

Technical Report WD/91/69

**RADIAL COLLECTOR WELLS IN ALLUVIUM PROJECT:
Final Report (#3) on Trenchless Molding Trials
at Carmer Wood, Laughton, Lincolnshire.**

B L Morris, J C Talbot and D M J Macdonald

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for the Overseas
Development Administration

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BRITISH GEOLOGICAL SURVEY

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EXECUTIVE SUMMARY

This report documents the results of the field trials carried out by BGS on behalf of ODA to develop an intermediate technology method of constructing collector wells in unconsolidated sandy alluvium. A system has been developed which uses a thrust-boring mole of the type now in common use in the construction industry to install sub-surface service mains without excavation. The system has been developed with the aim of utilising the groundwater resources which are present in thin shallow uncemented sandy aquifers but whose exploitation by borehole or shaft-only dugwell would be marginal due to small available drawdowns and moderate to low permeabilities. Mesh-wrapped plastic screen is emplaced inside jacked-out temporary steel casing which is then retracted under a small positive hydraulic head in order to avoid sand-locking and formation ingress into the main shaft. 38 mm ID pipe has been used, and rapid autodevelopment by the radials has provided collectors with yields of 1.5 l/s/radial from fine running sands. Arrays have been emplaced to over 20 m length with a 98 mm ϕ head at jacking forces of less than 7 tonnes f. The equipment required for the construction of the collectors is light to transport and install and significantly less expensive than a downhole rotary drilling rig to buy and operate. The method is however restricted to unconsolidated fine-grained alluvium, as the method is essentially one of formation displacement, not removal.

Contents

	<u>Page</u>
EXECUTIVE SUMMARY	
1. INTRODUCTION	1
2. BACKGROUND TO PRESENT PHASE OF WORK	1-4
2.1 Suitability of Collectors in Thin Shallow Alluvial Aquifers	1
2.2 Site Details	1
2.3 Evolution of Different Thrust-boring Approaches	2
2.4 Chronology of Screen-within-casing Trials	3
2.5 Timetable of Fieldwork	3
3. MAIN FEATURES AND PERFORMANCE COMMENTS OF S-W-C SYSTEM	4-8
3.1 Pilot Push-head	4
3.2 Disposable End-cap	5
3.3 Plastic Permanent Casing and Screen	5
3.4 Push Rods	6
3.5 Steel Temporary Casing	6
3.6 Access Plates and Wall Mountings	7
3.7 Screen Emplacement Accessories	8
3.8 Shuttering	8
4. RESULTS	9-12
4.1 Thrust-boring with Pilot Push-head	9
4.2 Thrust-boring with 73 mm ϕ Casing	10
4.2.1 73 mm ϕ Head and 73 mm ϕ Casing	10
4.2.2 98 mm ϕ Head and 73 mm ϕ Casing	11
4.3 Productivity Rates of Radial Construction	12
4.4 Summary of Thrust-boring Results	12
4.5 Timetabling Collector Construction by S-W-C Method	12
5. CONCLUSIONS	13-14
6. RECOMMENDATIONS	15-16
REFERENCES	
ACKNOWLEDGEMENTS	
APPENDICES	

1. INTRODUCTION

This report describes the work carried out by BGS during 1990 and early 1991 to develop a thrust-boring method of horizontal screen emplacement in collector wells. The trials form part of a programme to provide a practical and economical method, suitable for Third World application, of constructing radial collector wells in shallow unconsolidated sandy alluvial aquifers. This research project is undertaken on behalf of the Overseas Development Administration as part of the UK aid programme.

2. BACKGROUND TO PRESENT PHASE OF WORK

2.1 Suitability of Collectors in Thin Shallow Alluvial Aquifers

Although the borehole can be a most efficient method of groundwater extraction in unconsolidated alluvial aquifers, there are special, but not uncommon, circumstances where a collector well would be more suitable for groundwater extraction than either a normal dug well or a borehole. This is where the aquifer is shallow, thin and of low to moderate permeability. In this environment daily yields are controlled on the one hand by available drawdowns (frequently only 2 or 3 metres) and on the other by the rate of recovery after pumping. The large effective radius of shaft plus radials in a collector well can make it a hydraulically efficient method of maximising daily yields. In comparison with a shaft-only dugwell or a borehole, the presence of radial collectors tends both to minimise the drawdown in the main shaft and to maximise the subsequent recovery rate (Herbert, 1990).

