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1 **Plastic mulch and nitrogen fertigation in growing vegetables modify soil**
2 **temperature, water and nitrate dynamics: experimental results and a**
3 **modeling study**
4

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14

15 **ABSTRACT**

16 Plastic mulch in combination with drip irrigation present a common agricultural management
17 technique practiced in commercial vegetable production. This management can result in various
18 impacts on water and nutrient distribution and consequently affect nutrient dynamics in underlying
19 soil. The aim of this work was to: (i) compare the effects of different mulching types (color) on soil
20 temperature and (ii) crop growth; (iii) estimate the effect of plastic mulch cover (MULCH) on water
21 and (iv) nitrate dynamics using HYDRUS-2D. The field experiment was designed in the Croatian
22 coastal karst area on main plots with three levels of nitrogen fertilizer: 70, 140, and 210 kg ha⁻¹, which
23 were all divided in five subplots considering mulch covering with different colors types (black, brown,
24 silver, and white) and no covering (control). Monitoring of water and nitrate dynamics was ensured
25 through lysimeters which ensured input data for HYDRUS-2D model. The experimental results
26 showed that plastic mulch had a significant effect on soil temperature regime and crop yield. The dark
27 color mulch (black, brown) caused higher soil temperature, which consequently enabled earlier plant
28 development and higher yields. HYDRUS-2D simulated results showed good fitting to the field data

29 in cumulative water and also nitrate outflow. Water flow simulations produced model efficiency of
30 0.84 for control (CONT) and 0.56 for MULCH systems, while nitrate simulations showed model
31 efficiency ranging from 0.67 to 0.83 and from 0.70 to 0.93, respectively. Additional simulations
32 exposed faster transport of nitrates below drip line in the CONT system, mostly because of the
33 increased surface area subjected to precipitation/irrigation due the absence of soil cover. Numerical
34 modeling revealed large influence of plastic mulch cover on water and nutrient distribution in soil.
35 Study suggest that under this management practice the nitrogen amounts applied via fertigation can be
36 lowered and optimized to reduce possible negative influence on environment.

37

38 **Keywords:** Plastic mulch cover; Vegetable cultivation; Soil temperature; Water flow; Nitrate
39 dynamics; HYDRUS-2D.

40

41 **1. INTRODUCTION**

42 Growing global population, the consequent demand for food and increasing access to
43 irrigation have resulted in agriculture being the main water consumer at the global scale. Commercial
44 vegetables producers apply intensive management which involves high irrigation demands and input
45 of agrochemicals. Plastic mulch application is a common agricultural practice due to variety of
46 benefits to the crop, mostly vegetable biomass production. Plastic mulch can be used: (i) to modify
47 soil temperature, which may promote faster growth early in the season and generally lead to earlier
48 harvest, (ii) for effective weed control, (iii) to prevent nutrient losses by leaching, (iv) to prevent fruit
49 contact with soil, and (v) to reduce soil water loss by decreasing evaporation from the soil surface
50 (Fritz, 2002).

51 Various vegetables including bell pepper are commonly grown along the Mediterranean coast
52 in raised soil beds (ridge) covered with plastic mulch. The use of impermeable plastic mulch in bell
53 pepper cultivation affects water fluxes and may change crop water use and distribution compared to
54 open-field conditions (Allen et al., 1998; Amayrehand and Al-Abed, 2005). It can also improve water
55 use efficiency and decrease irrigation requirements by 10-20% by reducing soil evaporation (Deng et
56 al., 2006), as it acts as a moisture barrier which diminishes the surface area of soil evaporation. Plastic

57 mulch affects the microclimate around the crop by modifying the radiation budget (absorptivity vs.
58 reflectivity) of the surface and by decreasing the soil water loss. Color affects the surface temperature
59 of the mulch cover and consequently the underlying soil temperature.

60 Drip irrigation is usually placed underneath mulches for precise management of soil moisture
61 and nutrients, which can reduce irrigation frequency and quantity, and may reduce the incidence of
62 moisture-related physiological disorders. Combination of drip irrigation method with liquid fertilizer
63 application provides an effective and cost-efficient way of water and nutrients addition to crops (Bar-
64 Yosef, 1999) while minimizing leaching of nutrients from the root zone (Gärdenäs et al., 2005).
65 However, different crop management techniques such as mulch covers can have various impacts on
66 water and nutrient distribution in underlying soil and consequently affect nutrient leaching towards
67 groundwater resources. Liquid fertilizers are usually applied together with irrigation water which
68 makes them easily available for crops, but also for leaching to deeper soil layers.

69 Karst areas exhibit a challenge for the protection of groundwater resources, because high
70 heterogeneity, high vulnerability and fast groundwater flow result in low natural attenuation of
71 contamination (Bakalowicz, 2005). Due to geological and climatic conditions as well as anthropogenic
72 influence, high leaching potential is present in such environment in which agrochemicals can easily
73 reach groundwater or surface water resources (Romić et al., 2003a). Episodic rainfall events of high
74 intensity can lead to rapid recharge, which has strong impact on discharge and contaminant transport
75 to karst springs, particularly if the conduit system (*e.g.* soil porous system) is well developed
76 (Butscher et al., 2011).

77 Numerical modeling is being quite popular lately for the assessment of different agrochemical
78 leaching and water distribution under various initial and boundary conditions due to their rising
79 accuracy and effectiveness. In the absence of large experimental data sets, we can explain water and
80 nutrients dynamics in multi-dimensional space using mathematical solutions by performing numerical
81 simulations. The HYDRUS code is widely used for modeling water and solutes dynamics in the
82 (un)saturated zone in a one-, two or three-dimensional direction (Šimůnek et al., 2008). The HYDRUS
83 allows for specification of water and nutrient uptake, transport of multiple solutes, which can be either
84 independent or involved in sequential first order decay reactions, *e.g.* nitrification chain. The code has

85 been largely used to simulate fertigation and/or nitrate leaching (Hanson et al., 2006; Filipović et al.,
86 2013; Phogat et al., 2013). Rudisch et al. (2013) performed a modeling study using HYDRUS-2D to
87 evaluate the effect of plastic mulched ridge (raised soil beds) cultivation on soil water dynamics under
88 potato fields (*Solanm tuberosum* L.) on hillslopes in South Korea. The results indicated that plastic
89 mulch reduced drainage up to 16% but on the other hand increased surface runoff up to 65%, which
90 could lead to soil erosion and flood risk. Liu et al. (2013) simulated the temporal variations of soil
91 water content in a drip irrigated cotton field under mulching. They used HYDRUS-2D to fit the
92 observed soil water content indicating satisfying model accuracy.

93 Most of the modeling studies dealing with similar topics are focused on simulations of water
94 flow and/or nutrients under plastic mulch or drip irrigation system, but not their combination, so there
95 is a gap in the understanding how the plastic mulch in combination with drip irrigation affects soil
96 moisture and nitrate distribution. The effect of plastic mulch on water and a consequent solute
97 translocation are not well understood, in terms of their exact quantity and location in time below the
98 vegetable planting rows. Therefore, the objectives of this study were: (i) to compare the effects of
99 different mulching types (color) on soil temperature and (ii) consequently crop growth; (iii) to estimate
100 the effect of plastic mulch cover on water and (iv) nitrate dynamics using HYDRUS-2D. The
101 modeling study using 2D presentation is expected to allow better understanding of soil water dynamics
102 and nitrate behavior in crops managed with plastic mulch and drip irrigation.

103

104 **2. MATERIALS AND METHODS**

105 **2.1. Field experiment**

106 The experimental site was located in the Croatian coastal area *i.e.* Vrana valley (43°57' N,
107 15°30' E), which is an area with intensive agricultural (mostly vegetable) crop production. Vrana basin
108 is an ecologically highly sensitive area (in terms of leaching potential) located in a karst environment.
109 Additionally, the applied agrochemicals can easily reach Vransko Lake located in the research area,
110 the largest freshwater lake in Croatia protected as a Natural park, and induce water quality
111 deterioration and eutrophication. Mean annual precipitation in that area is 910 mm, and mean monthly

112 temperatures ranges from 7 °C (January) to 23 °C (July). The soil type is classified as Gleysol (WRB)
113 with 30% clay, and pH value of 7.2 in its tilled layer.

114 Prior to field experiment installation the soil was ploughed till 40 cm depth and harrowed to
115 provide necessary growing condition. Furthermore, experimental plots measuring 20 x 7.5 meters each
116 were treated with herbicide following the agricultural practices used in local vegetable production. The
117 experiment was designed according to the split-plot design in three repetitions with the main plots
118 corresponding to three different N inputs, *i.e.* 70, 140, and 210 kg ha⁻¹. The main plots were divided in
119 five subplots, four of them covered with different plastic mulch color types: black, brown, silver, and
120 white, and the fifth of them, the control subplot, remained without plastic mulch.

121 Fertilizer levels were applied in combination with drip irrigation (7:5:9 NPK, liquid fertilizer,
122 INA, Petrokemija - where N was in form of ammonium and nitrate). Irrigation was performed with a
123 single line of drip irrigation tape with 30 cm spaced emitters (Netafim, Israel) that was placed in the
124 center of each bed prepared for planting transplants. Installation of mulching materials and the drip
125 irrigation system, as well as planting of transplants were all done using a tractor-drawn planter and
126 film layer (Maas, MOD 140). Container-grown bell pepper (*Capsicum annuum* L. cv. Bianca F1)
127 transplants were planted on 8–9 May. Prior to mulching, pesticides were sprayed at the field site in
128 order to remove weeds and provide same growing conditions in all plots.

