

Benchmarking of Vertically-Integrated CO₂ Flow Simulations at the Sleipner Field, North Sea

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Abstract

Numerical modeling plays an essential role in both identifying and assessing sub-surface reservoirs that might be suitable for future carbon capture and storage projects. Accuracy of flow simulations is tested by benchmarking against historic observations from on-going CO₂ injection sites. At the Sleipner project located in the North Sea, a suite of time-lapse seismic reflection surveys enables the three-dimensional distribution of CO₂ at the top of the reservoir to be determined as a function of time. Previous attempts have used Darcy flow simulators to model CO₂ migration throughout this layer, given the volume of injection with time and the location of the injection point. Due primarily to computational limitations preventing adequate exploration of model parameter space, these simulations usually fail to match the observed distribution of CO₂ as a function of space and time. To circumvent these limitations, we develop a vertically-integrated fluid flow simulator that is based upon the theory of topographically controlled, porous gravity currents. This computationally efficient scheme can be used to invert for the spatial distribution of reservoir permeability required to minimize differ-

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ences between observed and calculated CO₂ distributions. When a uniform reservoir permeability is assumed, inverse modeling is unable to adequately match migration of CO₂ at the top of the reservoir. If, however, the width and permeability of a mapped channel deposit are allowed to independently vary, a satisfactory match between observed and calculated CO₂ distributions is obtained. Finally, the ability of this algorithm to forecast the flow of CO₂ at the top of the reservoir is assessed. By dividing the complete set of seismic reflection surveys into training and validation subsets, we find that the spatial pattern of permeability required to match the training subset can successfully predict CO₂ migration for the validation subset. This ability suggests that it might be feasible to forecast migration patterns into the future with a degree of confidence. Nevertheless, our analysis highlights the difficulty in estimating reservoir parameters away from the region swept by CO₂ without additional observational constraints.

Keywords: Geologic CO₂ storage, Numerical fluid flow simulation, Porous gravity current

1. Introduction

Storage of carbon dioxide in sub-surface geologic reservoirs is generally considered to be a key component of greenhouse gas emission reduction strategies (IPCC, 2014). For safe and effective storage results, CO₂ should be stored securely in isolation from the atmosphere for thousands of years (Bickle, 2009). The largest available reservoirs occur within sedimentary rocks and consist of either depleted hydrocarbon fields or pristine saline aquifers (Bachu, 2000). Here, we concentrate on the suitability of saline aquifers for safe storage. To determine the storage security of supercritical CO₂ trapped at depth and to demonstrate conformance between observed and simulated CO₂ migration, the flow of injected CO₂ must be numerically modeled over appropriate time and length scales (Chadwick and Noy, 2015). Storage reservoirs generally have complex geometries and geologic heterogeneities that directly affect parameters such as permeability, which in turn influence fluid migration. To understand the relationship between reservoir structure and fluid flow, it is important that observations from existing storage sites are exploited to test and improve both the accuracy and reliability of numerical simulations.

19

20 At the Sleipner carbon capture and storage project in the North Sea, seven
21 post-injection seismic reflection surveys acquired over the CO₂-filled reservoir
22 provide insights into the migration of CO₂ through complex porous media
23 at field scale (Figure 1a; Arts et al., 2004; Bickle et al., 2007; Boait et al.,
24 2012). At this site, $\sim 1 \text{ Mt yr}^{-1}$ of CO₂ is injected into a pristine sandstone
25 reservoir at a depth of 1000 m (Chadwick and Noy, 2015). Interpretation and
26 analysis of time-lapse seismic surveys shows that CO₂ is distributed within
27 nine discrete layers (Figure 1b). The CO₂ ponds beneath a stacked series
28 of 1 m thick, impermeable shale horizons that are vertically distributed at
29 about 30 m intervals through the Utsira Formation (Zweigel et al., 2004).
30 The shale horizon immediately below the uppermost CO₂ accumulation is
31 approximately 5 m thick and separates the uppermost section of the reservoir,
32 known as the Sand Wedge, from the rest of the formation (Figure 1c).

33 The stratigraphically highest Layer 9 is of particular interest since the
34 distribution of CO₂ within this layer is complex and there is no evidence of
35 vertical leakage from this layer. Previously, modeling of CO₂ flow through
36 Layer 9 has focused primarily on matching seismically observed areal plan-
37 forms as a function of time (Chadwick and Noy, 2010; Cavanagh, 2013).
38 This restriction is a consequence of the limited vertical resolution since the
39 thickness of a thin layer is difficult to seismically image. Recently, an inverse
40 modeling technique has been developed for determining the thickness of thin
41 CO₂-filled layers by combining measurements of the amplitude of a reflec-
42 tion with small changes in two-way travel time between time-lapse surveys
43 (Cowton et al., 2016). These authors applied this inverse method to each
44 of the time-lapse seismic reflection surveys in order to accurately map the
45 thickness of CO₂-saturated rock within Layer 9 as a function of time. The
46 resultant volumetric estimates can be used to address the important goal of
47 understanding CO₂ flow dynamics within Layer 9.

48 In this contribution, we develop a simple numerical reservoir simulator to
49 model the flow of CO₂ through an unconfined porous medium beneath a com-
50 plex caprock topography. By using a vertically-integrated formulation of the
51 governing equations, this simulator is computationally efficient. A significant
52 benefit of this efficiency is that it enables the inverse problem to be addressed:
53 namely, what spatial distribution of permeability can best account for the
54 flow of CO₂ within Layer 9? First, the optimal distribution of permeability
55 is calculated using a training subset of seismic surveys. Secondly, our results
56 are validated by exploiting a later sub-set of seismic surveys. In this way, a
57 reliable forecasting strategy to predict the future flow of CO₂ within Layer 9

58 of the Sleipner reservoir is developed.

59

60 **2. Previous Research**

61 Existing approaches for modeling CO₂ migration at the Sleipner Field
62 exploit industry-standard reservoir simulators such as GEM (Geomechanical
63 Modeling; CMG, 2009), ECLIPSE (Exploration Consultants Limited Implicit
64 Program for Simulation Engineering; Schlumberger, 2011), and TOUGH2
65 (Transport Of Unsaturated Groundwater and Heat; Pruess, 1991). These
66 different methods solve Darcy’s law for flow through porous media on a three-
67 dimensional grid. Such sophisticated Darcy flow simulators are capable of
68 forecasting the flow of CO₂ through complex geologic reservoirs but they are
69 computationally expensive for two reasons. First, four-dimensional simula-
70 tions have a large number of adjustable parameter values. Secondly, simula-
71 tions must be carried out on length scales of kilometers and on time scales
72 of tens to hundreds of years. As a result, coarse grid sizes are used to reduce
73 computation time which means that significant boundary conditions, such as
74 caprock topography, can be under-resolved (Oldenburg et al., 2016). High
75 performance computing can be used to carry out simulations with a finer grid
76 spacing on large domains by employing a massively parallel simulator such
77 as PFLOTRAN (Lichtner et al., 2015). However, the use of such computing
78 power is expensive and it is not always available or appropriate for regular
79 use.

80

81 Matching the complex spatial distribution of CO₂ within Layer 9 and
82 especially the rapid migration rate of CO₂ along a prominent north-striking
83 ridge has proved a particularly difficult challenge for typical reservoir simula-
84 tors. For example, the TOUGH2 software package has been used to simulate
85 CO₂ flow in this layer with an isotropic permeability of 3 D ($\approx 3 \times 10^{-12}$ m²).
86 The predicted planforms are approximately radial even though the topogra-
87 phy of the caprock is complex (Chadwick and Noy, 2010). The match be-
88 tween observed and calculated planforms can be improved by incorporating
89 anisotropic permeability (i.e. 10 D and 3 D in north-south and east-west
90 directions, respectively). Nevertheless, realistic migration rates along the
91 north-striking topographic ridge are difficult to reproduce. Using a sim-
92 pler ‘black oil’ simulator that ignores changes in composition, Cavanagh
93 (2013) found that a better match between observed and calculated plan-

94 forms is found by injecting the observed amount of CO₂ over the appropriate
95 timescale, and then halting CO₂ injection into Layer 9 and running the sim-
96 ulation for a further ~100 years. In this way, injection pressure is allowed to
97 dissipate over tens of years and CO₂ spreads as a result of buoyancy alone.
98 This predicted long-term behavior suggests that flow within Layer 9 could
99 be driven primarily by buoyancy and not by injection pressure. One pos-
100 sible solution to this modeling issue is to include lower CO₂-filled layers in
101 the numerical simulation, which removes Layer 9 from the vicinity of the
102 injection point (Lindeberg et al., 2001). However, computational limitations
103 mean that grid sizes would have to be dramatically increased, which would
104 decrease the resolution for flow within Layer 9.

