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Estimating the index flood with continuous hydrological models: an application in Great Britain.

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9 Estimates of peak river discharge are essential for designing and managing hydraulic infrastructure such as dams, bridges, and flood alleviation schemes. Typically these 10 are derived for an assigned annual exceedance probability (e.g. the 1 in 100 year 11 flood), and the provision of accurate estimates is a critical issue in engineering 12 hydrology, affecting both financial cost and human lives. In the UK, practitioners 13 typically apply the Flood Estimation Handbook (FEH) statistical method which 14 estimates the design flood as the product of a relatively frequent flow estimate (the 15 index flood, IF) and a dimensionless regional growth factor used for estimating peak 16 flows at higher return periods. For gauged catchments the IF is usually estimated from 17 observations as the median annual maximum flow which has a two year return period. 18 For ungauged catchments it is computed through a multiple linear regression model 19 20 based on a set of morpho-climatic indices of the basin.

While the FEH IF methods provide peak flow estimates that are robust and defensible, 21 they do not readily take into account catchment or rainfall heterogeneity (important for 22 large catchments) or the effect of environmental change on river flows. Successful 23 application to regions outside the UK currently requires a network of good quality, long-24

term flow gauges to underpin the design flood method, not always present in lessindustrialised regions of the world.

With the aim of addressing these limitations, we present and assess a methodology 27 to estimate the IF at national scale using continuous simulation from an area-wide 28 physically-based hydrological model (Grid-to Grid or "G2G"). The new methodology is 29 tested across Great Britain and compares well with estimates of the IF at 550 gauging 30 stations (R²=0.91) and similar performance simulating the annual maxima trend over 31 time. The promising results for Great Britain support the aspiration that continuous 32 33 simulation from large-scale hydrological models, supported by the increasing availability of global weather, climate and hydrological products, could be used to 34 develop robust methods to help engineers estimate design floods in regions with 35 limited gauge data or affected by environmental change. 36

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38 1. Introduction

An accurate estimate of the design flood, i.e. the peak flow for an assigned probability 39 of exceedance (NERC, 1975), is a critical requirement for reducing the social and 40 economic impact of floods. Floods constitute 40% of worldwide natural disasters (EM-41 DAT, 2015) and often cause fatalities and damage to houses, businesses and 42 infrastructure. Commonly, design flows are estimated with statistical models fitted to 43 annual maxima (AMAX) measured at a gauged site (flood frequency analysis). 44 Unfortunately hydrological records are often unavailable at the site of interest or, when 45 available, they are too short to allow reliable statistical analyses. To overcome this 46 limitation a standard approach is to adopt a "regionalization" procedure which 47 introduces data from other sites into the flood frequency analysis, chosen on the basis 48 that they exhibit similar hydrological behaviour. The regions from which these sites 49

50 can be selected are typically defined using one of several different regionalization methods such as cluster analysis, the region of influence approach, the method of 51 residuals and canonical correlation analysis. Several authors review these 52 regionalization methods (Blöschl et al., 2013, Srinivas et al., 2008, Hrachowitz et al., 53 2013). The index flood method (Dalrymple, 1960) is one of the most popular 54 regionalization procedures among engineers and practitioners (NERC, 1975; Hosking 55 and Wallis, 2005; Institute of Hydrology, 1999). The method is based on the 56 assumption that, for all the sites inside a "hydrologically homogeneous" region, the 57 58 AMAX frequency distributions are identical apart from a local scaling factor (index flood, IF [m³ s⁻¹]). This assumption allows the computation of any p-th quantile at any 59 location i-th as: 60

$$61 \qquad Q_i^p = IF_i \cdot q^p \tag{1}$$

where I_{i}^{p} is the index flood at location i and q^{p} [-] is the regional growth curve, a 62 dimensionless quantile function assumed to be identical for all the sites in the region. 63 Various approaches have been developed to provide reliable estimates of IF, and 64 Bocchiola et al., (2003) provides a summary of some of the most widely used. Broadly, 65 if the site of interest is gauged, the IF can be estimated by direct methods, i.e. from 66 the AMAX time series, using the sample mean (Dalrymple, 1960, Hosking and Wallis, 67 1993, NERC, 1975), the sample median (Robson and Reed, 1999), or using peak over 68 threshold analysis (Chow et al., 1988, Robson and Reed, 1999). If the site of interest 69 is ungauged, a variety of "indirect" methods have been proposed to estimate IF. The 70 most commonly used are empirical methods (Hirsch et al., 1992; Meigh et al., 1997; 71 Kjeldsen and Jones, 2009) that relate the IF evaluated by AMAX measurements to a 72 set of morpho-climatic catchment descriptors such as area, slope, average annual 73 rainfall, land use, etc. These methods include coefficients that are usually estimated 74