129

130 **2.2. Field monitoring**

131 Temperature probes were installed on all subplots near soil surface at 5 cm depth. Soil
132 temperature was measured three times a day *i.e.* always at 7, 14 and 21 h, during the period from May
133 15th till October 10th. Due to initial data fluctuation and a necessary period for probe calibration, the
134 first two weeks of measurements were excluded from the results. Therefore, the results presented
135 correspond for the period between June 4th and October 10th.

136 Field lysimeters were installed into 9 subplots, *i.e.* all subplots covered with black and brown
137 plastic mulch and in the three control subplots. For this procedure, a vertical trench was excavated to
138 the depth of 2 m. A horizontal slot was unearthed from the trench at a depth of 90 cm, and a round
139 stainless steel plate lysimeter (Ø 65 cm) was installed into that soil layer in order to not disturb the soil

140 above the plate. PVC net in combination with geotextile (fleece) was installed together with a gravel
141 layer on the lysimeter plate for preventing small particles to be washed with leachate and to conduct
142 the flow. A tygon tube was installed onto the plate to conduct the sampled water toward a 10 L tank
143 buried in the soil at the depth of 150 cm, which also provided a suction corresponding to -90 cm of
144 pressure head.

145 Meteorological data were collected on Jankolovica weather station (located in the proximity of
146 field site) which included daily rates of precipitation, air temperatures (maximum, minimum, and
147 average), humidity, wind speed, and solar radiation. From collected data daily potential
148 evapotranspiration rates were then calculated based on Penman–Monteith approach (Monteith, 1981).
149 The crop coefficient (K_c) approach was used in which crop evapotranspiration is calculated by
150 multiplying ET_o by K_c (Allen et al., 1998). Crop coefficient and the length of each phase (in days)
151 were taken from Allen et al. (1998) for three different growing stages of bell pepper crop *i.e.* initial
152 (K_{c-ini} 0.7), mid-season (K_{c-mid} 1.05), and late season (K_{c-end} 0.95). Daily rates of precipitation, irrigation,
153 evaporation, and bell pepper transpiration are presented on Fig. 1. Crop growth parameters and yield
154 were measured during the growing season on all subplots. Plant height and number of flowers and
155 fruits were determined on 20 plants per subplot. Bell pepper fruits were also collected as they reached
156 maturity and yield was measured.

157

158 **2.3. Laboratory analyses**

159 Bulk soil samples were taken at the beginning of the field experiment in each plot with an
160 auger in four layers of the profile: 0–40, 40–60, 60–92, and 92–120 cm depth, which correspond to
161 different soil horizons. The main physical and chemical analyses were conducted for each soil layer.
162 The particle size distribution was measured by the pipette method after disaggregation in sodium
163 pyrophosphate (HRN ISO 11277:2004). Soil pH and organic matter were determined using a Mettler
164 Toledo MPC 227 conductivity/pH meter in water (pH H₂O) (HRN ISO 10390:2005) and by
165 sulfochromic oxidation (HRN ISO 14235:2004), respectively. Nitrate concentration was determined in
166 the 1.0 M KCl soil extracts (HRN ISO 14256-2:2009) using the continuous flow auto-analyzer
167 (San++ Continuous Flow Analyzer, Skalar). Soil physical and chemical data are presented in Table 1.

168 Undisturbed soil samples of 100 cm³ volume were taken, at the same time and on the same
169 locations of the bulk soils samples, for the determination of bulk density and soil hydraulic properties
170 in each layer (e.g. soil water retention and hydraulic conductivity curves). The saturated hydraulic
171 conductivity, K_s , was determined using the constant head method (Klute and Dirksen, 1986) in the first
172 tilled layer (0–40 cm). The saturated water content, θ_s , was measured using the ISO 11274:1998, *i.e.*
173 sandbox method. The points of the soil water retention curves were measured in all layers using a
174 pressure plate apparatus (Dane and Hopmans, 2002) for applied pressures of 33, 625, and 1500 kPa.

175 Soil water samples were collected from all lysimeter tanks after each large precipitation and
176 irrigation event during the whole experiment, transported to the laboratory, and stored at 4 °C before
177 analysis. Nitrate concentrations were determined in these water samples using the continuous flow
178 auto-analyzer (San++ Continuous Flow Analyzer, Skalar).

179

180 **2.4. Modeling study**

181 **2.4.1. Coupled flow and solute transport equations**

182 Numerical modeling of water flow and fertilizer movements was performed in two-
183 dimensional domain using HYDRUS-2D software (Šimůnek et al., 2008). Water flow dynamics in a
184 variably saturated medium is solved using a numerical solution for Richards' equation, which is
185 defined as:

$$186 \quad \frac{\partial \theta}{\partial t} = \nabla(K \nabla H) - S_w \quad (1)$$

187 where θ is the volumetric water content [L³ L⁻³]; K is the unsaturated hydraulic conductivity [L³ T⁻¹];
188 H is the hydraulic head [L]; S_w is a sink term, accounting for plant uptake [L³ L⁻³ T⁻¹]; ∇ is the spatial
189 gradient operator; and t is time [T]. The plant water stress is accounted for using the model suggested
190 by Feddes et al. (1978), which is implemented in HYDRUS:

$$191 \quad S_w(h) = \alpha(h)S_p \quad (2)$$

192 where h is the soil water pressure head [L]; $\alpha(h)$ is the water stress response function, which varies
193 between 0 and 1; and S_p is the potential root water uptake rate (1/d).

194 The analytical van Genuchten Mualem model (van Genuchten, 1980) describing the
 195 unsaturated soil hydraulic functions (*i.e.* soil water retention curve and unsaturated hydraulic
 196 conductivity) was used in the modeling study, which is defined as follows:

$$197 \quad \theta(h) = \theta_r + \frac{\theta_s - \theta_r}{(1 + |\alpha h|^n)^m}, \text{ for } h < 0 \quad (3)$$

$$198 \quad \theta(h) = \theta_s, \text{ for } h \geq 0$$

$$199 \quad K(h) = K_s S_e^l (1 - (1 - S_e^{\frac{1}{m}})^m)^2 \quad (4)$$

$$200 \quad S_e = \frac{\theta - \theta_r}{\theta_s - \theta_r} \quad (5)$$

$$201 \quad m = 1 - \frac{1}{n}; \quad n > 1 \quad (6)$$

202 where $\theta(h)$ and $K(h)$ are volumetric water contents [$L^3 L^{-3}$] and unsaturated hydraulic conductivities [L
 203 T^{-1}] at the soil water pressure heads of h (L), respectively; θ_r and θ_s denote residual and saturated soil
 204 water contents [$L^3 L^{-3}$], respectively; S_e is the effective saturation; K_s is the saturated hydraulic
 205 conductivity [$L T^{-1}$]; α is the inverse of air-entry value or bubbling pressure [L^{-1}]; n is the pore size
 206 distribution index; and l is the pore connectivity parameter. The pore connectivity parameter equaled
 207 to an average value for many soils was used for all soil layers ($l=0.5$) (Mualem, 1976).

208 For solute transport, ammonium and nitrate were considered and their transformations and
 209 transport were simulated. The partial differential equations governing non-equilibrium chemical
 210 transport of solutes involved in a sequential first-order decay chain during transient water flow in a
 211 variably saturated rigid porous medium are simplified as follows:

212 a) For ammonium:

$$213 \quad \frac{\partial \theta c_1}{\partial t} + \rho \frac{\partial s_1}{\partial t} = \nabla (\theta D \nabla c_1) - \nabla (q c_1) - \mu_v \theta c_1 - \mu_n \theta c_1 - S_w c_1 \quad (7)$$

214 b) For nitrate:

$$215 \quad \frac{\partial \theta c_2}{\partial t} = \nabla (\theta D \nabla c_2) - \nabla (q c_2) + \mu_n \theta c_1 - S_w c_2 \quad (8)$$

216 where c_i is the liquid phase concentration of the chemical species i (subscripts 1 and 2 represent
 217 ammonium and nitrate, respectively) [$M L^{-3}$]; D is the dispersion coefficient tensor [$L^2 T^{-1}$]; q is the
 218 volumetric flux density [$L T^{-1}$]; ρ is the bulk density of the soil [$M L^{-3}$]; s_1 is the adsorbed
 219 concentration of ammonium [$M M^{-1}$]; μ_v is the first-order reaction rate constant [T^{-1}] representing

220 volatilization of ammonium to ammonia; and μ_n is the first-order reaction rate constant [T^{-1}]
221 representing nitrification of ammonium to nitrate. The relationship between ammonium in solution (c_1)
222 and adsorbed (s_1) is described as follows:

$$223 \quad s_1 = K_d c_1 \quad (9)$$

224 where K_d is the distribution coefficient for ammonium [$L^3 M^{-1}$].

225

226 **2.4.2. Model parameterization**

227 The model domain geometry was 200 x 200 cm with a 110 cm width and 10 cm high rise in
228 the middle of surface, which represents the soil bed (ridge) for growing bell pepper (Fig. 2). The
229 simulations were performed for two different management techniques, *i.e.* MULCH and CONT
230 systems, using different boundary conditions at the top. The MULCH corresponds to the subplots with
231 plastic mulch cover. The upper boundary conditions on the sides of these subplots were set as
232 atmospheric conditions, while the raised seed bed had no flow conditions (plastic mulch), except for
233 the small opening in the middle, corresponding to the bell pepper growing opening, which had
234 irrigation conditions and crop transpiration applied (Fig. 2a). In MULCH system the precipitation
235 amount was increased by a factor of 3.33 (Dusek et al., 2010) due to surface runoff from the plastic
236 mulch which ends up in open field (30 cm width) at both sides. Note that MULCH field data was an
237 average of two subplots, *i.e.* subplots covered with black and brown plastic mulch, since in the model
238 it was not possible to distinguish between those two. The CONT system corresponds to the control
239 subplots without plastic mulch cover, which had atmospheric conditions along the upper boundary,
240 except for the small opening in the middle that received the irrigation and transpiration conditions as
241 for the MULCH scenario (Fig. 2b). The lateral (both) and lysimeter boundary conditions were
242 determined as no flux and as seepage face, respectively. The bottom boundary condition was set as
243 variable groundwater fluctuations with the highest groundwater level reaching 180 cm below surface
244 (ensured by the pumping station at Vrana Lake).