105
106 Zweigel et al. (2004) identified a possible high permeability channel within
107 Layer 9. Subsequently, Williams and Chadwick (2017) used the ECLIPSE 100
108 simulator with a channel permeability of 8 D, and a bulk reservoir permeabil-
109 ity of 3 D. This simulation yields a better match between the observed and
110 calculated planforms for most of Layer 9. However, it still does not match
111 the observed rate of migration along the ridge.

112
113 Computation time for modeling CO₂ flow on physically appropriate length
114 scales and time scales can be significantly reduced by employing a reser-
115 voir simulator with reduced complexity (e.g. Bandilla et al., 2014; Nilsen
116 et al., 2016). Less complex simulators exploit analytical analysis of vertically-
117 equilibrated models and apply it to geologically realistic settings. Since these
118 simulators use a vertically-integrated formulation, fluid flow can be solved on
119 a two-dimensional grid which significantly increases computational efficiency.
120 For example, Bandilla et al. (2014) report running times of several minutes on
121 a single core for their vertically equilibrated model when simulating CO₂ flow
122 in Layer 9 using the International Energy Agency Greenhouse Gas Research
123 and Development Programme (IEAGHG) benchmark (50 × 50 m grid; Singh
124 et al., 2010). This value compares favorably with several hours on 100 cores
125 for a typical TOUGH2 simulation with identical input parameters. Compara-
126 tive studies show that these different simulators yield broadly similar results
127 (Nilsen et al., 2011; Bandilla et al., 2014).

128
129 Finally, Nilsen et al. (2017) exploit the adjoint method to invert for
130 caprock topography, permeability, CO₂ density, porosity and injection rates.
131 This method yields an excellent match to estimated thickness measurements

132 of Layer 9 for calendar years 2001, 2004, 2006 and 2010 (Chadwick and Noy,
133 2010; Furre and Eiken, 2014). Their analysis shows that a generalized in-
134 verse model with many adjustable parameters can yield an accurate match
135 to observations. However, the formulation used by Nilsen et al. (2017) yields
136 a non-unique set of parameters that are not necessarily constrained by ad-
137 ditional observational constraints. For example, changes in any combination
138 of permeability, density or caprock topography can reduce CO₂ flux through
139 a grid cell. If all parameters are allowed to vary, the likelihood of matching
140 observations increases at the expense of insight gained. Consequently, the
141 results of Nilsen et al. (2017) are only a partially satisfactory explanation of
142 the spreading planform of CO₂ within Layer 9.

143

144 In summary, the problem of matching observed spreading rates for Layer 9
145 is not necessarily resolved by employing a new formulation of the governing
146 equations. Nonetheless, the development of simulators with greatly reduced
147 computational times opens up the possibility of investigating uncertainties
148 in model space by facilitating an inverse modeling approach.

149

150 3. Modeling Strategy

151 The reservoir model described here simulates the flow of CO₂ through sat-
152 urated porous media as a buoyancy-driven gravity current. A key feature of
153 these currents is that their lateral extent is about one hundred times greater
154 than their thickness. This characteristic aspect ratio is observed for all nine
155 CO₂-filled layers at the Sleipner Field. Laboratory studies also demonstrate
156 that flow of a density-driven invading fluid through porous media can be ac-
157 curately described by a gravity current (Huppert and Woods, 1995; Golding
158 et al., 2011). In its simplest form, the governing equation of a gravity cur-
159 rent is vertically-integrated, which means that vertical changes in reservoir
160 properties are incorporated as depth-averaged quantities.

161

162 A significant consideration when modeling CO₂ flow through porous me-
163 dia is whether the reservoir is confined or unconfined. A reservoir is uncon-
164 fined if the flow of ambient water can be neglected. This assumption is valid
165 when the thickness of the reservoir unit is much greater than the thickness
166 of the intruding fluid. Pegler et al. (2014) found that confinement can be

167 neglected provided that

$$h \ll \frac{\mu_c}{\mu_a} H_a, \quad (1)$$

168 where h is the thickness of the CO₂-saturated layer, H_a is the thickness of the
169 reservoir unit, μ_c is the viscosity of supercritical CO₂, and μ_a is the viscosity
170 of the ambient water.

171

172 At the Sleipner Field, the uppermost unit of the Utsira Formation that
173 includes Layer 9 is known as the Sand Wedge (Figure 2b). The top surface
174 of this unit is bounded by the caprock of the Utsira Formation and its base
175 is marked by a 5 m thick shale layer. This reservoir is estimated to be \sim
176 20 m thick, increasing to 30 m where the CO₂ layer is thickest (Williams
177 and Chadwick, 2017). A viscosity ratio of $\mu_c/\mu_a \simeq 0.1$ implies that the
178 CO₂ layer behaves as an unconfined current wherever it is thinner than 2–
179 3 m— a circumstance that probably holds during the early stages of flow
180 and at the nose of the gravity current. We note that Equation (1) is an
181 approximation that applies to a uniform, two-dimensional reservoir and does
182 not include the effects of topographic gradients within the caprock. This
183 *caveat* suggests that the unconfined approximation may be used for complex
184 three-dimensional geometries with modest confinement. Here, we make the
185 simplifying assumption that the current is unconfined at all times and explore
186 the ability of such a simulator to explain the observed spreading patterns.

187

188 We have chosen to neglect capillary forces that give rise to partially sat-
189 urated currents. The results of centrifuge experiments carried out on core
190 material from the Utsira Formation yield vertical CO₂ saturation profiles
191 which suggest that the capillary transition zone at the base of the CO₂ layer
192 is approximately 1 m thick (Chadwick et al., 2004). Other experimental and
193 analytical results suggest that the rate of CO₂ migration is not significantly
194 impeded by capillary forces during the injection phase (Golding et al., 2011).

195 Our simple model describes the flow of a single-phase gravity current with
196 a sharp interface along a slope within an unconfined saline aquifer. Fluid flow
197 in porous media is governed by Darcy’s law,

$$\phi \tilde{\mathbf{u}} = \mathbf{u} = -\frac{k}{\mu} (\nabla P + \rho g \hat{z}), \quad (2)$$

198 where ϕ is the porosity, $\tilde{\mathbf{u}}$ is the interstitial fluid velocity, $\mathbf{u} = (u, v, w)$ is the

199 Darcy velocity or volumetric fluid flux, k is the permeability, μ the viscosity of
 200 CO₂, ∇P is the pressure gradient, ρ the density of the fluid, g is gravitational
 201 acceleration, and \hat{z} is a unit vector in the vertical direction (Figure 3). We
 202 treat the flow of CO₂ as incompressible so that

$$\nabla \cdot \mathbf{u} = 0. \quad (3)$$

203 For a long, thin gravity current flowing beneath an impermeable boundary
 204 with topography $d(x, y)$, the vertical velocity is negligible and hence the
 205 pressure is hydrostatic,

$$P = \begin{cases} P_H - \rho_a g[H - (d + h)] - \rho_c g[(d + h) - z], & d < z < d + h, \\ P_H - \rho_a g(H - z), & d + h < z < H, \end{cases} \quad (4)$$

206 where P_H is the pressure at a reference horizon beneath the gravity current at
 207 depth $z = H$, ρ_c is the density of the injected buoyant fluid, ρ_a is the density
 208 of the ambient water, and $h(x, y, t)$ is the thickness of CO₂-saturated rock
 209 (i.e. the gravity current). In contrast to the models of Huppert and Woods
 210 (1995) and Vella and Huppert (2006) that are formulated in a slope-parallel
 211 reference frame, this model uses a horizontal reference for which it is simpler
 212 to compute complex reservoir geometries (e.g. Figure 2a).

213

214 From Darcy's law, the horizontal Darcy velocity, $\mathbf{u}_H = (u, v)$, is given by

$$\mathbf{u}_H = -\frac{k}{\mu} \nabla_H P = -\frac{kg\Delta\rho}{\mu} \nabla_H (d + h), \quad (5)$$

215 where ∇_H is the horizontal gradient operator, $\Delta\rho = (\rho_a - \rho_c)$ is the density
 216 difference between the two fluids, and $u_b = kg\Delta\rho/\mu$ is the buoyancy velocity.

217

218 For vertically uniform permeability, flow within the current is uniform as
 219 a function of depth. Integrating the divergence of the Darcy velocity over
 220 the depth of the current in combination with Equation 5 yields

$$\phi \frac{\partial h}{\partial t} - \nabla_H \cdot \left\{ \frac{k\Delta\rho g}{\mu} h \nabla_H d \right\} = \nabla_H \cdot \left\{ \frac{k\Delta\rho g}{\mu} h \nabla_H h \right\}. \quad (6)$$

221 This formulation highlights that the change in thickness of the CO₂ current
 222 with time is driven by advection of CO₂ caused by topographic gradients

223 within the caprock and by diffusion of CO₂ away from regions where the
224 gravity current is thickest.