by least squares (e.g. Stedinger and Tasker, 1985), maximum-likelihood (e.g. Kjeldsen 75 et al., 2008), and Bayesian methods (e.g. Haddad et al., 2012). The uncertainty in the 76 IF estimate attributable to the data used in the regression model calibration was 77 quantified by Jaafar, W., Zurina and Han, (2012). Other indirect approaches for 78 estimating IF and flow quantiles are based on on the use of artificial neural networks 79 (e.g. Hall et al., 2002; Shu and Burn, 2004; Dawson et al., 2006) or on the connection 80 between stochastic rainfall models and lumped flow routing models (Cordova and 81 Rodriguez Iturbe, 1983; Brath et al., 1992; Calver et al., 2005; Kjeldsen et al., 2005; 82 83 Rigon et al., 2011). Limitations of the latter modelling approach are: i) the simplified assumptions for the hydrological model component; ii) the requirement of catchment 84 initial moisture conditions; iii) the assumption of high simplified and uniform rainfall 85 storms in catchment. 86

Indirect estimation of IF based on continuous physically-based hydrological model 87 simulations has also been explored in recent years. The advantages of such an 88 approach include: i) taking into account catchment heterogeneity, ii) accommodation 89 of temporal and spatial rainfall variability, and iii) ability to provide a consistent IF 90 estimate for multiple points on the river network. Demonstrations of the use of 91 continuous, physically-based model simulations for flood frequency analysis are 92 provided for various catchments by Cameron et al., (2000), Calver et al., (2005), 93 94 Moretti and Montanari, (2008), and Viviroli et al., (2009), but to our knowledge, only Ravazzani et al., 2015 used continuous hydrological model simulation for estimating 95 the IF. They applied the model FEST-WB (Montaldo et al. 2007, Rabuffetti et al. 2008) 96 to reconstruct river flows for an alpine basin in the north part of Italy and to predict the 97 IF. 98

For a gauged location, an estimate of the IF recommended by the FEH, is the median 99 of the observed AMAX. This corresponds to the 2 year return period flow which is 100 considered a good estimate of the bankfull river discharge. If less than 14 years of 101 102 AMAX are available, the FEH suggests use of peak over threshold data. For ungauged sites, the Environment Agency Flood Estimation Guidelines 2012 recommends use of 103 the regression model of Kjeldsen et al. (2008) to estimate the IF. Practitioners are also 104 advised that data transfer from donor catchments to the site of interest can improve 105 the accuracy of IF estimates (Kjeldsen and Jones, 2007). The "donors" are gauged 106 107 catchments hydrologically similar to the site of interest (i.e. located upstream or downstream on the same river, or possessing similar size and land use). 108

Here we present a general methodology to estimate the IF at national scale using continuous hydrological simulation (Section 2). This approach aims to: i) integrate the indirect methods for IF estimation and address their limitations for larger and spatially heterogeneous catchments, and ii) provide effective tools for IF estimation in ungauged or poorly gauged catchments. The methodology is tested in Great Britain (Section 3) and assessed (Section 4) by comparison with estimates of the IF at 550 gauging stations.

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117 2. Methodology

The area-wide physically-based hydrological model Grid-to-Grid (G2G, Bell et al., 2007a,b; 2009) has been used to estimate the IF at national scale. The G2G typically operates at a 1km² resolution across Britain and has been configured to represent spatial variability in catchment response. The model uses landscape information provided by gridded spatial datasets of elevation, soil and geology in preference to the identification of model parameters through catchment calibration, and for the application discussed here, a single model configuration and set of parameters is
applied across Britain (i.e. with no catchment calibration). G2G model configuration
and inputs are discussed in subsection 2.1. Model output consisting of river flow time
series at each 1km² river grid-cell are used to construct maps of AMAX across Britain
and to estimate the IF following the FEH methodology (Institute of Hydrology, 1999).
Annual maxima in the UK are taken as the highest flow value recorded in a water year,
which runs from October to September.