245 Three additional scenarios were performed for each of the two management systems
246 corresponding to application of three doses of nitrogen. In these scenarios, liquid fertilizer was applied
247 every 7 days, starting from May 28th and finishing on September 11th (16 applications), which

248 accounted for total application of 70, 140 and 210 kg N ha⁻¹, depending on the plot. The scenarios for
249 CONT system were named as CONT₇₀, CONT₁₄₀ and CONT₂₁₀, with the numbers representing the N
250 doses applied with the irrigation. MULCH system names followed this same criterion, *i.e.* MULCH₇₀,
251 MULCH₁₄₀ and MULCH₂₁₀. Rooting depth was set as 35 cm with maximum root density in both
252 systems (considered to be the depth of main root mass).

253 Modeling study was performed from 1st of May till 31st of December, while the bell pepper
254 transplants were planted on 9th May with the first fertigation input on the 28th of May. The simulation
255 started earlier in order to approach a “pseudo-equilibrium conditions” before starting with the
256 irrigation and fertilizer addition (Hanson et al., 2006) which ensured that the initial soil water regime
257 was not a factor that influenced in the transport processes of applied nutrients (Gärdenäs et al., 2005).
258 The initial condition for water content was set as a hydrostatic pressure head distribution with 20 cm at
259 the bottom of soil profile (groundwater level at 180 cm below soil surface at the start of simulation).
260 The initial ammonium concentrations were neglected while nitrate concentrations were set for entire
261 domain based on soil measurements in first soil layer (0–40 cm). These values were transformed based
262 on the molar mass in order to fit model input units *i.e.* mmol cm⁻³ (Ravikumar et al., 2011; Filipović et
263 al., 2015). The initial nitrate concentrations ranged from 9.67 e⁻⁶ to 1.98 e⁻⁵ mmol cm⁻³ depending on
264 the plot. For solute modeling parameters, the longitudinal dispersivity along the direction of flow was
265 taken as 5 cm and the transverse dispersivity was taken as one order of magnitude less (Filipović et al.,
266 2013). The bulk densities for soil layers were set according to Table 1. The first-order reaction term
267 representing nitrification of ammonium to nitrate (μ_n), of 0.2 day⁻¹ and distribution coefficient for
268 ammonium (K_d) of 3.5 cm³ g⁻¹ were taken from Hanson et al., 2006. The first-order reaction term for
269 volatilization of ammonium to ammonia (μ_v) was 0.0552 day⁻¹ (Bolado-Rodriguez et al., 2005).
270 Application of fertilizer (7:5:9 NPK liquid fertilizer), which was defined also in kg ha⁻¹, was in the
271 same way transformed into concentration of nitrogen for both species (ammonium or nitrate) in the
272 volumes of applied irrigation (mmol cm⁻³). For the crop solute uptake (cRoot), a high value of 10
273 mmol cm⁻³ was selected aiming that all nitrogen species could be taken up passively without any
274 constraints (Hanson et al., 2006), since the quantity of crop uptake was not the aim of this study.

275

276 2.4.3. Soil hydraulic properties estimation

277 Additional soil hydraulic properties needed (*i.e.* θ_r and K_s for deeper layers, and α and n for all
278 layers) for solving van Genuchten-Mualem model were derived from the Rosetta model (Schaap et al.,
279 2001) implemented in HYDRUS. The initial estimates of hydraulic properties were based on soil
280 textural distribution, bulk density and water retention values at 33 and 1500 kPa. The hydraulic
281 properties were determined for the four soil layers: 0–40, 40–60, 60–92 and 92–120 cm. All
282 parameters of the 92–120 cm soil layer were considered to be valid till 200 cm depth in the modeling
283 approach, because of its low influence on lysimeter and rhizosphere. Values of selected hydraulic
284 parameters, *i.e.* α and K_s , of the four different soil layers were further fine-tuned using an inverse
285 modelling technique (Hopmans et al., 2002). The calibration of the saturated hydraulic conductivity K_s
286 and α parameter was done using selected values of experimental data from lysimeter outflow. Final
287 values of soil hydraulic parameters utilized in the model are shown in Table 2.

288

289 2.5. Statistical analysis

290 Statistical analysis of experimental field results (soil temperature, crop growth and yield) was
291 performed using the Statistical Analysis Software (SAS Institute, 2001). Analysis of variance was
292 applied using One-way ANOVA or MIXED procedure, depending on the analyzed data. The
293 significance of differences between the means was determined using a Tukey's Honestly Significant
294 Difference test at $P < 0.05$.

295 For the modeling results, in addition to graphical comparison of observed and simulated
296 values, the model performance was evaluated using coefficient of determination (r^2), and the model
297 efficiency coefficient (E) also known as Nash-Sutcliffe (1970) coefficient:

$$298 \quad r^2 = \left(\frac{\sum_{i=1}^n (O_i - \bar{O})(S_i - \bar{S})}{\sqrt{\sum_{i=1}^n (O_i - \bar{O})^2} \sqrt{\sum_{i=1}^n (S_i - \bar{S})^2}} \right) \quad (10)$$

$$299 \quad E = 1 - \frac{\sum_{i=1}^n (O_i - S_i)^2}{\sum_{i=1}^n (O_i - \bar{O})^2} \quad (11)$$

300 where O_i and S_i represents observed and simulated values, respectively; \bar{O} and \bar{S} represent average of
301 observed and simulated values, respectively; and n is the number of observed/simulated points.

302

303 **3. RESULTS AND DISCUSSION**

304 **3.1. Experimental results**

305 **3.1.1. Soil Temperature**

306 The statistical comparison was performed for a period of 129 days, from June 4th (starting
307 measurement of temperature probes) until October 10th (end of growing season). Bell pepper roots and
308 plant canopy were already well-established on June 4th. Soil temperature regimes in subplots covered
309 with plastic mulches were similar among the different color mulches, but were higher than in the
310 control subplots, which showed the lowest values (average of 21.4 °C) during the research period
311 (Table 3 and Fig. 3). Although the difference between the mulch covers were not significant (Table 3),
312 the subplots with the black plastic cover showed the largest values during the season (average of 23.3
313 °C). The average soil temperatures were in order black>brown>white>silver as expected (Fig. 3),
314 which is in agreement with studies performed under similar growing conditions (Romić et al., 2003a).
315 Other studies also report the temperature increase in soil with mulching, *e.g.* Ibarra-Jiménez et al.
316 (2011) in Mexico, and Ngouajio and Ernest (2005) in United States, which also showed the highest
317 soil temperatures when covered with black colored plastic mulches.

318

319 **3.1.2. Growth parameters**

320 Different fertilization rates were applied in the experiment to test the effects on yield and
321 vegetative growth of bell pepper. However, nitrogen fertigation did not have a significant effect on
322 bell pepper yield (Table 4). This could be partly attributed to the fact that some N was leached below
323 root zone due to the large irrigation events. Moreover, the main reason was the manure application on
324 the year before in the whole experimental site which could have provided sufficient amounts of slow
325 releasing nutrients needed for crop growth, minimizing the effect of the nitrogen addition.

326 On the other hand, plastic mulches significantly affected yield, but the statistical difference
327 was found only between the control plot (without mulch) and brown and black plastic mulch, which
328 both caused a significant increase of bell pepper yield. Still, there was no statistically significant
329 difference between brown and black plastic mulch, nor between the control plot and white and silver

330 plastic mulch. What is more, evaluating only the mulches (white, silver, brown, black) no statistically
331 significant difference was verified. However, noticeable differences were seen when evaluating the
332 growth parameters at the early stage *i.e.* on June 23rd when black and brown mulch covers provided
333 larger plant height, following larger number of fruits and flowers (Table 4). This clearly indicates
334 positive mulch effect on growth in the initial stage, which could lead to earlier harvest time. Similar
335 results were presented in the study performed by Romić et al. 2003b on watermelon (*Citrus lanatus*
336 L.). They indicated that mulching with polyethylene materials enabled an earlier harvest compared to
337 the control treatment and paper mulching, which was due to more rapid initial crop growth.

338

339 **3.2. Modeling study**

340 **3.2.1. Water flow**

341 Water flow simulations were performed using HYDRUS-2D for specified initial and boundary
342 conditions (described in 2.4.2 section). First, the model results were confronted with the observed data
343 of cumulative water outflows from lysimeters at the two different management types, *i.e.* CONT and
344 MULCH systems. The modeling of CONT system showed good agreement with the observed data
345 ($r^2=0.97$, $E=0.84$) and followed the outflow pattern during the researched period (Fig. 4). The large
346 outflows and their appearances during time were well captured by the model. Simulations of MULCH
347 system resulted in lesser fitting to the observed data but still in well agreement, presenting satisfactory
348 comparison coefficients, *i.e.* $r^2=0.97$ and $E=0.56$. The MULCH system simulations showed a more
349 uniform cumulative water outflow curve due to smaller interaction area between irrigation and rainfall
350 at the upper boundary considered in HYDRUS model, in which preferential flow was not considered
351 (Fig. 4). However, in the field some structure variations and macropore presence could be expected,
352 thus small discrepancies between the model and field derived data is expected. The measured data of
353 CONT system showed larger amount of cumulative water outflow compared to the MULCH system
354 *i.e.* 135.8 compared to 111.35 mm, respectively. This difference is the direct result of increased
355 surface area in CONT system for precipitation on the raised bed and around bell pepper crop, which
356 are located exactly above the lysimeter and therefore easily conduct the water to this point. This has
357 certainly affected water and nutrient distribution in the upper soil layers.