225

226 The model described by Equation 6 is a simplified version of so-called ver-
227 tical equilibrium models developed over the last decade (e.g. Golding et al.,
228 2011; Guo et al., 2014; Andersen et al., 2015). Such models exploit the large
229 aspect ratio of spreading currents of CO₂ to reduce the complexity of flow
230 simulations in three dimensions by assuming that flow predominantly occurs
231 in the horizontal, or along-slope, direction. The large aspect ratio implies
232 that pressure is, to leading order, hydrostatic which means that flow is driven
233 by gradients in the depth of the current and by gravity acting along slope
234 for topographically controlled, unconfined currents. Many of these models
235 also treat partial saturation within the CO₂ plume. Here, given both the
236 advantageous geometry and the pore structure of the Utsira sandstone, we
237 can confidently neglect these complicating features and focus on using this
238 simplified approach to understand what principally controls CO₂ flow at the
239 Sleipner Field. In this sense, The model presented here is a useful test of the
240 efficacy of vertical equilibrium models when matching field observations.

241

242 We solve Equation (6) using a Crank-Nicholson finite difference scheme
243 that is centered in time and space (Press et al., 2007). Subsequent time
244 steps are solved efficiently by using tridiagonal elimination. A predictor-
245 corrector scheme is used to evaluate non-linear diffusive buoyancy (Press
246 et al., 2007). To improve the stability of this numerical solution in regions
247 that are susceptible to numerical instability (e.g. sharp changes in topo-
248 graphic gradient), the Il'in three-point differencing scheme is applied (Il'in,
249 1969; Clauser and Kiesner, 1987). This scheme automatically determines
250 the amount of 'upwinding' required to keep the model stable for high Peclet
251 numbers. An alternating direction implicit (ADI) scheme is adapted to prop-
252 agate the gravity current in three dimensions (Peaceman and Rachford, 1955;
253 Press et al., 2007). This numerical scheme has been carefully benchmarked
254 against analytical solutions for simplified gravity currents in both two- and
255 three- dimensions presented by Huppert and Woods (1995) and Vella and
256 Huppert (2006), respectively.

257 4. Application

258 Solutions of Equation (6) yield predicted distributions of CO₂, $h(x, y, t)$,
259 that can be directly compared with the observed distribution obtained by
260 analyzing seismic reflection surveys (Cowton et al., 2016). The geometry
261 of the reservoir and its physical properties, for example the shape of the
262 impermeable boundary along which CO₂ fluid is spreading, $d(x, y)$, and the
263 permeability, $k(x, y)$, and porosity, $\phi(x, y)$, must be determined. In addition,
264 the volumetric flux of CO₂ into Layer 9 at the top of the reservoir, $V(t)$,
265 together with the location of the injection point are required. Finally, the
266 density and viscosity of supercritical CO₂ must be estimated.

267 4.1. Reservoir Geometry and Properties

268 The reservoir geometry is constrained by picking the bright reflection
269 that marks the top of the Utsira Formation on the 1994 baseline seismic
270 reflection survey. This survey was binned into 12.5×12.5 m blocks before
271 signal processing. The dominant frequency of the stacked seismic volume is
272 30 Hz which means that the vertical and horizontal resolution is about 16
273 m. This value limits the scale of topographic features that can be resolved.
274 A reflection at the top of the Utsira Formation can also be easily picked on
275 subsequent seismic surveys. Differences between two-way travel time maps
276 of this reflection are as small as ± 1 ms which suggests that estimates of
277 reservoir topography are robust but affected by noise of order ± 1 m (Cow-
278 ton et al., 2016). To mitigate short wavelength noise, a median filter with
279 50 m block sizes is applied to the picked surface on each time-lapse survey
280 (Hall, 2007). Each filtered surface is then interpolated using a continuous
281 curvature spline with a tension factor of 0.1 (Smith and Wessel, 1990). By
282 smoothing picked surfaces in this way, spikes, sinks and other unphysically
283 sharp gradients that could affect the stability of numerical flow simulations
284 are removed. The top of the Utsira Formation is not affected by faulting in
285 the vicinity of the injection site.

286
287 The topographic surface of the caprock is picked in two-way travel time
288 (twtt) and is converted into meters below sea-level using

$$d = \left(\frac{t_{rc}}{2} \right) V_{sed} - c, \quad (7)$$

289 where d is the relative depth to the reservoir-caprock boundary in meters,
290 t_{rc} is the two-way travel time down to this boundary, $V_{sed} = 2150 \text{ m s}^{-1}$
291 is the acoustic velocity of the Nordland Shale Formation (i.e. the overlying
292 stratigraphic unit), and $c = 115 \text{ m}$ is a constant obtained from sonic
293 log measurements that enables relative depth to be synchronized to true
294 depth (Figure 2a). Chadwick et al. (2016) report that, although there is no
295 systematic spatial variation in stacking velocities determined during seismic
296 processing, the uncertainty in the value of V_{sed} is $\pm 46 \text{ m s}^{-1}$. Values of
297 V_{sed} calculated using sonic log measurements from nearby wells fall within
298 the range of 2133–2159 m s^{-1} . Uncertainties in the regional velocity of the
299 Nordland Shale Formation contribute to uncertainty in the magnitude of topographic
300 gradients, whereas local variability of velocity affects the detailed
301 pattern of topographic relief.

302
303 Pre-existing gas-rich pockets within the Nordland Formation demonstrate
304 that the assumption of a uniform velocity within the overburden does not
305 hold across the survey region. These pockets have lower acoustic velocities
306 than those of the surrounding brine-saturated rock. Consequently, their
307 presence systematically increases the calculated depth down to the reservoir-
308 caprock boundary in these regions and disrupts the coherency of underlying
309 reflections. In these circumstances, topographic measurements are interpolated
310 and filled across any gaps in mapping (Smith and Wessel, 1990).

311
312 Porosity and permeability of the Utsira Formation are estimated using
313 core material from a well located $\sim 1 \text{ km}$ from the injection point (Zweigel
314 et al., 2004). This formation is composed of largely unconsolidated sand
315 grains with a bimodal grain size distribution showing peaks at $3 \mu\text{m}$ and at
316 0.2 mm . In core samples, its porosity is $\phi = 0.37 \pm 0.03$ which agrees with
317 estimates from wireline logs. Measured permeabilities of the Utsira Formation
318 are $k = 2\text{--}5 \text{ D}$ (Lindeberg et al., 2001; Zweigel et al., 2004). Well tests
319 from the nearby Grane and Oseberg areas suggest that permeability could
320 have a bigger range of $1\text{--}8 \text{ D}$ (Zweigel et al., 2004).

321
322 The thickness of the Sand Wedge unit is shown in Figure 2b. A pronounced
323 linear feature that runs approximately north-south has been previously
324 interpreted as a submarine channel deposit (Zweigel et al., 2004). Such
325 channels are characteristic of the Utsira Formation (Gregersen, 1998). In
326 this case, the mapped channel has a similar scale and sinuosity to low sin-

327 uosity submarine channels described elsewhere (Clark and Pickering, 1996).
328 Sediments deposited within channels are often coarser grained as a result of
329 faster flow velocities within the channel and are likely to have higher perme-
330 abilities (Beard and Weyl, 1973). These high permeability channels can play
331 an significant role in fluid migration.

332

333 *4.2. Fluid Properties and Injection Rates*

334 Layer 9 sits at the top of the reservoir where the hydrostatic pressure is
335 8.2–8.9 MPa and temperature is 28.4–30.7 ° C (Alnes et al., 2011). These
336 estimates are close to the critical point on the phase diagram which means
337 that estimates of the density and viscosity of CO₂ within Layer 9 are sensi-
338 tive to small changes in temperature within the saline reservoir. Alnes et al.
339 (2011) calculated that the average density of CO₂ within the reservoir is
340 $675 \pm 20 \text{ kg m}^{-3}$ by modeling time-lapse micro-gravity measurements. This
341 estimate agrees with that determined by modeling the temperature history
342 of the CO₂ plume for the entire reservoir with the PFLOTRAN software pack-
343 age that solves for multi-phase reactive flow and transport within a porous
344 medium (Lichtner et al., 2015; Williams and Chadwick, 2017). Here, we use
345 a slightly higher value of $690 \pm 30 \text{ kg m}^{-3}$ to account for cooling of CO₂ away
346 from the injection point. Finally, the dynamic viscosity of CO₂ at pressures
347 and temperatures that are characteristic of the top part of the reservoir is
348 $\mu_c = 5 \pm 1 \times 10^{-5} \text{ Pa s}$ (Bickle et al., 2007; Williams and Chadwick, 2017).