A small drawdown would be especially important, for instance, where salinisation due to up-coning could occur, as in coastal littoral sand aquifers. Similarly, the rate of recovery after daily pumping could decide the viability of a small-farm irrigation scheme, where cumulative residual drawdown needs to be minimised over a crop watering season. Given a practical and rapid method of radial construction using inexpensive simple equipment, shallow alluvial collector wells could be economically constructed in this hydrogeological environment.

While a method had been developed early in the project of installing radials by telescoped jetting, using a specially-constructed rotary drilling rig (Allen, 1988), it was felt that a simpler, lighter and cheaper method could be devised which would be suitable for fine-grained aquifer environments, whose lower permeabilities would result in yields that were worthwhile but insufficient to merit the capital-intensive rotary drilling method.

2.2 Site Details

All field research and development for this part of the project was conducted in the UK at a site whose groundwater conditions are representative of such an environment.

Carmer Wood, where the site is located, is an area of Forestry Commission woodland situated near Laughton, north Lincolnshire. It is located on the eastern edge of the alluvial sequence which makes up the Quaternary floodplain deposits of the lower Trent valley (Figure 1). At the site a clay aquiclude underlies a shallow localised watertable aquifer. This completely unconsolidated fine to medium sand is up to 6.5 m thick, about 4.5-5.5 m of which is saturated at any one time depending on season (Morris and Talbot, 1990). During short periods of pumping (2 days or less) the aquifer behaves like a semi-unconfined two layer system, the lower layer of which is a zone of moderate permeability with an average transmissivity of c. 20 m²/d (Morris, 1991).