358 Fig. 5 show the simulated distribution of pressure heads in CONT and MULCH systems. On a
359 selected day (September 15th), there was a large precipitation event with 32.6 mm of rainfall and 21.7
360 mm of irrigation applied the day before (cumulative amount of 54.3 mm). Such large amount of water
361 caused a decrease in pressure head and an increase in water content range, which also resulted in large
362 differences between the two systems. The system with the plastic mulch showed drier conditions in the
363 whole area of raised bed due to the absence of rainfall along upper boundary. Plastic cover decreased
364 wetting area and reduced outflow in the MULCH system (47.8 compared to 51.0 mm for the CONT)
365 on this selected date. There is a noticeable effect of the increased runoff occurring in the MULCH
366 system, which raised the pressure head values below the open rows at the sides. Also, the lysimeter
367 plate influenced the pressure head distribution above them in both cases. The drip irrigation
368 distribution below drip line shows uniform wetting patterns in the absence of precipitation events
369 (Skaggs et al., 2004), on the contrary they can be deformed by the precipitation events. Water content
370 also showed (not shown) larger variation in the MULCH system due to uneven precipitation
371 distribution following the pressure head behavior. Since the irrigation amounts applied were the same
372 on both investigated systems (CONT and MULCH), both of them had enough water for optimal crop
373 growth. Consequently, the additional amount of water in CONT system influenced nitrate leaching
374 pattern and distribution towards deeper soil layers.

375

376 **3.2.2. Nitrogen dynamics**

377 After water flow was correctly described by the HYDRUS-2D model, we proceeded with
378 nitrogen modeling at the two applied management practices *i.e.* CONT and MULCH systems, with
379 three scenarios in each system *i.e.* 70, 140 and 210 kg N ha⁻¹ (six scenarios). The fertilizer inputs are
380 implemented in the model every seven days (weekly), in the form of ammonium and nitrate, together
381 with the irrigation application (mmol cm⁻³).

382 Nitrate concentrations in solution leached from the lysimeter reflect the behavior of water flow
383 and depended mostly on large precipitation/irrigation events. Fig. 6 shows the values of observed and
384 simulated cumulative nitrate concentrations in lysimeter outflow in the researched period for the
385 CONT system. A good agreement between observed and model derived results was verified for the

386 three CONT scenarios, shown by the model performance coefficients $r^2=0.95$ and $E=0.67$ for CONT₇₀,
387 $r^2=0.94$ and $E=0.81$ for CONT₁₄₀, and $r^2=0.93$ and $E=0.83$ for CONT₂₁₀. Similar values for model
388 performance coefficients were observed on the simulated results for the MULCH scenarios ($r^2=0.93$
389 and $E=0.70$ for MULCH₇₀, $r^2=0.94$ and $E=0.87$ for MULCH₁₄₀, and $r^2=0.95$ and $E=0.93$ for
390 MULCH₂₁₀ – Fig. 7). The high level of agreement between the simulated and measured water and
391 nitrate fluxes indicate a very good performance of HYDRUS model, as reported by several studies
392 with the similar modeling approach (Skaggs et al., 2004, Phogat et al., 2013). In both systems, the
393 highest nitrate concentrations in lysimeter outflow followed the input rate, and were in order 210 >
394 140 > 70 kg N ha⁻¹, as expected. Therefore, the leaching of nitrate was related to the fertilizer
395 application rate, with the larger nitrate input providing larger nitrate outflow.

396 After the simulations of nitrate leaching towards the lysimeter and satisfactory fitting, a new
397 set of simulations was conducted without the lysimeter in the modeling domain. The same initial
398 concentrations (zero ammonium and nitrate) in the soil profile were maintained, in order to eliminate
399 its direct effect on nitrate dynamics and to be able to compare two management systems in terms of
400 nitrate translocation.

401 The snapshot of ammonium concentration presented in the Fig. 8 showed its distribution in the
402 soil profile 105 days after the beginning of the simulation (on the day of the 12th application of
403 fertilizer, with 13.3 mm of irrigation). The contour of the solute pattern in both systems shows that
404 most of the ammonium concentration remained in the near vicinity of drip line emitter, which was
405 observed during the whole period of fertigation in all scenarios. Only a slight movement until
406 approximately 10 cm depth could be noticed, which is reduced because of its sorption to the soil solid
407 phase, its fast transformation to nitrate via nitrification process, and also due to root uptake (Hanson et
408 al., 2006). Since ammonium ions are positively charged, they adsorb well to the negatively charged
409 soil clay particles, and thus their leaching significantly reduces. Also, only matrix flow was considered
410 in our simulations *i.e.* single porosity model, and there was no consideration of rapid preferential flow
411 of ammonium, which may occur in the field during growing season.

412 In contrast to this ammonium transport pattern, continuous downward nitrate movement was
413 observed during the whole simulated period as a result of the high amount of water input

414 (irrigation/precipitation) and inability of soil to adsorb nitrate. On the Fig. 9 different snapshots in time
415 are presented for the 210 kg N ha⁻¹ application dose scenario in both CONT and MULCH systems
416 (note different scales for each time – this was done for better presentation of nitrate dynamics). Only
417 the scenario with the highest N input is shown, since the graphical presentation is the same for all
418 three fertilization levels and the only difference is that the concentrations are reduced with the
419 decrease on N dose application. The simulations show similar nitrate behavior in both systems, with
420 nitrate concentration being the highest around drip line during the whole crop growing period, in
421 which the fertigation were applied on a weekly basis. This can be seen up to the t=208, since the last
422 fertigation was applied on 168th day, after which redistribution phase began to take place. The contour
423 of nitrate in the soil profile was similar in both systems, although there is a tendency in CONT system
424 for more lateral and uneven distribution near the drip line, which was mainly due to the
425 evapotranspiration and rainfall. Such an unequal fertilizer distribution can affect crop growth, while
426 excess precipitation can foster nitrate leaching towards deeper soil layers. This can be noticed on the
427 two last print times (t=208 and t=245) when the large precipitation event leached the most of the
428 nitrate toward deeper layers. The CONT system showed larger accumulation of nitrate in the subsoil
429 (~80 cm), while the highest concentration of nitrate in the MULCH system was still located near the
430 drip line (~20 cm). This can also be seen from lysimeter outflow results, where we have measured a
431 cumulative nitrate leaching of 0.0031 mmol cm⁻³ from the subplots with no mulch covering (control),
432 compared to 0.0016 mmol cm⁻³ from the plastic mulch covered subplots.

433 In this study, we have applied equal amount of fertilizer in two systems. However, farmers can
434 easily add less fertilizer in the mulched management system, since the nutrients will be longer present
435 in the tilled soil layer and thus provide more available nutrients for crop uptake during the growing
436 season.

437 Mass balance was calculated for all simulated scenarios, and the cumulative N contents (kg ha⁻¹)
438 are presented in Table 5. Both CONT and MULCH systems showed increasing root uptake with
439 increasing N dosage, since we presumed an unlimited passive crop uptake. Leaching was considered
440 to be at lysimeter boundary (90 cm depth), while bottom flux of N was neglected because of the small

441 values of nitrate reaching bottom of the profile during our simulation period (the bottom leaching
442 would be certainly more pronounced if the simulations were extended in time).

443 Large differences were observed between CONT and MULCH system leaching, which are
444 related to the increased infiltration and flow velocity (Gärdenäs et al., 2005). Accumulated N in soil
445 profile (200 x 200 cm) presented in Table 5 is a sum of nitrogen from the applied fertilizer during the
446 research period. In the CONT system, large differences are evident when comparing different dosage
447 scenarios, while in MULCH system the differences were smaller due to the fact that most of the N was
448 still remained in the upper soil layers, because of its less leaching. Root uptake values and its
449 efficiency is reported to be around 50% when drip irrigation in combination with fertigation is applied
450 (Hanson et al., 2006 – grape, Phogat et al., 2013 – orange tree). Lower efficiency was found for bell
451 pepper due to shallow rooting since the bell pepper rooting depth is under 50 cm below soil surface,
452 and is not able to uptake nutrients from deeper layers. Thus, the fertigation should be optimized in the
453 way that: (i) more fertigation events (here we used weekly fertigation) with less fertilizer amount are
454 applied, which would increase fertilizer efficiency (Gärdenäs et al., 2005, Ravikumar et al., 2011); and
455 (ii) increase irrigation frequency, based on crop evapotranspiration values.

456

457 **4. CONCLUSIONS**

458 Different management practices used in a crop production can affect water distribution and
459 soil water content, which may consequently influence nutrient dynamics and crop growth and yield. In
460 this study, the effect of plastic mulching in combination with drip irrigation was evaluated on soil
461 temperature and bell pepper growth parameters and yield using experimental field data. The data
462 showed that plastic mulch had a significant effect on soil temperature regime and crop yield, with
463 small differences between the different coloring mulches. The dark color mulch (black, brown) caused
464 a higher soil temperature, which consequently enabled earlier crop development and higher yields. On
465 the other hand, different N dosage (70, 140, and 210 kg ha⁻¹) did not cause differences in the same
466 parameters. This is attributed to the fast transport of nutrients to the deeper soil layers (below root
467 zone) due to high input of precipitation/irrigation, and more importantly to the animal manure

468 application of the preceding year, which increased the initial nutrient content in the soil of the
469 experimental site.