G2G modelled IFs were compared to measured IFs for 550 gauged sites using 131 132 observations obtained from the National River Flow Archive (NRFA). Modelled and measured IFs were compared using a linear regression, together with an analysis of 133 the sensitivity of model performance to morpho-climatic catchment descriptors. The 134 agreement between the G2G-derived and the measured IF was evaluated by: i) 135 quantifying the coefficient of determination, and ii) assessing the uncertainty in IF 136 estimate using the factorial standard error (Kjeldsen, 2014). Maps of model residuals 137 (differences between modelled and measured IF) provide additional information on 138 regions and types of catchment where the model performs best (and worst). Finally 139 the temporal trends of modelled and measured AMAX were compared to assess the 140 model capability in detecting observed long term trends. 141

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143 2.1 Grid-to-Grid model set-up and input data

The Grid-to-Grid Model (Bell et al., 2007a) is a grid-based hydrological model that simulates surface and sub-surface runoff, lateral movement of soil-moisture, and flowrouting along rivers. Over Britain it is typically applied at a 1km² grid resolution and a 15-minute time-step, and is configured using spatial datasets of topography, soil, and land cover. Applications include flood forecasting (e.g. Cole and Moore, 2009) and

assessment of climate change impacts on floods and snowmelt (i.e. Bell et al., 2007b; 149 Bell et al., 2009; Bell et al., 2016). The most recent version of the model as presented 150 in Bell et al., (2016) was tested over the Great Britain for the period 1960-2011. Driving 151 data consist of daily precipitation observations on a 1 km² grid, (CEH GEAR: Keller et 152 al., 2015), monthly PE estimates on a 40 km² grid (MORECS: Hough and Jones, 153 1997), and daily minimum and maximum temperature observations on a 5km² grid for 154 1960–2014 (Perry et al., 2009) which were applied through the day using a sine curve 155 and downscaled to 1 km² using a lapse rate and elevation data (Morris and Flavin, 156 157 1990). Model output consisting of 15 minutes river flows were used to provide AMAX values for 1km² river grid-cells across Britain. 158

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160 3. Study Area and Data Availability

The study region includes 550 catchments from England, Scotland, and Wales. They 161 are part of the United Kingdom peak flow dataset (version v4.1) obtained from "The 162 National River Flow Archive" (NRFA, 2008; Dixon et al., 2013) and available at 163 http://nrfa.ceh.ac.uk/. For the purposes of this analysis we used the instantaneous 164 peak flow AMAX values and a set of catchment descriptors consisting of: the 165 catchment area (AREA [km²]); the average annual rainfall (SAAR, [mm]) for the period 166 1961-1990; the base flow index based on the Hydrology Of Soil Types classification 167 presented in Boorman et al., 1995 (BFIHOST [-]), which reflects the geology of the site 168 and has typical values that ranges from below 0.2 (highly impermeable) to above 0.8 169 (highly permeable); the mean distance between each pixel of the basin and the outlet 170 (mean drainage path length, DPLBAR, [km]), and the extent of urban and suburban 171 land cover during the year 2000 (URBEXT2000, [-]). Table 1 summarises these 172 catchment properties in terms of the mean, minimum, maximum, and standard 173

deviation value over the chosen set of 550 catchments. Of the 810 catchments for 174 which peak flow data are available in Great Britain, 260 have been excluded for various 175 reasons, including catchment size, and how well the gauged flows are thought to 176 represent actual flows. Specifically, 225 catchments where DPLBAR<10 km and Area 177 <50 km² have been excluded from the comparison of simulated and observed peak 178 flows as modelled flows for these relatively small catchments were most likely to be 179 adversely affected (underestimated) by the use of daily mean rainfall. These 180 catchments have a faster hydrological response and probably the use of hourly rainfall 181 182 data would be more appropriate to mimic the instantaneous peak flows. A modest number of catchments (35) were excluded due to strong anthropogenic influences 183 including: i) the presence of an artificial channel that modifies the natural flow-paths; 184 ii) unreliable rating curves due to the lack of high flow measures; and iii) strong 185 influence of reservoirs or groundwater abstraction on the flow regime. Figure 1 186 presents a map of the study area, the location of the gauges selected for the analysis 187 (black points), and the excluded gauges (white points). 188