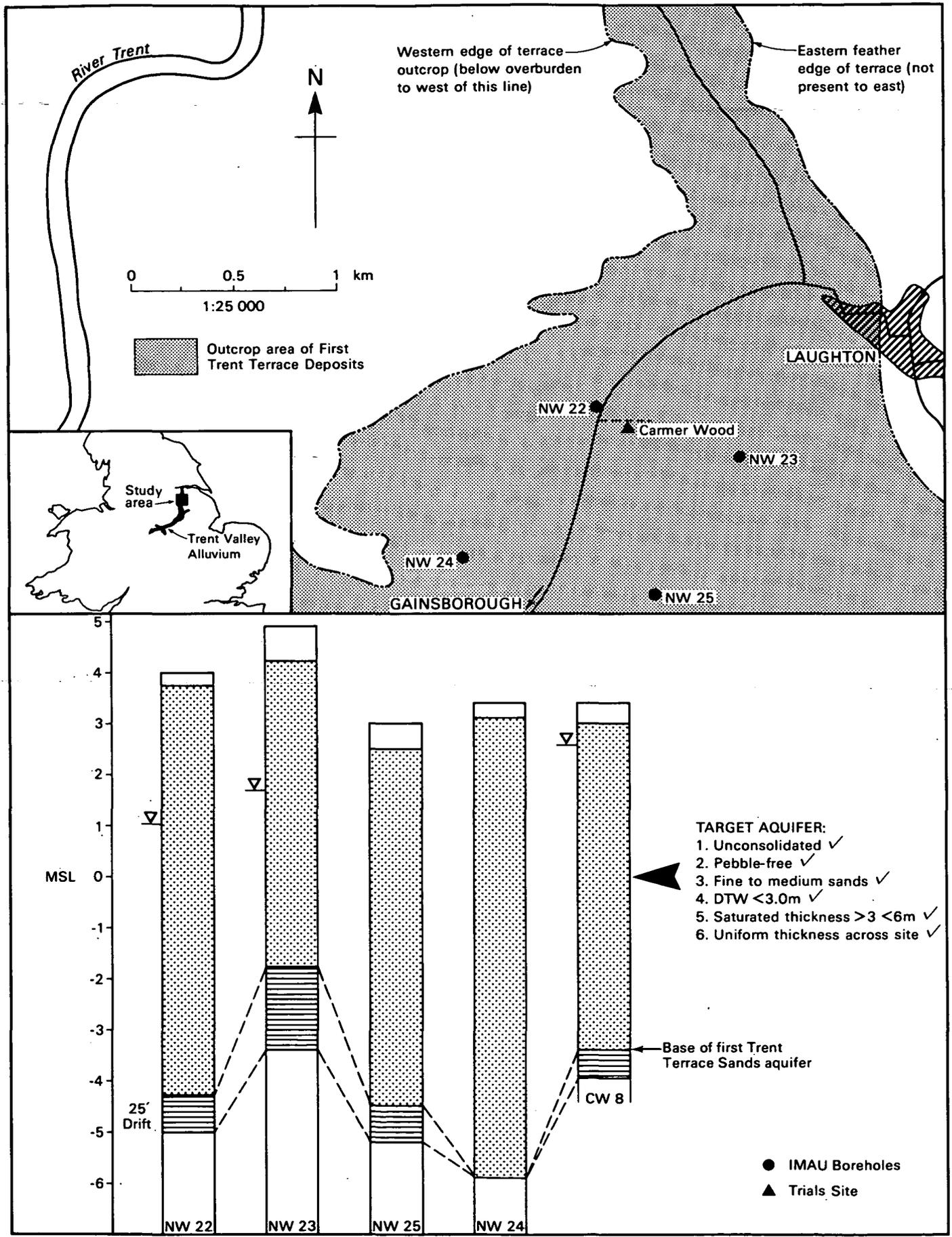


Figure 1. Carmer Wood location map & borehole sections showing continuity of First Terrace Sands aquifer

2.3 Evolution of Different Thrust-boring Approaches

A thrust-boring field trial conducted in February 1990 using a 70 mm diameter pilot push-head and standard 45 mm diameter push rods had showed that pipe-jacking from a dewatered large diameter well out into the saturated zone several metres below the water table was both practicable and rapid (Morris and Talbot, 1990). Jacking advance and withdrawal rates of over 1 m/min to 20 m radial length were attained with low to moderate formation resistances which were observed to lie well within the capacity of both thrust-borer and reinforced concrete well-lining.*

The simplest and most economical field arrangement for installing permanent collector screen/filter pipe with thrust-boring equipment involves coupling plastic pre-slotted casing to a disposable push head, telescoping the push rods inside, progressively jacking the whole array out to the required length, then retrieving the rods from within the emplaced screen. This rod-within-screen system was tried (Morris and Talbot 1990), and although the array was successfully jacked out to 8.5 m from the main shaft, insurmountable problems of sand-locking between rods and filter pipe were encountered. Excessive deterioration of the plastic screen was observed, and it was suspected that this had in part occurred during driving of the array. In addition, an excessive quantity of sand was admitted to the main shaft, requiring laborious removal and causing problems with the dewatering pump.

Field experience gained during this phase pointed to the need to not only protect the screen during emplacement but also to devise an arrangement whereby formation pressure could be prevented from introducing sand-laden water into the filter/borer array during advance and withdrawal of the radial.