470 In addition, a modeling approach was confronted to lysimeter study in terms of water and
471 nitrates dynamics. After optimization of soil hydraulic properties, simulations were carried using
472 HYDRUS-2D for two selected management options *i.e.* CONT system – without plastic mulch cover,
473 and MULCH system – plot covered with plastic mulch. The results of HYDRUS-2D modeling showed
474 good fitting in both cumulative water and nitrate outflows to the observed field site data, with a high
475 level of agreement. Water flow simulation produced model efficiency of 0.84 for CONT and 0.56 for
476 MULCH systems, while nitrate simulations showed model efficiency range from 0.67 to 0.83 and
477 from 0.70 to 0.93, respectively.

478 After successful model performance, the new set of simulations was initiated with all same
479 initial conditions but without the lysimeter plate. The simulations revealed faster transport of nitrates
480 below drip line in CONT system mostly because of the increased precipitation/irrigation at soil surface
481 as a result of the absence of soil cover. Contrary, in the MULCH system most of the nitrates were still
482 left in the upper soil layer at the end of simulation. Numerical modeling revealed a large influence of
483 plastic mulch cover on water and nutrient distribution in soil, and suggested that in such conditions
484 fertigation rates and frequency can be optimized in order to diminish the possibility of nitrate leaching
485 towards groundwater resources.

486

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Highlights

- Field data revealed positive effect of plastic mulch on crop yield and soil temperature.
- Water and nitrate distribution were affected by plastic MULCH cover.
- HYDRUS-2D simulations showed good agreement with the field data.
- Modeling revealed faster transport of nitrates below drip line in CONT system.
- Research suggests that MULCH systems can reduce nitrate leaching from fertigation.

Table 1. Basic soil physical and chemical parameters at the study site

Depth (cm)	Sand (%)	Silt (%)	Clay (%)	Bulk density (g cm ⁻³)	pH (H ₂ O)	OM (%)
0–40	12.4	57.5	30.1	1.36	7.20	13.08
40–60	19.0	54.8	25.2	1.27	7.05	nd*
60–92	18.5	53.3	28.2	1.22	7.11	nd
92–120	9.8	63.9	48.6	1.18	6.95	nd

* nd: not determined.

Table 2. Optimized soil hydraulic properties at the field site used in numerical simulations.

Layer (cm)	θ_r (cm ³ cm ⁻³)	θ_s (cm ³ cm ⁻³)	α (cm ⁻¹)	n (-)	K_s (cm day ⁻¹)
0–40	0.08	0.45	0.0073	1.54	42.82
40–60	0.07	0.48	0.0063	1.59	38.86
60–92	0.05	0.45	0.0050	1.51	29.35
92–200	0.08	0.45	0.0064	1.57	12.85

Table 3. Average soil temperature in uncovered (control) and plastic mulch covered (white, silver, brown, and black) treatments during bell pepper cultivation (June 4th till October 10th).

Soil covering	Soil temperature (°C)
Control – no covering	21.4 b *
White plastic mulch	22.5 a
Silver plastic mulch	22.8 a
Brown plastic mulch	23.2 a
Black plastic mulch	23.3 a

* Means with the same letter are not significantly different at P<0.05.

Table 4. Effect of nitrogen fertigation, plastic mulch and their interaction on the bell pepper yield (total) and growth parameters measured on 23.06.

Treatment	Yield (t ha ⁻¹)	Plant height (cm)	Number of fruits	Number of flowers
N fertigation				
N ₇₀	69.6 a *	32.9 a	2.5 a	8.8 a
N ₁₄₀	74.4 a	32.6 a	2.3 a	9.2 a
N ₂₁₀	71.7 a	34.1 a	2.7 a	9.5 a
Plastic mulch				
Control	63.9 b	31.2 b	1.9 b	8.3 b
White	68.9 ba	30.6 b	1.8 b	7.7 b
Silver	69.3 ba	31.6 b	2.2 b	8.1 b
Brown	78.5 a	36.6 a	3.4 a	11.1 a
Black	78.9 a	36.0 a	3.2 a	10.7 a

* Means with the same letter are not significantly different at P<0.05.

Table 5. Nitrogen mass balance (originating from ammonium/nitrate fertilizer) for CONT and MULCH subplots at the end of simulation period.

	CONT ₂₁₀	CONT ₁₄₀	CONT ₇₀	MULCH ₂₁₀	MULCH ₁₄₀	MULCH ₇₀
	kg N ha ⁻¹					
Root Uptake	78	59	31	76	56	29
Leaching	73	50	22	28	24	12
Accumulated in soil profile	59	31	17	106	60	29

Figure 1. Daily rates of precipitation, irrigation, evaporation, and transpiration during and after the bell pepper growing season on Vrana field site.

Figure 2. Boundary conditions and domain description of the selected field experiment used in HYDRUS-2D simulations: a) MULCH system (plastic mulch cover), with upper boundary conditions only, and b) CONT system (control, without mulch cover) boundary conditions; the lysimeter, lateral and bottom boundary conditions were identical in both scenarios.

Figure 3. Average daily (left axis) and cumulative (right axis) soil temperature (5 cm depth) during research period at different mulching types: black, brown, silver, white, and control plot (without plastic mulch).

Figure 4. Observed and simulated cumulative water outflow (mm) from lysimeter during experimental period in the CONT and MULCH systems cultivated with bell pepper.

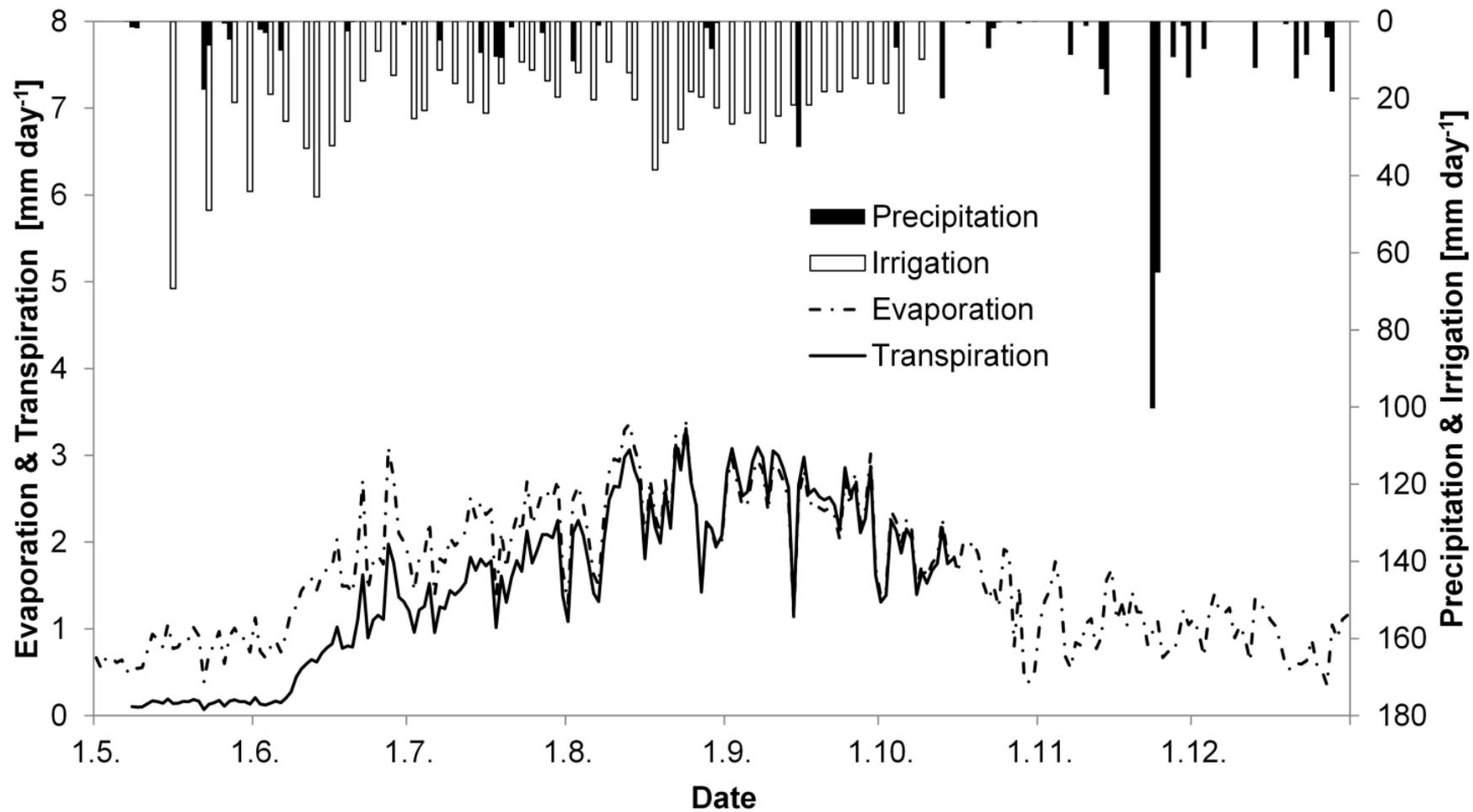
Figure 5. Pressure head (cm) distribution on September 15th (138 days after the beginning of experiment) on CONT (left) and MULCH (right) systems.