349

350 The existence of sub-vertical seismic chimneys described by Chadwick
351 et al. (2004) and by Cowton et al. (2016) is consistent with vertical migration
352 of CO₂ through the reservoir rocks. One major chimney correlates closely
353 with the first observed accumulation of CO₂ in different layers. Therefore,
354 it is reasonable to infer that the location of this chimney is likely to be the
355 most significant injection point for Layer 9 (Figure 2c and Figure 4g,n). On
356 Figure 4f, a small disconnected patch of CO₂ exists south of the significant
357 CO₂-filled layer on the seismic survey for calendar year 2008. This outly-
358 ing patch connects with the rest of the CO₂-filled distribution on the 2010
359 survey. Its existence suggests that there may be at least one other, albeit
360 considerably smaller, injection point for Layer 9. For simplicity, we assume
361 that its contribution is negligible and that most CO₂ is injected through the
362 largest central chimney (Cowton et al., 2016).

363

364 Finally, the flux of CO₂ fluid into Layer 9 is estimated from the detailed
 365 volume calculations of Cowton et al. (2016). Re-evaluation of their calcula-
 366 tions suggest that the volumetric injection rate is given by

$$q = \frac{dV(t)}{dt} = nC (t - t_0)^{n-1}, \quad (8)$$

367 where $C = 9500 \pm 5700 \text{ m}^3 \text{ yr}^{-n}$, $t_0 = 1998.1 \pm 0.5$ and $n = 2.1 \pm 0.2$. The un-
 368 certainty of this injection rate is estimated from CO₂ thickness measurements
 369 which includes the uncertainty of the acoustic velocity of CO₂-saturated sand-
 370 stone (Cowton et al., 2016).

371 5. Results of Inverse Modeling

372 By adopting a vertically-integrated formulation, the flow model presented
 373 here is considerably more efficient than conventional Darcy flow simulators.
 374 Each of our simulations takes less than ~ 10 minutes to run on a single core.
 375 This short calculation time means that the best-fitting value of permeability
 376 that minimizes the difference between the observed and calculated CO₂ dis-
 377 tributions can be determined by inverse modeling. At each stage, a starting
 378 model is computed using permeability values measured from nearby bore-
 379 holes. The influence of uniform and spatially variable permeabilities is inves-
 380 tigated by grid search.

381
 382 Simulated CO₂ flow throughout Layer 9 for a uniform permeability of
 383 $k = 2 \text{ D}$ is compared with the observed CO₂ distribution (Figure 4a-g, o-u;
 384 Cowton et al., 2016). In this simulation, it is clear that the northerly exten-
 385 sion of the plume along the topographic ridge at the top of the reservoir does
 386 not move rapidly enough to reach the northern topographic dome. Instead,
 387 the sluggish spreading rate causes CO₂ to accumulate adjacent to the injec-
 388 tion point where it reaches a thickness of 12 m by 2010 which is considerably
 389 greater than observed.

390
 391 The principal result of constant permeability simulations is that using
 392 different combinations of input parameters does not yield adequate matches
 393 between observed and calculated CO₂ distributions. For example, uncertain-
 394 ties in the detailed shape of caprock topography could potentially account
 395 for significant discrepancies (Chadwick et al., 2016). However, to signifi-
 396 cantly improve the match between observed and calculated planforms at the

397 northern end of survey, the topographic gradient would need to be increased
 398 by as much as 50 m. This value is substantially greater than permitted
 399 by uncertainties in the acoustic velocity of the Nordland Shale Formation.
 400 Alternatively, the physical properties of supercritical CO₂ may vary within
 401 Layer 9 since the estimated pressure and temperature are close to the critical
 402 point. Changes in these properties directly affect the value of the buoyancy
 403 velocity, u_b . Here, we note that quoted uncertainties in $\Delta\rho$ and μ for $k = 2$ D
 404 yields $u_b = 1.4_{-0.3}^{+0.5} \times 10^{-4}$ m s⁻¹. This range is equivalent to changes in per-
 405 meability of $k = 2_{-0.5}^{+0.7}$ D.

406

407 5.1. Uniform Permeability

408 The mismatch between observed and simulated CO₂ distributions is sub-
 409 stantial, which suggest that the assumption of a uniform permeability of
 410 $k = 2$ D is incorrect notwithstanding uncertainties in the fluid properties
 411 injected CO₂ fluid within Layer 9. Here, we first explore simulations where
 412 different but constant values of k are assumed. A parameter sweep is per-
 413 formed to find the optimal permeability for Layer 9. For each value of k , the
 414 calculated distribution of CO₂ is compared with the observed distribution
 415 using a misfit function

$$M = \frac{1}{N_s} \sum_{j=1999}^{N_s} \left[\frac{1}{N} \sum_{i=1}^N \left(\frac{h_{ij}^c - h_{ij}^o}{\sigma_{ij}} \right)^2 \right]^{1/2}, \quad (9)$$

416 where h_{ij}^c is the calculated thickness of the CO₂ layer, h_{ij}^o is the observed
 417 thickness, and σ_{ij} is the standard deviation of the observed thickness (Fig-
 418 ure 5a; Cowton et al., 2016). Here, i refers to a particular thickness value out
 419 of a total of N values from each survey where the observed CO₂-filled layer
 420 is > 0.5 m thick, and j refers to a given seismic reflection survey between
 421 calendar years 1999 and 2010 where N_s is the total number of surveys.

422 Our estimates of standard deviation are deliberately conservative. Thus
 423 for $h_{ij}^o > 5$ m, σ is determined from synthetic tests but for $h_{ij}^o < 5$ m we apply
 424 a large uniform uncertainty of $\sigma = 0.5$ m. This uniform uncertainty account
 425 for errors in caprock topography that can cause discrepancies between ob-
 426 served and calculated CO₂ thicknesses, particularly in regions where Layer 9
 427 is very thin. A threshold of 0.5 m is chosen based on the uncertainty in
 428 reliably resolving the thickness of a thin layer on a seismic reflection survey

429 with a given frequency content (Figure 5a).

430

431 A parameter sweep of k shows that a broad global minimum of residual
432 misfit between observed and calculated CO₂ thicknesses occurs for $k = 5$ –
433 12 D (Figure 5b). Despite this success, the spatial distribution of CO₂ and
434 its observed rate of northward migration cannot be matched, even when
435 $k = 12$ D (Figure 4h-n and o-u). At the southern end of the platform,
436 there is also significant misfit between observed and calculated distributions.
437 Therefore although high values of permeability can generally account for a
438 rapid rate toward the north, the southward spread of CO₂ requires a lower
439 permeability to allow ponding of CO₂ close to the injection point. These
440 remaining discrepancies suggest that a more complex spatial pattern of per-
441 meability is required.

442

443 *5.2. Spatially Variable Permeability*

444 Our justification for investigating the consequences of a more complex
445 pattern of permeability is centered on the existence of a notable, 25–30 m
446 thick, linear channel that curves and splays northward (Figure 2b). A series
447 of small crevasse splays can be interpreted along the left-hand bank of this
448 feature which suggests that it is a channelized submarine fan deposit. It is
449 well known that these channel deposits can have high values of porosity and
450 permeability which make them favorable hydrocarbon exploration targets.
451 Eldrett et al. (2015) observe that in the Paleocene Sele Formation, North
452 Sea, the permeability contrast between high-quality sands deposited within
453 channels and the overbank and levee facies is typically several orders of mag-
454 nitude.

455

456 Here, we test the influence that this linear permeability feature has upon
457 flow prediction by using a simple parametrization of spatially varying perme-
458 ability (Figure 2b). The region under consideration is divided into two parts
459 comprising the linear channel and the rest of the reservoir by using three in-
460 dependent parameters: w , the width of the channel; k_1 , the permeability of
461 the reservoir; and k_2 , the permeability of the channel (Figure 2c). Our goal
462 is to minimize the misfit between the observed and calculated distributions
463 of CO₂ by varying these three parameters using a simple grid search.