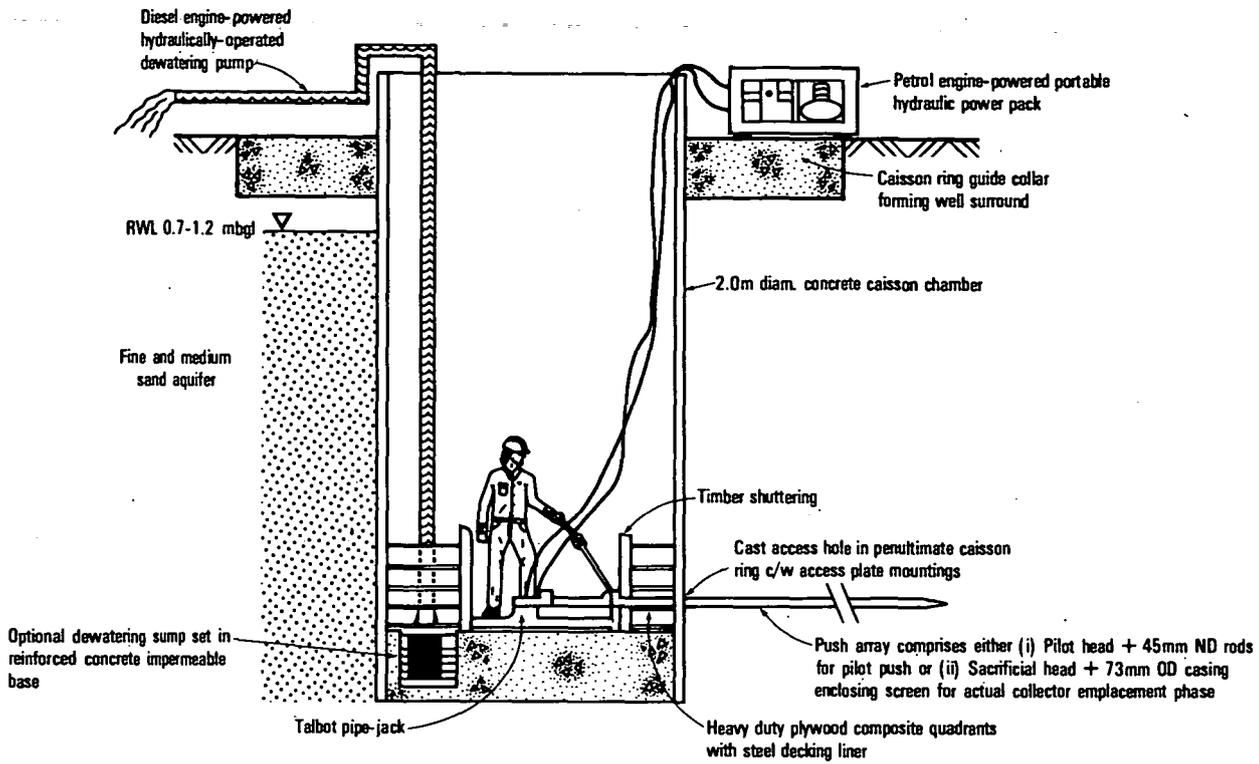
As a result, an alternative field arrangement was proposed in which the position of the screen and the thrust-boring tools was effectively inverted. After completing a pilot push, the push rods would be replaced by steel temporary water well casings, the disposable end-cap being loose-coupled and connected to mesh-wrapped plastic screen telescoped inside the casing. This screen-within-casing system, illustrated in Figure 2A, would have two main advantages:

- (a) It would permit the screen to be emplaced in a protected fashion in dry conditions. Also sand ingress problems during the first half of the operation would be effectively avoided.
- (b) The problem of sand-locking as the casing was withdrawn around the screen would be prevented by overcoming the difference in head between the (dewatered) main shaft and the (saturated) collector emplacement zone which caused inflow and mobilised the sand. By effectively isolating the screen/casing annulus from the main shaft it would be possible to reverse the hydraulic gradient so that water flowed outward into the aquifer, not inward into the shaft. This was achieved by connecting the screen outlet at the main shaft via a hose to a water tank situated at the surface. The tank would act as a simple pressure device maintaining a small positive head over that in the aquifer outside the shaft (Figure 2B).

The arrangement described above offered the prospect of rapid installation and the continued use of plastic casing, both important constructional factors affecting the economics of the system.

* The performance of the push-head and push rod combination used for the pilot boring exercise is referred to in more detail in section 4, where various arrays are considered).