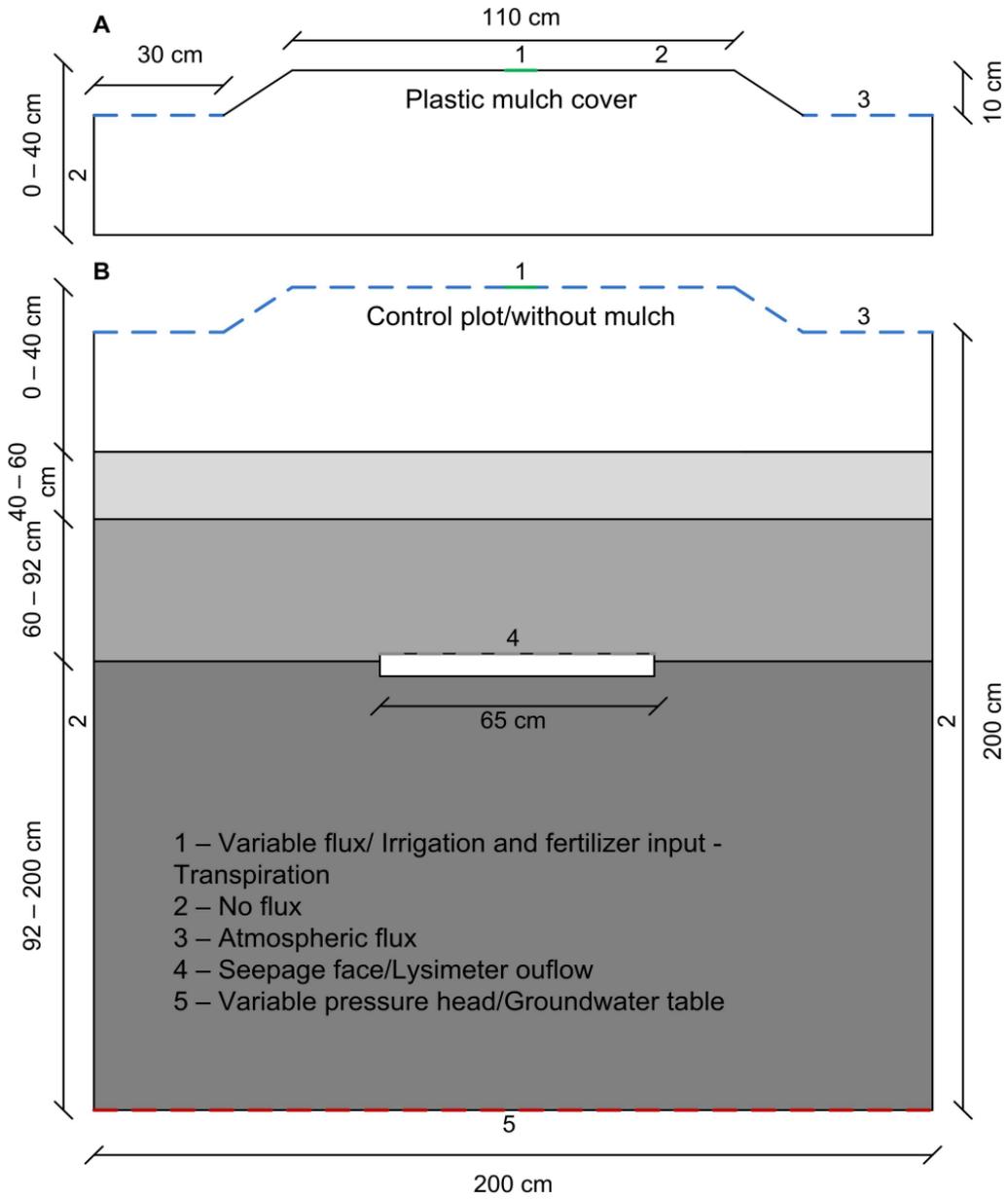
Figure 6. Observed and simulated cumulative nitrate outflows in lysimeters from CONT system (without mulch cover) with different rates of nitrogen input *i.e.* 210, 140 and 70 kg ha⁻¹.

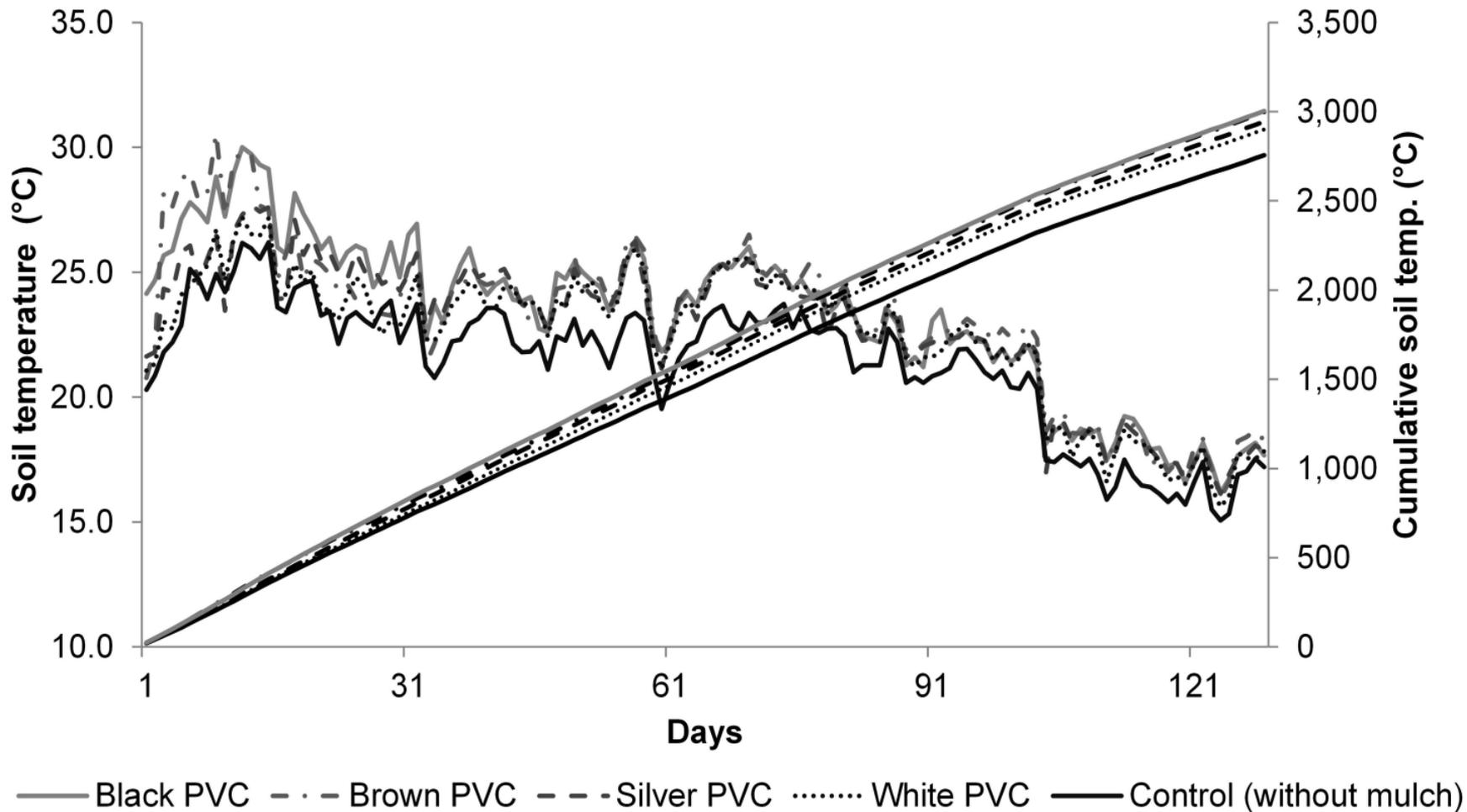
Figure 7. Observed and simulated cumulative nitrate outflows in lysimeters from MULCH system (the data represent average from black and brown plastic covers) with different rates of nitrogen input *i.e.* 210, 140 and 70 kg ha⁻¹.

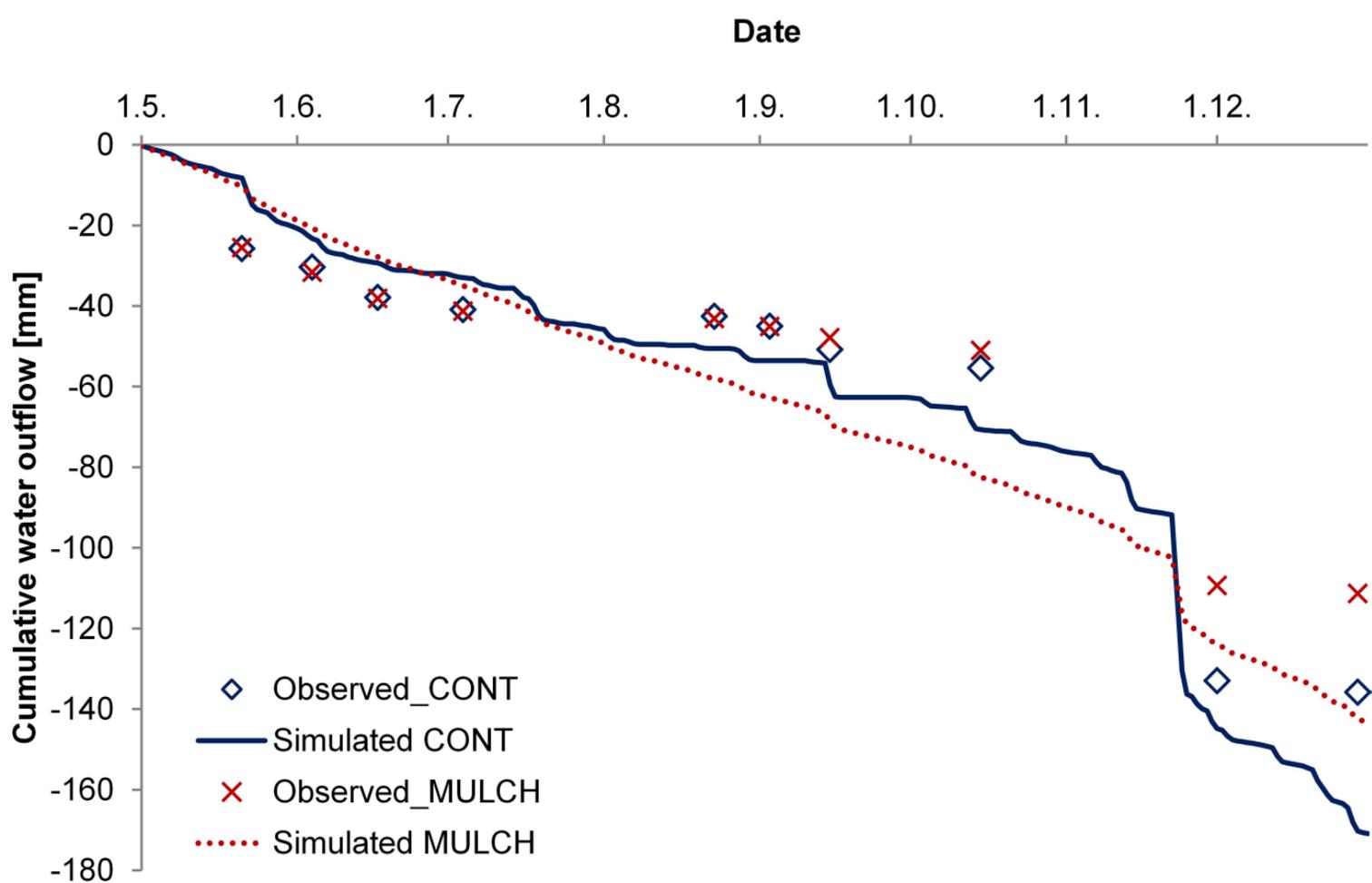
Figure 8. Spatial distribution of ammonium in the soil profile (200 x 200 cm) and around dripper 105 days after the beginning of the simulation for CONT and MULCH system.