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190 4 Results and Discussion

191 4.1 Model Verification and Index Flood Map Estimation

A linear regression model was fitted to the measured and modelled log-transformed IF values for 550 catchments. The G2G model was executed for the whole simulation period (1960-2014) and the modelled IF in a given gauged station was computed using the modelled AMAX values corresponding to the period for which the measurements were available. Figure 2-a shows a scatterplot of 550 G2G and observation-derived IFs in logarithm scale, together with the derived linear regression model plot, and Table 2 shows the summary statistics of the linear regression model. The high values

of the t-ratio, computed as the coefficient estimated value divided by its estimated 199 standard deviation, give an indication that the estimated coefficients are statistically 200 different from 0. The coefficient of determination R²=0.91 summarizes the goodness 201 of fit. Following Kjeldsen (2014), given the large number of catchments for which the 202 model was evaluated (550) it is reasonable to assume that the prediction variance can 203 be approximated by the variance of the regression model residuals, s=0.15. Under this 204 assumption it is possible to evaluate the factorial standard error of the model 205 FSE=1.47. The latter defines the 68% and 95% confidence intervals for the regression 206 model as [q. FSE-1; q. FSE] and [q. FSE-2; q. FSE2] respectively (Kjeldsen, 2014), 207 where q indicates given discharge value. In our case q corresponds to the median of 208 the AMAX. The FSE presented in this study is comparable with the FSE values of the 209 210 regression models currently used in FEH which are based on the AMAX measurements of 600 gauging stations. The original FEH index flood regression model 211 reported an FSE value of 1.56 (Robson and Reed, 1999) and the revised model 212 lowered it to 1.431 (by assuming that the correlation between model errors is a function 213 of the geographical distances between gauging stations (Kjeldsen et al., 2008)). 214

Figure 2-b presents a map of the residuals between modelled and measured IF using 215 a logarithmic scale. The residuals are close to zero across most of Britain, with a 216 modest underestimation in central and south west England, and a similarly modest 217 overestimation in the South East. A significant factor contributing to the 218 underestimation is the contribution of short-duration intense rainfall events to peak 219 river flows in central and southern Britain, which will be poorly represented by daily 220 gridded rainfall observations, while the overestimation in southern and eastern Britain 221 can, for many groundwater-dominated catchments, be attributed to the effects of 222 artificial abstractions which are not currently included in the G2G model formulation. 223

Figure 3-a presents a map of the modelled index flood (m³s⁻¹) on a logarithmic scale, 224 for the period 1960 to 2014. The IF is typically higher in the north and west of Britain, 225 and in major rivers. The use of continuous G2G model simulation provides a consistent 226 spatial and temporal dataset to explore whether there has been a significant change 227 in the IF over the last 50 years. Figure 3-b presents a map of the change in the derived 228 index floods between two periods: 1960 to 1986 and 1987 to 2014. The changes range 229 from an increase in the IF of up to 45 m³s⁻¹ (predominantly in the north and west) to a 230 decrease of -40 m³s⁻¹ in parts of Southeast Britain. This regional split is broadly in line 231 232 with the increased trends detected in measured mean daily flows since the early 1960s in Scotland and, to a lesser extent, Wales and western England (Hannford and Marsh, 233 2008). However, the authors noted that the analysis of trends in some areas was 234 limited by the available length of record. 235

The use of continous model simulation provides a method of estimating the IF with a 236 91% agreement with observation-derived estimates for 550 catchments across Britain. 237 In order to investigate whether this agreement is influenced by catchment properties 238 a series of analyses relating model fit with properties such as area, drainage path 239 length, urban extent and baseflow index were undertaken. For each catchment 240 property, the catchment values were divided into deciles (i.e. the nine values that 241 divide the sorted data into ten equally sized subsamples) and measured and modelled 242 IF for each catchment property subgroup were compared. Figure 4 presents 10 243 scatterplots and the coefficient of determination (R²) of linear models fitted to the 244 results for the catchment property: AREA. The title of each scatterplot specifies the 245 AREA range [km²] of each classes, for example the first plot is for catchments which 246 range in area from 53 to 80 km², the second from 80 to 110 km², etc. Similar results 247 are presented for percentage of urban extent (URBEXT2000) in Figure 5, and for 248

