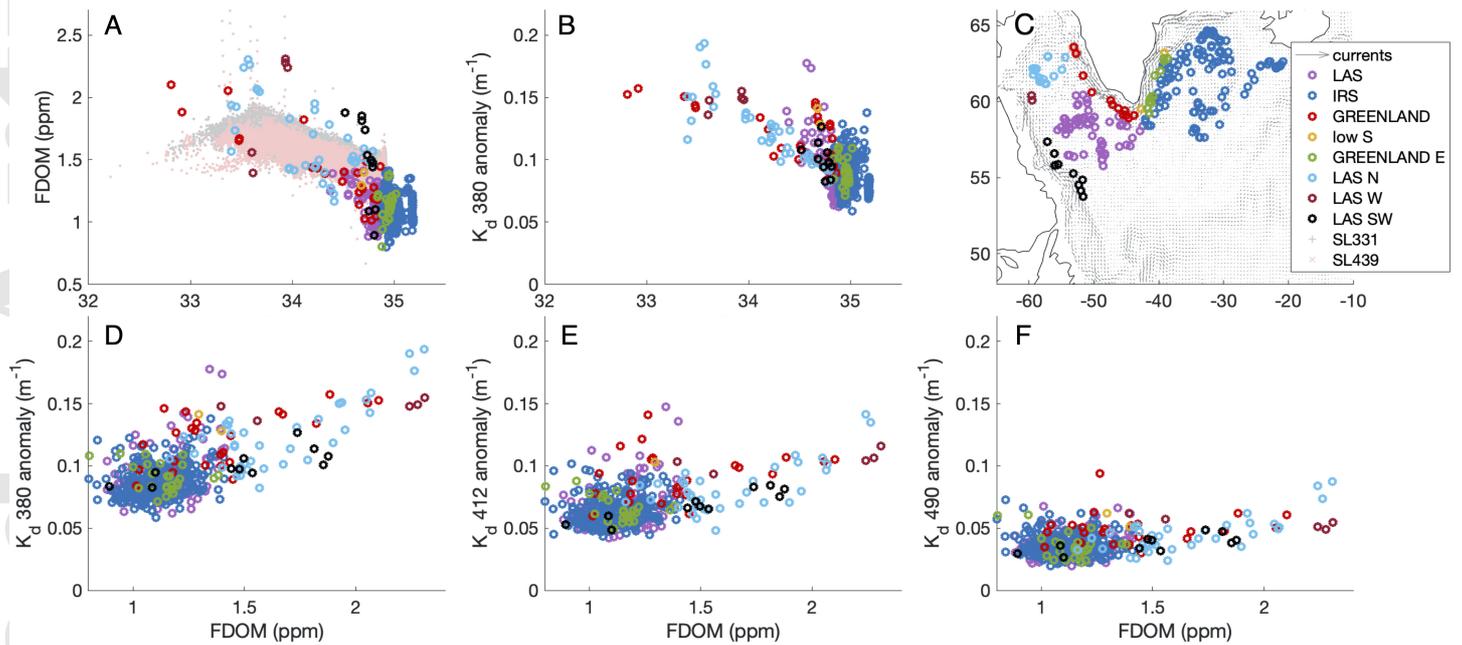


Figure 7. Regional relationships between FDOM, Salinity, and K_d from BGC-Argo floats. Individual panels show relationships between salinity and FDOM (A), salinity and K_d 380 (B), FDOM and K_d 380 (D), FDOM and K_d 412 (E), FDOM and K_d 490 (F). Panel C shows a map with the locations of the float and glider data. Pale symbols (pink and grey) represent glider data from this study. Other colours represent data from 10 BGC Argo floats. Float data all come from the top 10 to 100 m (where natural light is strong enough to measure K_d). All data points with $Chl\ a > 1\ mg\ m^{-3}$ were eliminated to minimize possible influence of $Chl\ a$ on K_d . For the average regression slopes see the supplementary information (Fig. S8).

Table 1. Correlation coefficient, critical r value (r_{sig}) and effective number of degrees of freedom corrected for autocorrelations (N_{eff}) between calculated meltwater proportions (Equations (1 and 2)) and bio-optical properties measured by glider sensors. ** = 95% confidence limits; *** = 99% confidence limits

Glider	Depth range (m)	FDOM (ppb)	Chl a (mg m^{-3})	b_{bp} (m^{-1})
331	<50 m	$r = 0.79; r_{sig}^{***} = 0.35; N_{eff} = 60$	$r = 0.01; r_{sig}^{**} = 0.27; N_{eff} = 58$	$r = 0.16; r_{sig}^{**} = 0.29; N_{eff} = 45$
	50-200 m	$r = 0.87; r_{sig}^{***} = 0.45; N_{eff} = 30$	$r = 0.13; r_{sig}^{**} = 0.30; N_{eff} = 41$	$r = 0.49; r_{sig}^{**} = 0.43; N_{eff} = 20$
	>200 m	$r = 0.08; r_{sig}^{**} = 0.17; N_{eff} = 138$	$r = 0.79; r_{sig}^{***} = 0.62; N_{eff} = 14$	$r = 0.65; r_{sig}^{***} = 0.57; N_{eff} = 17$
439	<50 m	$r = 0.55; r_{sig}^{***} = 0.27; N_{eff} = 94$	$r = 0.19; r_{sig}^{**} = 0.23; N_{eff} = 79$	$r = 0.17; r_{sig}^{**} = 0.23; N_{eff} = 77$
	50-200 m	$r = 0.81; r_{sig}^{***} = 0.45; N_{eff} = 30$	$r = 0.25; r_{sig}^{**} = 0.33; N_{eff} = 39$	$r = 0.65; r_{sig}^{***} = 0.57; N_{eff} = 17$
	>200 m	$r = 0.02; r_{sig}^{**} = ; N_{eff} = 206$	$r = 0.68; r_{sig}^{***} = 0.48; N_{eff} = 26$	$r = 0.54; r_{sig}^{**} = 0.45; N_{eff} = 32$

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