464

465 Figure 6 shows how misfit varies as a function of w , k_1 and k_2 . A shal-
466 low global minimum occurs at $w = 700 \pm 125$ m, $k_1 = 3.5 \pm 1$ D, and
467 $k_2 = 20 \pm 8$ D. The shape of this misfit function makes calculating formal
468 uncertainties challenging. Our quoted uncertainties are estimated from that
469 misfit contour which shows a 1 % increase above the global minimum. These
470 uncertainties clearly show that k_1 is well constrained with a value that is sat-
471 isfyingly close to that estimated independently from reservoir core material
472 (Zweigel et al., 2004). There is little trade-off between k_1 and the other two
473 parameters. The values of k_2 and w are less well constrained and exhibit the
474 expected degree of negative trade-off (i.e. a narrower channel with a higher
475 permeability yields as good a fit as a wider channel with lower permeability).
476

477 The optimal permeability of this channel is regarded as physically plausi-
478 ble when compared to experimental permeability measurements carried out
479 on unconsolidated sand (Beard and Weyl, 1973). An empirical relationship
480 between permeability and porosity based on measurements from the clean
481 and well sorted Fontainebleau sandstone shows that $k \simeq 3.03 \times 10^{-4}(\phi)^{3.05}$,
482 which suggests that rocks with a porosity of $\phi = 0.37$ can have a permeability
483 as great as ~ 20 D (Bourbie and Zinszner, 1985). Similarly clear correlations
484 between porosity and permeability are also observed for Paleocene North
485 Sea hydrocarbon reservoirs, such as the Ormen Lange field, the Maureen
486 formation, and the Forties Sandstone member. In each case, permeabilities
487 of ~ 20 D are reasonable for sandstones with $\phi = 0.37$ (Grecula et al., 2015;
488 Kilhams et al., 2015; Jones et al., 2015). These estimates are in line with
489 a permeability calculated using the Carman-Kozeny relationship for clean
490 sand with a mean grain size of $200 \mu\text{m}$. Figure 7 confirms that, in order
491 to accurately match the observed rate of migration along the length of the
492 channel, a permeability of up to 30 D is required. We note that the predicted
493 buoyancy velocity within this channel is too great to have been generated by
494 reasonable variations in the density and viscosity of CO_2 .
495

496 Figure 8h-n shows that the combination of lower permeability near the
497 injection point and higher permeability within the channel provides the re-
498 quired heterogeneity of reservoir properties to yield an improved match to
499 both the southward and northward migration of fluid. The largest residual
500 misfit occurs along the eastern side where migration of CO_2 into part of the
501 north-running ridge occurs much earlier than observed on the seismic re-
502 flection surveys. One possible explanation is that a low permeability region

503 exists between two distinct and parallel channels, reducing the flux of CO₂
504 into the eastern channel. Alternatively, the topographic smoothing applied
505 to mitigate the effects of noise may have reduced the spill-point depth in this
506 area.

507

508 The results of running flow simulations that include spatially variable
509 permeability suggest that vertical equilibrium algorithms can be exploited
510 in combination with seismically derived observations to build reservoir mod-
511 els that predict good matches between observed and calculated CO₂ distri-
512 butions throughout Layer 9. Here, we have been able to match observed
513 migration rates by considering buoyancy driven flow with reasonable val-
514 ues of permeability without requiring significant changes to the observed
515 caprock topography. Note, however, that the impact that reservoir confine-
516 ment might have upon flow of CO₂ cannot be assessed using this model alone.
517 We conclude that an inverse modeling approach can shed useful light on the
518 properties of Layer 9 and have a role to play alongside traditional reservoir
519 characterization techniques to improve forecasts of CO₂ flow at other poten-
520 tial carbon capture and storage sites.

521

522 **6. Benchmarking, Testing, and Forecasting**

523 The computational efficiency of our algorithm relies on the assumption
524 that the flow of CO₂ may be treated as an unconfined, porous gravity current.
525 It is important to test the results of using a vertically-integrated approach
526 with more conventional three-dimensional flow simulators. Here, CO₂ flow
527 within Layer 9 was also simulated by running the ECLIPSE 100 black oil
528 reservoir model with our optimal, spatially variable, permeability distribution
529 (Figure 8o-u). Due to the necessarily greater computation time, grid cells
530 for the ECLIPSE 100 simulation were chosen to be twice the size of those
531 for the vertically-integrated model (i.e. 25 × 25 m). These grid cells were
532 vertically spaced 1 m apart and the reservoir was assumed to be 24 m thick
533 with an impermeable lower boundary. Other parameters such as caprock
534 topography, reservoir properties, rate of injection, locus of injection point,
535 and fluid properties are unchanged.

536 The results of the ECLIPSE 100 simulation are nearly identical to those
537 of our vertically-integrated model (compare Figure 8o-u and h-n). Inclusion
538 of an impermeable lower boundary condition does not appear to make a

539 significant difference, which strongly supports our assumption of an uncon-
540 fined reservoir. Minor differences can probably be attributed to the reduced
541 resolution of caprock topography used in the ECLIPSE 100 simulation (Fig-
542 ure 8v-ab). Note that this simulation took approximately one hundred times
543 longer to run than the vertically-integrated model on a single core. This sub-
544stantial difference in computation time confirms that an inverse permeability
545 model based upon conventional flow simulators is, at present, impractical. It
546 is also worth noting that, within the constraints of the gravity current ap-
547 proximation, improved horizontal is achieved with the vertically-integrated
548 simulations.

549 A reservoir simulator should have the ability to forecast future flow through
550 a given reservoir model. To test the ability of our vertically averaged sim-
551 ulator to predict CO₂ flow at the Sleipner Field, we have divided the set
552 of time-lapse seismic images from surveys for all seven calendar years into
553 different training and validation sub-sets (Table 1). In each case, the train-
554 ing sub-set of surveys are used to identify optimal reservoir parameters by
555 minimizing the misfit between observed and calculated flow distributions
556 (Equation 9). These results are then used to predict flow distributions for
557 the validation sub-set. Confidence in the simulator depends upon its ability
558 to independently predict flow distributions that have a small residual misfit
559 compared with the baseline performance that is calculated using the entire
560 set. We acknowledge that this machine-learning approach is less useful when
561 the number of sets of observations is small. However, the significant expense
562 of acquiring additional seismic reflection surveys suggests that testing even
563 a limited ability to predict future behavior is a worthwhile endeavor.

564
565 Our analysis indicates that a reasonable prediction of the distribution of
566 CO₂ up to 2008 can be made by using simulations up to and including 2004,
567 provided that the rate of injection into Layer 9 is known (Table 1). However,
568 our ability to predict the distribution of CO₂ for 2010 by fitting the training
569 set shows a marked deterioration. This deterioration may be caused by a
570 notable reduction in observed migration velocity along the northern protu-
571 berance, which suggests that permeability may decrease northward along the
572 channel (Figure 7). This inference is in accordance with observations made by
573 (Clark and Pickering, 1996), who suggested that deposition of sands within
574 a channel can be variable along the length of a channel, particularly near
575 channel bends, and cause permeability to spatially vary. An alternative pos-
576 sibility is that uncertainties in the detailed topography of the northern dome

Table 1: Forecasting CO₂ flow in Layer 9. Best-fitting parameters for flow model found by grid search for training set. Misfit for each seismic reflection survey for each set of trained parameters are shown in black. Misfits for test data shown in red.

Training Set	Model Parameters			Misfit						
	w , m	k_1 , D	k_2 , D	1999	2001	2002	2004	2006	2008	2010
1999-2010	700	3.5	20	2.88	2.21	2.31	2.60	2.86	3.35	3.33
1999-2008	650	3.5	30	2.89	2.15	2.27	2.66	2.93	3.23	3.66
1999-2006	700	3.5	20	2.88	2.21	2.31	2.60	2.86	3.35	3.33
1999-2004	650	4	28	2.88	2.17	2.28	2.62	2.95	3.26	3.63
1999-2002	650	3.5	50	2.88	2.13	2.24	2.80	3.10	3.43	4.26

577 give rise to discrepancies between observed and calculated distributions of
 578 CO₂.

579

580 Since supercritical CO₂ fluid is being injected into the Utsira Formation
 581 as of 2017, it is worthwhile attempting to use our vertically-integrated simu-
 582 lator to forecast future distributions. Here, we explore two end-member sets
 583 of forecasts that are based upon having fitted CO₂ distributions up to and
 584 including 2010. The first set assumes that no additional CO₂ is injected into
 585 Layer 9 after 2010 (Figure 9a; c-h). With zero additional flux, the distribu-
 586 tion of CO₂ shows little further change which suggests that fluid has already
 587 reached a state of buoyant equilibrium by previously migrating rapidly from
 588 the southern to the northern dome. The second set assumes that the in-
 589 jection rate continues to increase in accordance with Equation 8 after 2010
 590 (Figure 9b; i-n). In this case, the areal planform continues to increase almost
 591 linearly. Note that the volume of CO₂ trapped beneath the southern dome
 592 does not significantly increase between 2010 and 2022 and the maximum
 593 thickness only increases by ~ 3 m. The bulk of CO₂ that enters Layer 9
 594 during this period is accounted for by an increase in the amount that is
 595 trapped beneath the northern dome. This northern dome has a significantly
 596 greater trapping capacity than the southern dome, which implies that CO₂
 597 will continue to safely migrate into it for many years. However, as the layer
 598 of accumulated CO₂ thickens, it is likely that reservoir confinement and the
 599 consequent flow of ambient fluid will begin to influence flow dynamics. At

600 that stage, our simplified reservoir simulator will not longer be capable of
601 accurately describing the distribution of CO₂.