A During pilot push and screen emplacement phases



B During temporary casing withdrawal phase

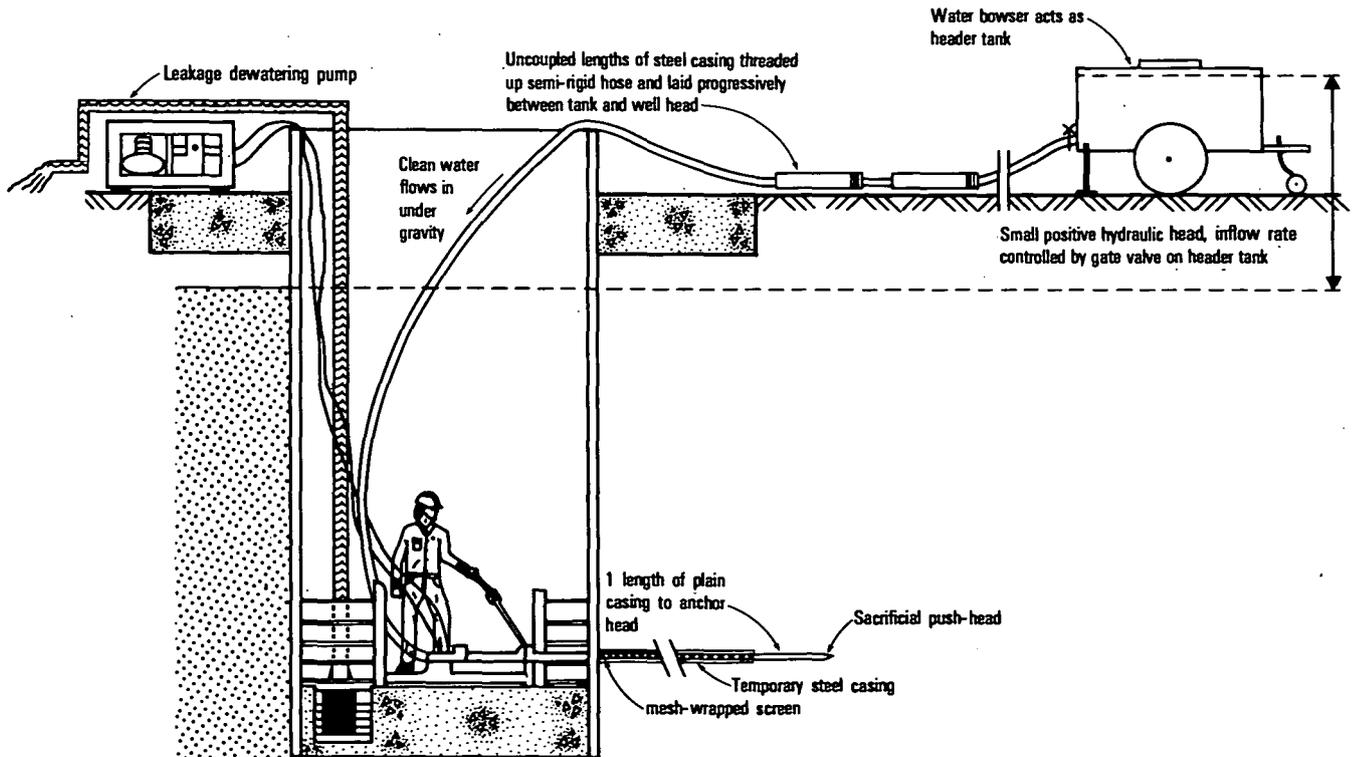


Figure 2A/B. Working layout in main shaft

The trials described in this report were all designed to test the viability, and subsequently to improve the practicability, of the screen-within-casing thrust-boring system.

2.4 Chronology of Screen-within-casing Trials

Although lightweight portable thrust-boring moles are now in routine use in the UK for the installation of service pipes and cable ducting below highways and railway lines, their use below the water table is novel, and the project needed to devise a number of new techniques to render the method practicable. For this reason the field trials of the method were conducted on an empirical basis.

Early work concentrated on devising a functional constant head system which would keep at bay the running sand which had proved so troublesome during both emplacement and withdrawal phases of the rod-within-screen trials. In the event, most effort was required at the well shaft end, devising a practical method which would enable the casings to be withdrawn over the screen without losing the positive head within the array through flow back along the screen/casing annulus into the well.