baseflow index (BFIHOST), and drainage path length (DPLBAR) in Figure A1 and A2 249 in Appendix 1. The model fit is robust in the sense that is not strongly affected by the 250 catchment properties. The decile range in R² is 0.82-0.90 for AREA, 0.78-0.92 for 251 URBEXT2000, 0.81-0.93 for BFIHOST, and 0.84-0.91 for DPLBAR. These figures 252 indicate relatively high levels of agreement between modelled and measured IF 253 estimates, suggesting that the quality of the G2G estimated IF is relatively unaffected 254 by different catchment properties and can provide estimates of consistent quality 255 across various types of catchment (e.g. small, steep, or urbanized catchments). 256

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4.2 Annual Maxima Trend Analysis

In the previous section we assessed whether AMAX output from a G2G continuous 259 simulation could be used to estimate the measured IF by comparing the median of 260 observed and simulated AMAXs over several decades. Typically, however, climate, 261 anthropogenic or natural changes at the catchment scale can lead to long-term trends 262 in observed annual maxima. For this reason it is important to ensure that if AMAX from 263 continuous hydrological simulation are used in place of observed AMAX, they can also 264 reproduce observed trends in river flows. This trend analysis has now been 265 undertaken on 285 catchments, selected from the original 550, for which at least 40 266 year of measured flow data are available and the Mann Kendall test (MK, Kendall, 267 1975) with permutations provides a measure of the significance of potential trends in 268 time. This method is presented in detail by Kundzewicz and Robson (2000) and has 269 been used in several applications (i.e. Hannaford and Marsh, 2008, Hannaford and 270 271 Marsh, 2006). The procedure is as follows: i) randomly re-order the AMAX time series to provide a large number of samples with no replacement; ii) perform Mann-Kendall 272 trend test to each sample; iii) rank the trend test results; iv) compute the trend test for 273

the original time series. If the derived trend for the original series falls outside the [0.05, 274 0.95] percentile range of the ranked values, it is deemed to be significant at the 95% 275 confidence level, indicating a change in the magnitude of the AMAX over the 40-year 276 period. The statistical tests have been performed on both measured and modelled 277 AMAX providing test values (including the direction of the trend) and significance 278 assessments for a trend in both the measured and modelled series. Results have been 279 compared for the 69 catchments where the trend for the measured AMAX presented 280 a significant test at the 95% significance level and are shown in Figure 6. No results 281 282 are available for Scotland because the two criteria of at least 40 year of measured flow data are available and trend with a 95% significance level were not matched. 283

Figure 6 shows that: i) for 59 catchments positive trends were detected in both 284 modelled and measured AMAX and ii) for 10 catchments the trend in the modelled 285 series is not in agreement with the direction of the trend in the measured AMAXs 286 series. These catchments are predominantly located in the south east part of England 287 and for all of them the NRFA archive suggests that the runoff is affected by at least 288 one of these reasons: a) reservoir in the catchment, b) presence of industrial or 289 agricultural abstraction, and c) presence of water supply and groundwater 290 abstractions. This anthropogenic influence which is not modelled in the current 291 version of G2G may potentially explain the differences between measured and 292 293 modelled AMAX trend in time for those basins.

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295 Conclusions

In this paper we demonstrate how use of continuous flow simulation by a nationalscale distributed hydrological model (such as G2G) can be used to estimate key parameters such as the index flood (IF) required for flood estimation methods. The comparison between index floods estimated from current (FEH) and continuous simulation methods for 550 catchments throughout Great Britain indicates a good correlation between the two methods (R²=0.91, factorial standard error FSE=1.47). We have also demonstrated that AMAX from continuous hydrological simulation can reproduce observed trends the measured annual maxima (agreement in 90% of the analysed catchments), indicating the potential utility of the methodology for conditions of non-stationarity.