602 7. Discussion and Conclusions

603 We describe and apply a simplified numerical reservoir simulator based
604 on buoyancy-driven gravity currents to model CO₂ flow through an uncon-
605 fined porous reservoir. The vertically-integrated nature of the governing
606 equations means that this model is computationally efficient compared to
607 industry-standard, three-dimensional Darcy flow simulators. This reservoir
608 simulator is used to investigate flow of CO₂ together with the reservoir prop-
609 erties required to reproduce the seismically-derived distribution of CO₂ in
610 three dimensions for Layer 9 of the Sleipner Field. Flow simulations per-
611 formed using measured reservoir geometry and reservoir and fluid properties
612 only partially match the observed CO₂ distributions. Analysis of the base-
613 line seismic reflection survey suggests the existence of a submarine channel
614 deposit within the reservoir. A simple spatially varying reservoir model with
615 a high permeability channel is found to reduce the misfit between observed
616 and calculated CO₂ distributions. Consideration of the confinement of the
617 reservoir does not appear to be required the evolution of Layer 9. Using this
618 best-fitting reservoir model, the future flow of CO₂ within Layer 9 can be
619 forecast by making simplified assumptions about the future flux of CO₂ into
620 Layer 9.

621
622 An inverse modeling strategy is used to identify a reservoir permeability
623 that permits a good match between the observed and calculated migration
624 of CO₂ through Layer 9 of the Utsira Formation reservoir. Our comparisons
625 and tests validate the utility of using vertically equilibrated models as the
626 basis of inverse tools with which to assess reservoir properties. However, it
627 is clear that there are regions in which discrepancies between observed and
628 calculated CO₂ distributions remain. These discrepancies can be attributed
629 to uncertainties in geologic parameters that are not permitted to vary in
630 our inversion scheme, such as detailed caprock topography and intra-channel
631 permeability. The high bias and low variance input permeability model used
632 here is likely to underfit the observed CO₂ distribution (Geman et al., 1992).
633 Equally, a low bias and high variance approach that manipulates parameters
634 such as permeability and caprock topography on the grid square level to yield
635 a precise match with the observed CO₂ distribution will overfit the data. The

636 choice of parameters that would permit this match is non-unique, a problem
637 exacerbated by the limited number of time-lapse seismic surveys and by the
638 uncertainty in the observed CO₂ distribution.

639 In order to build an improved forecasting strategy, a permeability model
640 with intermediate complexity is required. For example, our simple channel
641 model can be made more complex by the addition of a variable permeability
642 within the channel. However, for unconfined flows, the observed pattern of
643 migration is only sensitive to the area swept out by the CO₂ plume. Estimat-
644 ing parameters in this way, outside of the swept region, is difficult without
645 evidence from additional sources. While a generalized model could be in-
646 verted to find a more complex permeability structure this is, at present,
647 unlikely to lead to significant improvements in the inferred reservoir model
648 and its associated ability to forecast future CO₂ flow.

649 The success of this reservoir simulation, in conjunction with analysis
650 by Bandilla et al. (2014) and Nilsen et al. (2017) amongst others, shows
651 that vertically-integrated models are a computationally efficient alternative
652 to conventional Darcy flow simulators when modeling the flow of CO₂ on
653 appropriate length and time scales. These efficient models can help to im-
654 prove the match between reservoir simulations and geophysical observations.
655 Whilst limited agreement has already been demonstrated at the Ketzin site
656 in Germany and at the Snøhvit site in Norway, the use of low-computational
657 cost reservoir simulations to test suites of reservoir models could enhance
658 our understanding of the sub-surface reservoir characteristics of other fields
659 where CO₂ injection has been carried out (Grude et al., 2014; Lüth et al.,
660 2015). A large body of literature that has already documented analytical
661 solutions for gravity currents in different situations means that the simulator
662 described here can be adapted quickly and easily to model CO₂ flow within
663 other storage geologic reservoirs.

664

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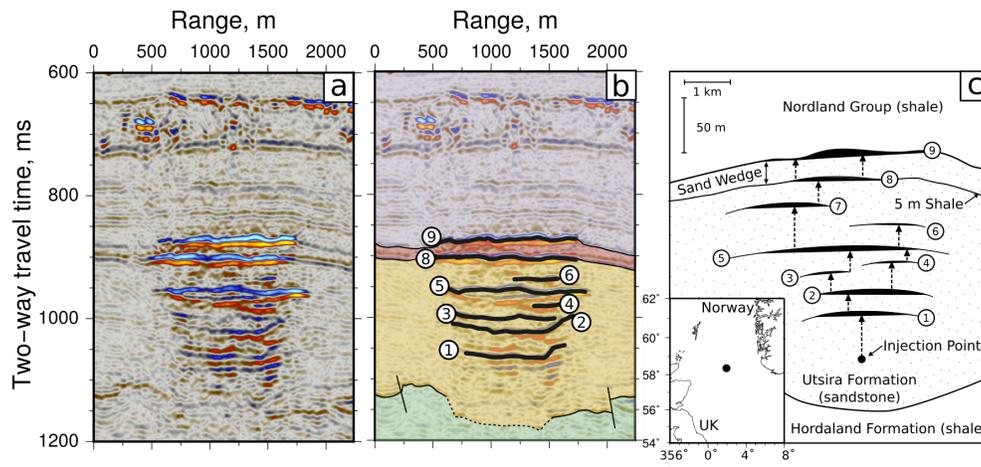


Figure 1: **(a)** Cross-line (i.e. vertical slice) from 2010 seismic reflection survey. Red/blue = positive/negative amplitude reflections. **(b)** Geologic interpretation. Numbered black layers = mappable reflections from CO₂-filled sandstone horizons; orange layer = Sand Wedge unit; yellow layer = Utsira Formation; green layer = Hordaland Formation (solid/dashed line = mappable/extrapolated top of this formation); sub-vertical lines = minor normal faults. **(c)** Schematic cross-section showing configuration of CO₂-filled horizons within saline reservoir (note vertical exaggeration). Dotted pattern = Utsira Formation; numbered black layers = nine CO₂-filled sandstone horizons separated by thin mudstones; solid circle = locus of injection well; dashed vertical arrows = putative flow of CO₂ between sandstone layers. Inset map shows general location of carbon capture and storage project at Sleipner Field.

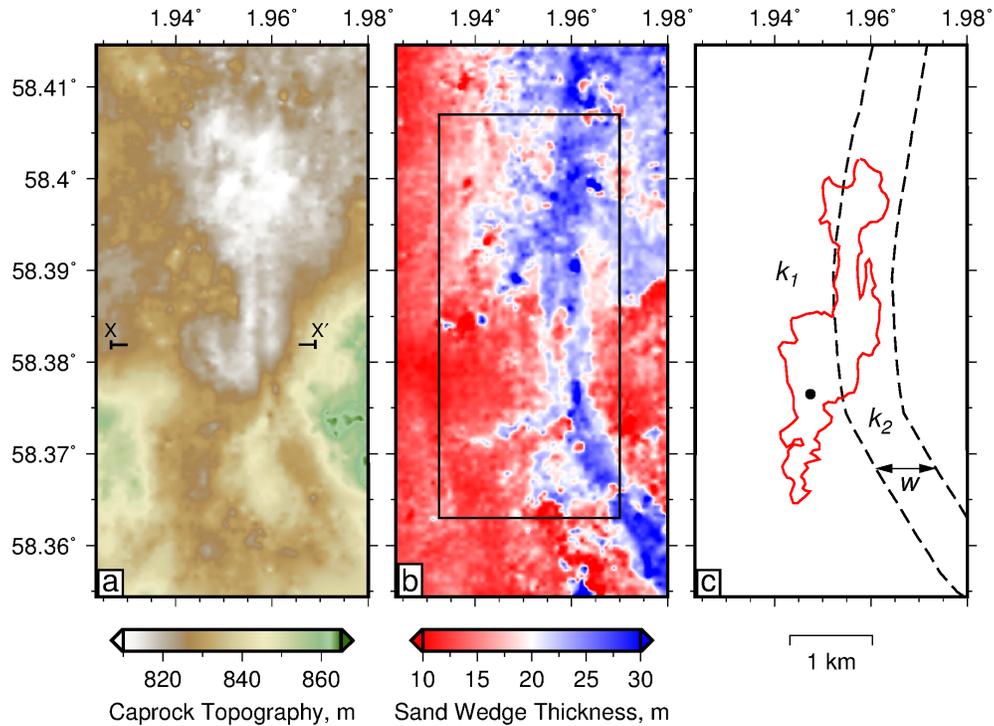


Figure 2: **(a)** Topography of upper surface of Utsira Formation (meters below sea level). $X-X'$ indicates location of seismic profile shown in Figure 1a-b. **(b)** Thickness of Sand Wedge unit. Solid black box = extent of modeled domain described in text. **(c)** Sketch of idealized model used for flow simulations. Solid circle = locus of CO_2 input; red line = outline of CO_2 -filled Layer 9 for year 2010; pair of dashed lines = locus of putative sedimentary channel where w is width of channel in x direction, k_2 is permeability of channel, and k_1 is background permeability.