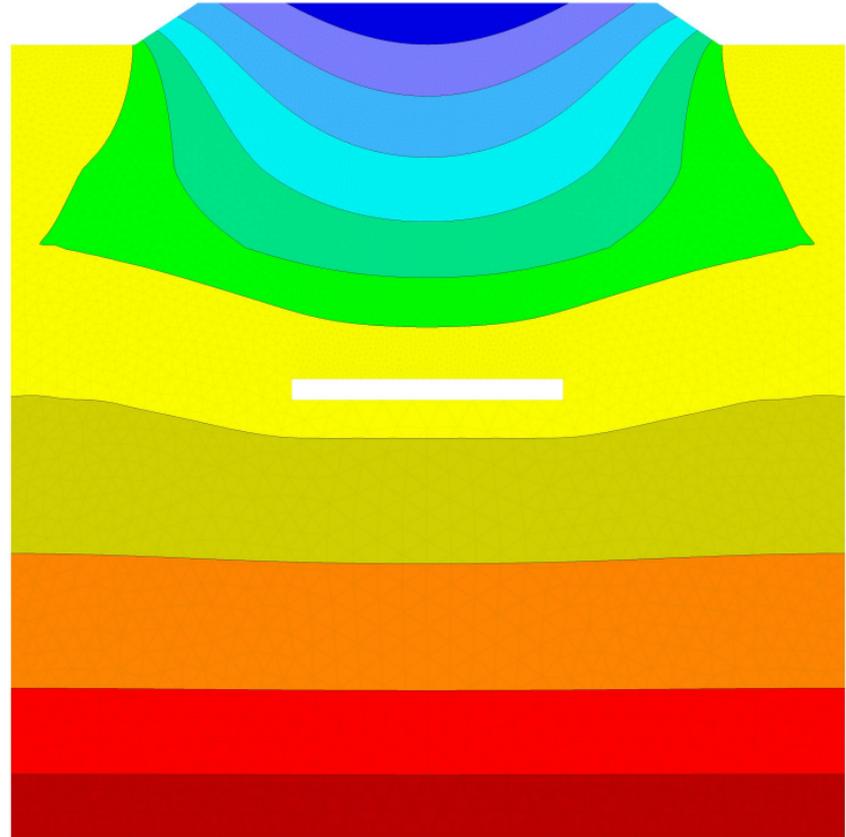
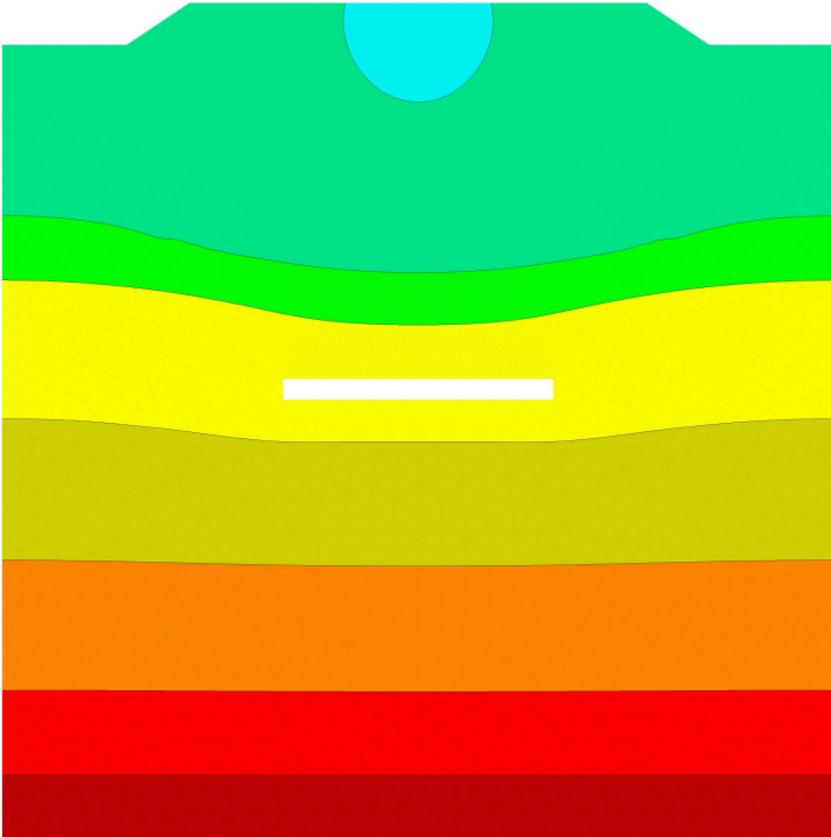
Figure 9. Spatial distribution of nitrate in the soil profile (200 x 200 cm) during different time steps *i.e.* 42, 77, 105, 138, 208, 245 days after the beginning of the simulation for CONT and MULCH system.



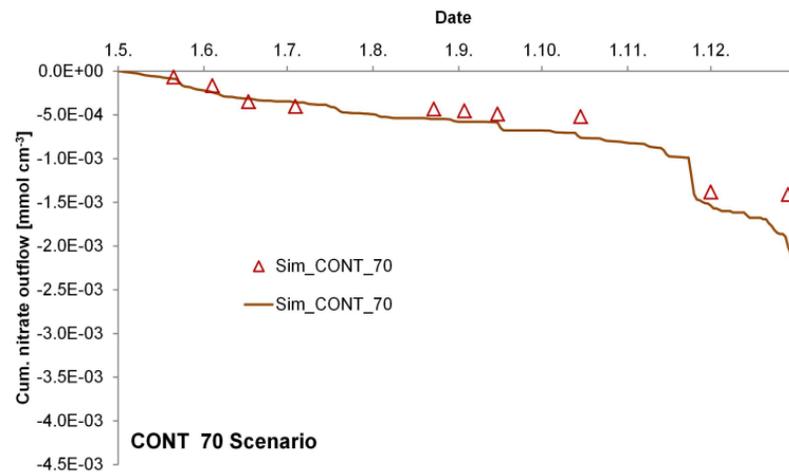
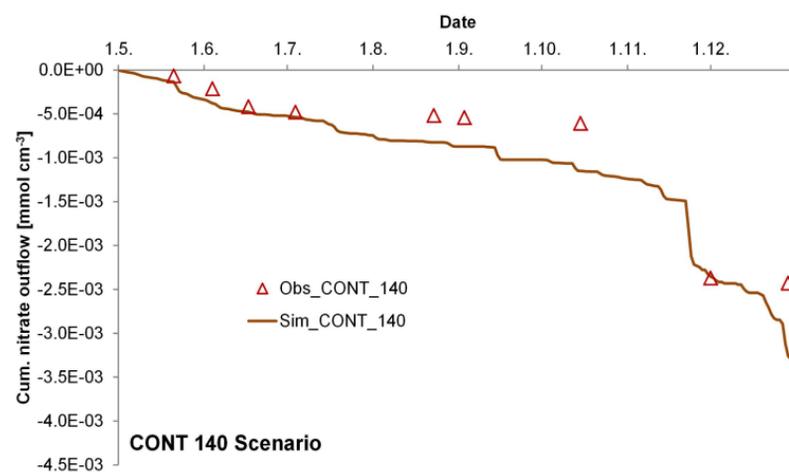
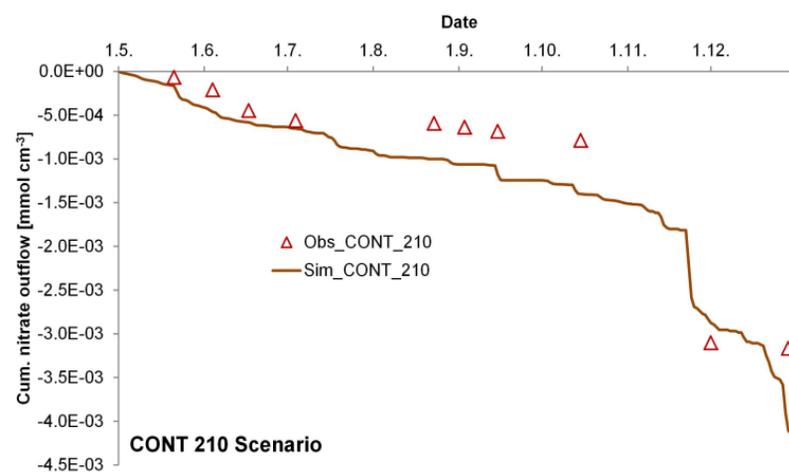