This initial assessment of continuous simulation from a national-scale hydrological 306 307 model (G2G) for estimating the IF is encouraging and demonstrates the new method can potentially overcome current methodological limitations such as the assumption 308 of spatially homogeneous rainfall over the catchment and climate non-stationarity. 309 310 Other benefits of the proposed new method include estimation of index floods in catchments subject to anthropogenic change, which at present can only be estimated 311 using observed flows in naturalised catchments and require a correction to take into 312 account the extent of urbanisation. Here, the accuracy of IF estimates from G2G 313 continuous simulation is shown to be relatively unaffected by catchment properties 314 such as area and urban extent, indicating that the methodology is robust for a variety 315 of catchment types, so long as the continuous hydrological simulation is able to take 316 into account the many factors (natural and anthropogenic) affecting river flows. 317

Countries such as Britain, for which an extensive network of flow and raingauges can support existing observation-based FEH methods, provide ideal test conditions for assessing the ability of alternative model-based flood estimation methods, such as continuous simulation from large-scale hydrological models, to underpin methods for flood estimation in data-sparse regions. It is to be hoped that the increasing availability and accuracy of global weather, climate and hydrological products can be used to

324	develop a robust methodology to help engineers estimate design floods in regions with
325	limited gauge data or affected by environmental change, potentially saving many lives.
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524 Figures





Figure 1: Location of the 550 catchments used in this study







Figure 3: Maps of Britain showing, on a logarithmic scale: (a) Modelled index flood (m³s⁻¹) for the
period 1961-2011 (b) Change in the derived index flood (m³s⁻¹) between 1961-1985 and 1986-2011.

			AREA C	LASSES		
		(53,80]	(80,110]	(110,138]	(138,171]	
	1000	$R^2 = 0.9$	R ² = 0.89	R ² = 0.87	R ² = 0.86	
	10		J.	1	Į.	
			1	K		
	[s]	(171,203]	(203,258]	(258,357]	(357,546]	
	<u>E</u> 1000	$R^2 = 0.9$	$R^2 = 0.87$	$R^2 = 0.9$	$R^2 = 0.87$	
	aasured index flood		1	1	1	
	Ψ	(546 1 02e+03)	(1 02e+03 9 93e+03)]]
		$R^2 = 0.8$	$R^2 = 0.82$			
	1000					
	10	0-				
553		10 1000	10 1000 G2G index	flood [m3/s]		
554	Figure 4: Scatte	erplots and coefficient	cients of determir	nation for model	led and measured	l index flood
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578	Figure 6: Comparison between the measured and modelled AMAX trend with time with a 95%
579	significance. The catchments where both model and data agree are represented by blue triangles
580	(positive); the points where they disagree are represented by black points.
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593 Tables

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595 Table 1: Summary statistics (minimum, median, maximum, and standard deviation value) for the

selected set of catchments indicators: AREA, SAAR, BFIHOST, DPLBAR, and URBEXT2000

	AREA [km ²]	SAAR [mm]	BFIHOST [-]	DPLBAR [km]	URBEXT2000 [-]
Minimum	55	558	0.24	10	0
Median	203	962	0.47	19	0.009
Maximum	9931	2913	0.96	140	0.592
Stand. Dev.	935	401	0.14	18	0.085

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599 Table 2: Summary of the linear regression model linking the measured and modelled index floods

	=	Intercept	T-Stat	Scaling exponent	T-Stat	Residual	R ²
		moroopt	intercept		Scaling exponent	Stand. Dev	
	=	0.41	8.995	0.99	76.681	0.386	0.910
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606	Append	lix 1					
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			BFIHOST	CLASSES		
		(0.23,0.35]	(0.35,0.39]	(0.39,0.42]	(0.42,0.45]	
	1000-	R ² = 0.9	R ² = 0.91	R ² = 0.84	R ² = 0.86	
	[S/	(0.45,0.48]	(0.48.0.5]	(0.5.0.54]	(0.54,0.59]	
	- 1000 لي 10- بالموط 10- أي	R ² = 0.89	R ² = 0.92	R ² = 0.93	R ² = 0.89	
	Measure 0001-	(0.59,0.7] R ² = 0.86	(0.7,0.96] R ² = 0.84			
	10-	1	1			
608		10 1000	G2G index	(flood [m3/s]		
609	Figure A1: Scatte	erplots and det	ermination coeffic	cients for modelle	ed and measured	l index fl
610			grouped by BFIH	OST classes.		
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grouped by DPLBAR classes.

(10,11.7]