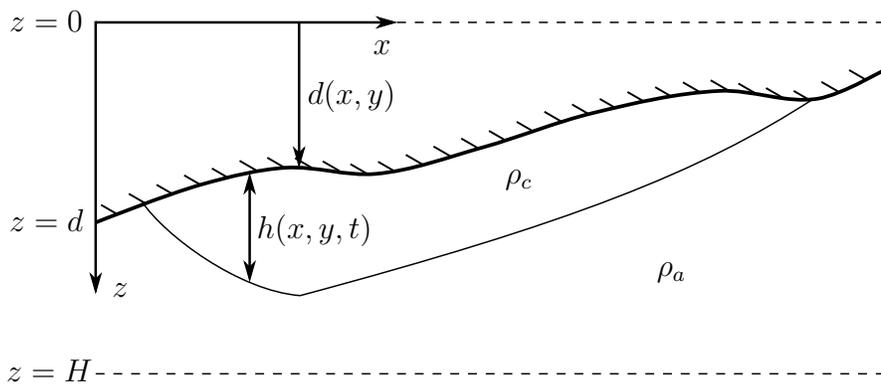


Figure 3: Sketch showing a three-dimensional geometry of gravity current along the sloping interface. Thick line with hatching = caprock interface; thin line = base of gravity current; symbols described in text.

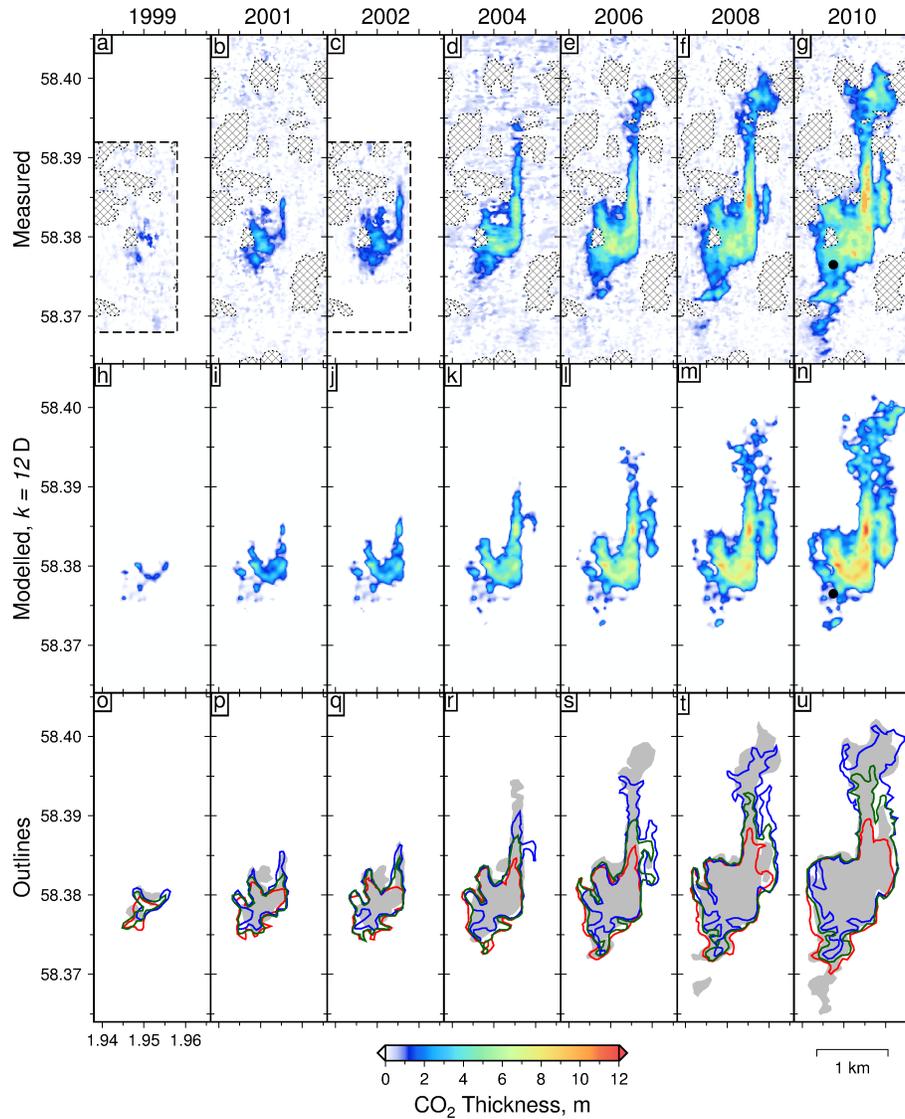


Figure 4: **(a)-(g)** Temporal sequence showing measured distributions of CO₂ thickness for years 1999–2010 determined from analysis of seismic reflection datasets (Cowton et al., 2016). Cross-hatched polygons = regions where reflections are incoherent due to pockets of natural gas within sedimentary overburden; solid circle in panel **(g)** indicates locus of inferred CO₂ input for 2010. **(h)-(n)** Temporal sequence showing predicted distributions of CO₂ thickness using $k = 12 D$. Solid circle as before. **(o)-(u)** Gray polygons = temporal sequence of measured distributions from panels **(a)-(g)**; polygons outlined in red/green/blue = temporal sequence of predicted distributions for $k = 2, 5$ and $12 D$, respectively.

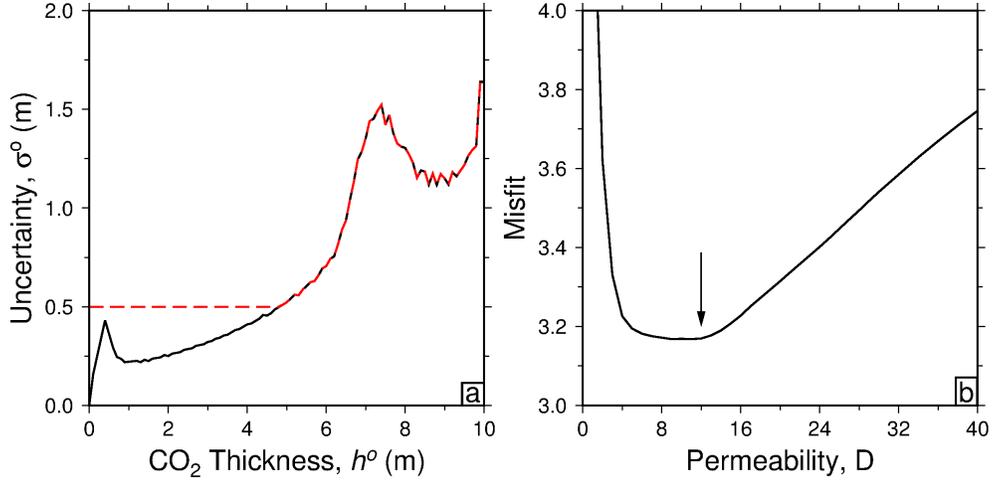


Figure 5: **(a)** Uncertainty of observed thickness measurement, σ^o , obtained using method of Cowton et al. (2016), as function of observed CO₂ thickness, h^o . Black line = values of σ^o gauged from synthetic modeling of CO₂ thickness (Cowton et al., 2016). Red dashed line = relationship between uncertainty and thickness used here for minimizing misfit function which ensures that uncertainty values for $h^o < 5$ are not unrealistically small but set as $\sigma^o = 0.5$. **(b)** Misfit as function of permeability for simulations that assume uniform permeability. Vertical arrow = position of global minimum at 12 D (see Figure 4o-u for end-members).

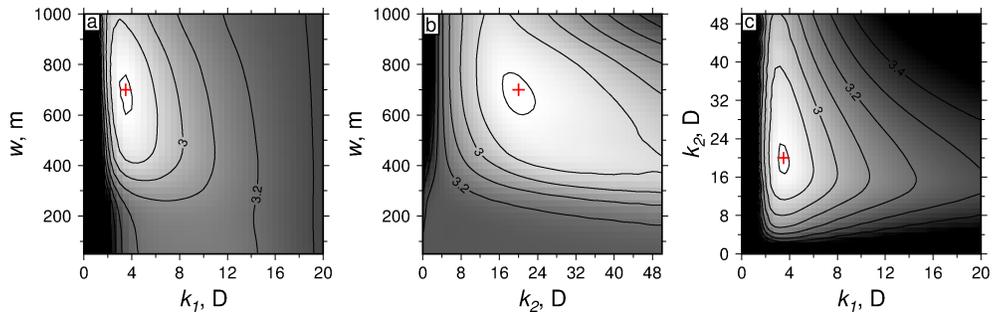


Figure 6: Orthogonal slices through w - k_1 - k_2 misfit function for channel permeability model. **(a)** w - k_1 slice at $k_2 = 20$ D. Red cross = locus of global minimum. **(b)** w - k_2 slice at $k_1 = 3.5$ D. **(c)** k_2 - k_1 slice at $w = 700$ m.