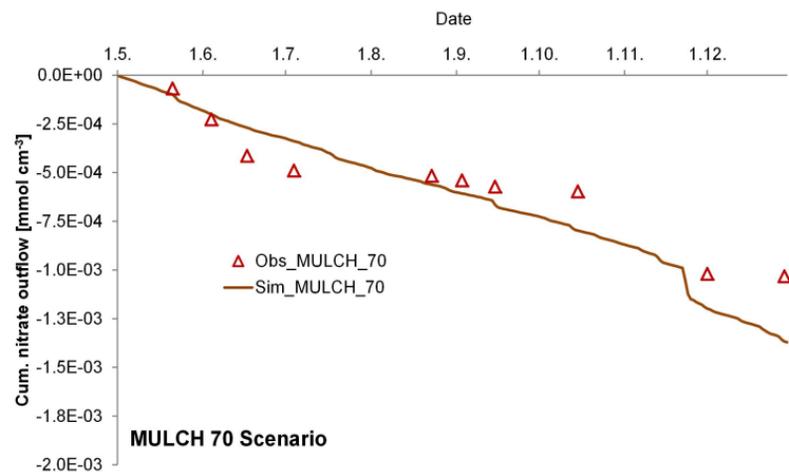
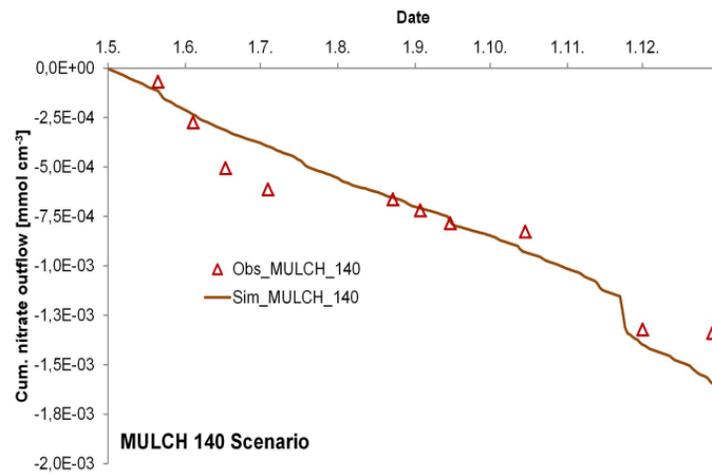
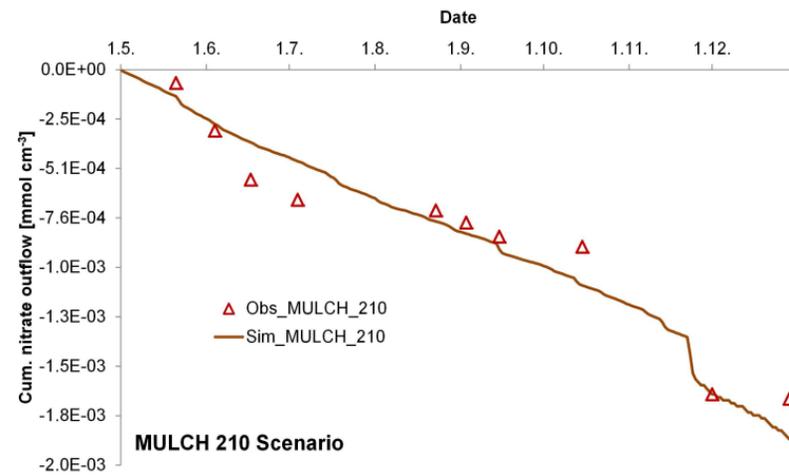




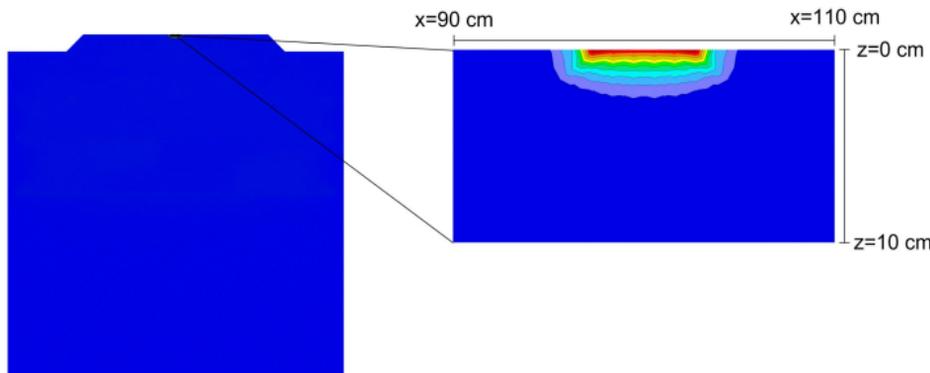


Pressure Head - h[cm]



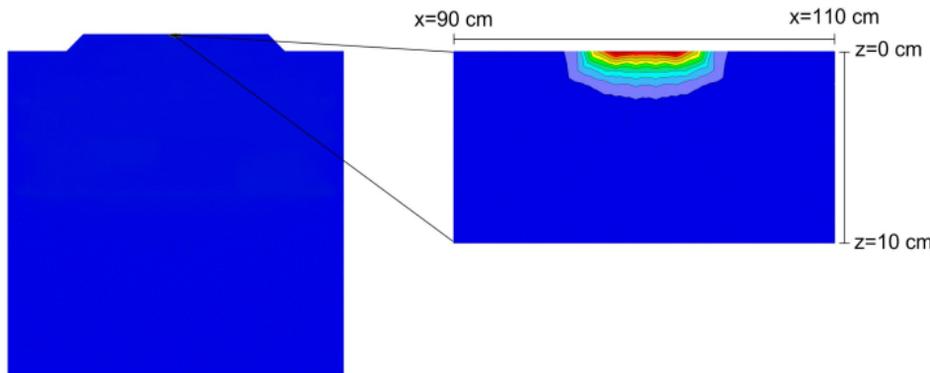


CONT



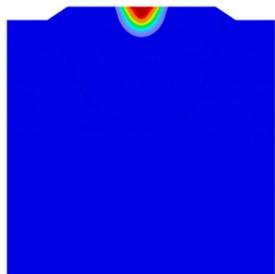
T=105

MULCH

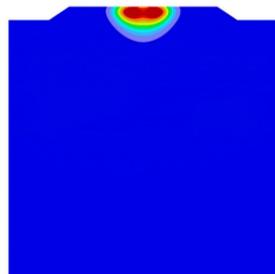


Ammonium concentration range [mmol cm⁻³]

CONT



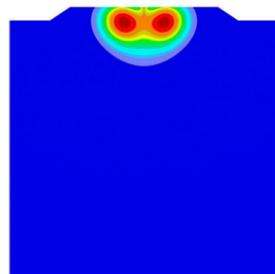
T=42



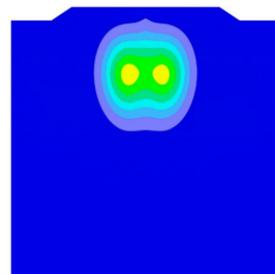
T=77



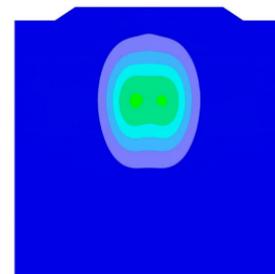
T=105



T=138

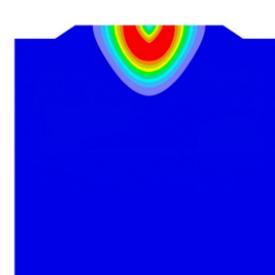
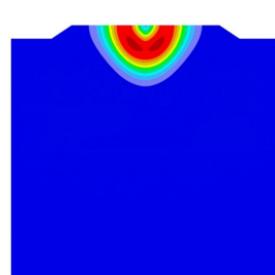
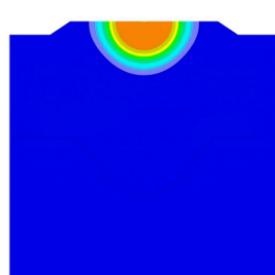
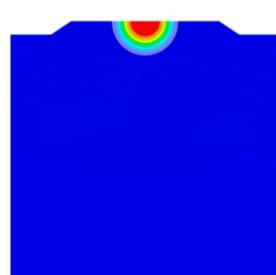
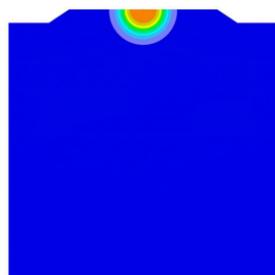
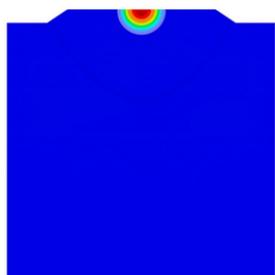


T=208



T=245

MULCH



Nitrate concentration range [mmol cm⁻³]