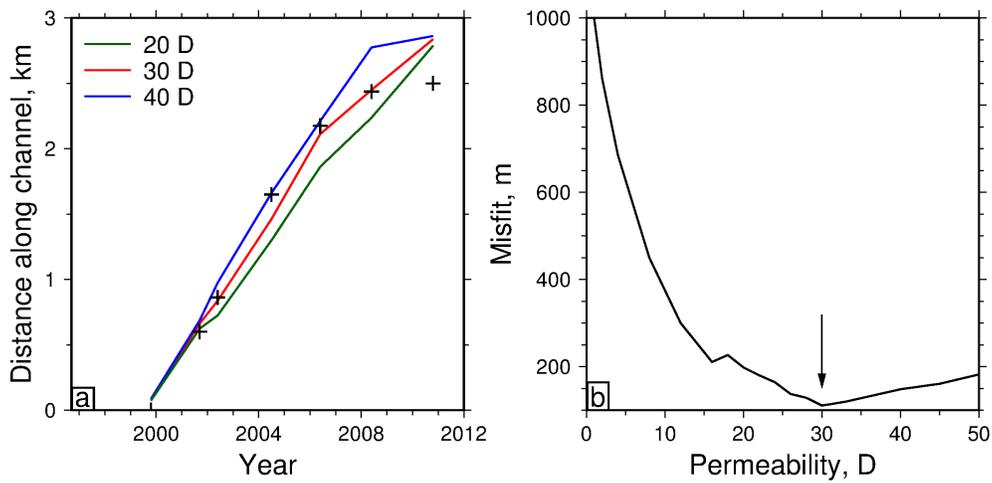


Figure 7: **(a)** Migration distance of CO_2 along channel as function of calendar year for different values of permeability. In each case, distance from estimated entry point is chosen using northernmost grid square where CO_2 thickness is greater than 0.5 m. Crosses = observed migration distances along channel for each calendar year. Green/red/blue lines = simulated migration distances as function of calendar year for $k_2=20$ D, 30 D and 40 D, respectively (in each case, $k_1=3.5$ D and $w=700$ m). **(b)** Misfit between observed and simulated migration rates for all calendar years as function of permeability. Vertical arrow = locus of global minimum at $k_2 = 30$ D.

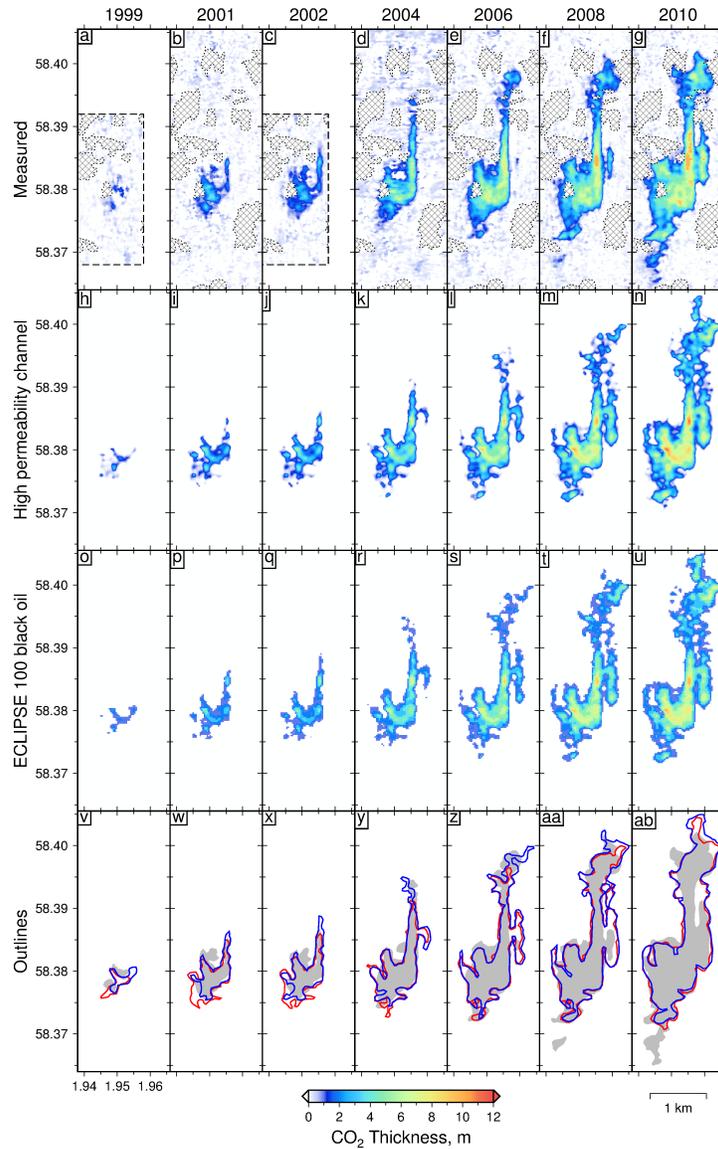


Figure 8: **(a)-(g)** Temporal sequence showing measured distributions of CO₂ thickness for years 1999–2010 determined from analysis of seismic reflection datasets (Cowton et al., 2016). Cross-hatched polygons = regions where reflections are incoherent due to pockets of natural gas within sedimentary overburden. **(h)-(n)** Temporal sequence showing distributions calculated by inverting for optimal channel permeability model where $k_1 = 3.5$ D, $k_2 = 20$ D and $w = 700$ m ($u_1 = 6.5 \times 10^{-4}$ ms⁻¹, $u_2 = 3.7 \times 10^{-3}$ ms⁻¹). **(o)-(u)** Temporal sequence showing distributions calculated using ECLIPSE 100 black oil reservoir model for identical permeability model with half the grid resolution. **(v)-(ab)** Gray polygons = temporal sequence showing measured distributions from panels **(a)-(g)**; polygons outlined in red/blue = temporal sequence of predicted distributions for vertically-integrated and ECLIPSE models, respectively.

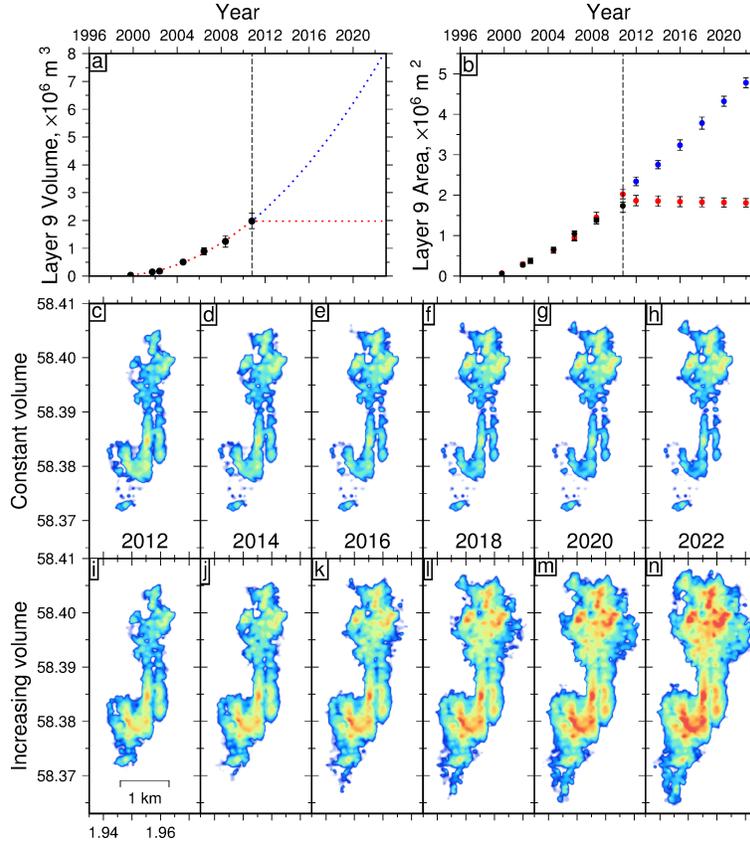


Figure 9: Forecasting calculations. **(a)** Volume of CO₂ injected into Layer 9 as function of calendar year. Solid circles = measured volumes (Cowton et al., 2016); dashed line = calendar limit of available seismic reflection surveys; red dotted line = constant volume of injection into Layer 9 at future times; blue dotted line = increasing volume of injection into Layer 9 in accordance with pre-2010 rate of injection. **(b)** Planform area of Layer 9 as function of calendar year. Solid circles = observed areas of Layer 9 measured using available seismic reflection surveys; dashed line as before; red circles = predicted areas assuming constant volume of injection; blue circles = predicted areas increasing volume of injection in accordance with pre-2010 values. **(c)-(h)** Temporal sequence predicted distributions of CO₂ thickness for years 2012–2022 where post-2010 injected volume remains constant. Forecasts were calculated using 700 m-wide channel with permeability of 20 D embedded in background permeability of 3.5 D. **(i)-(n)** Temporal sequence showing predicted distributions where injected volume grows in accordance with pre-2010 estimated. Color scale as for Figure 8.

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