Later work sought to perfect a reliable system of casing emplacement to the 20 m+ which had been shown during the preliminary work to be so easily attainable with rods and the pilot push head. This proved to be a much less tractable problem but in the event gave rise to some of the most interesting results of the whole project.

2.5 Timetable of Fieldwork

- | | |
|-----------------|--|
| 19/2/90-23/2/90 | Pilot moling of L6: dummy push head + 45 mm ϕ rods. |
| 26/2/90-1/3/90 | Attempted rod-in-screen insertion in L6; insuperable dewatering problems. |
| 7/30/90-8/3/90 | Dewatering problem finally solved (after trying several different pump types and arrays), using Flygt hydraulic submersible pump. |
| 22/3/90-23/3/90 | Selected access hole plate mountings installed. |
| 26/3/90-28/3/90 | Rod-in-screen method attempted again on L6; very severe sand locking problems during several attempts indicated method not viable. |
| 8/5/90-17/5/90 | Pilot head diameter increased to 73 mm ϕ ; screen-in-casing and constant head system tried on L6 with just 10 casings; withdrawal successful but unwieldy and protracted; screen mobile due to fluidised bed conditions. Full advance attempted on L5 but excessive push resistance halted progress due to slippage of casing in jaw grip. Short L5 radial installed. |
| 25/6/90-27/6/90 | Remaining lower access hole mountings installed by improved method. |
| 23/7/90-25/7/90 | Screen-in-casing attempted in L3 after pilot rod push; standard casing observed to deform permanently at moderate push forces; need for thickwall casing indicated. |
| 10/9/90-14/9/90 | Pumping test on CW2 for formation characteristics. |

- 14/1/91-17/1/91 Screen-in-casing using heavy duty pipe tried on L1 after pilot rod push; excessive push resistance encountered; short L1 radial installed; head redesign indicated.
- 4/2/91-7/2/91 Heavy duty casing + redesigned oversize head tried successfully on U3; process repeated on U4 and U2 using various pilot push combinations. 118 m of moling completed in 3 days, 78 m of which using 73 mm diameter casing.
- 21/2/91-22/2/91 Well CW8 capped; site cleared.

3. MAIN FEATURES AND PERFORMANCE COMMENTS OF SCREEN-WITHIN-CASING SYSTEM

The early trials of the screen-within-casing system showed that there was scope for considerable improvement in methodology. The objectives were to simplify both the procedures and the accessories required. The rate of installation would therefore be speeded up and, combined with the relatively low capital cost of the equipment, this would result in a reduced unit cost per radial when compared with conventional rotary drilling methods.

The designs of the pilot push head and the disposable end-cap evolved together during the field trials and are shown diagrammatically in Figure 3.

3.1 Pilot Push-head

Description.

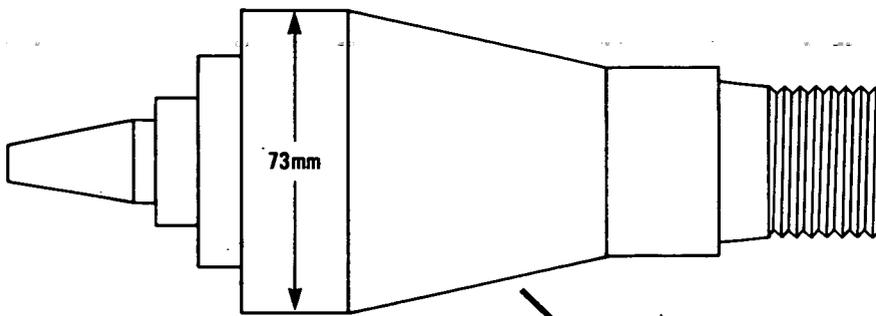
These were fabricated from mild steel and comprised a stepped conical head of the same dimensions as the disposable end-cap, a shank and a 6 tpi 1½" UNC male thread to fit standard 45 mm ND push-rods. For the early work, through the 75 mm access holes in the concrete chamber ring, a 73 mm head was used (modified slightly from the rod-within screen trials), while a 98 mm head was employed for the later work in the 100 mm access holes. No significant wear on thread or end-faces was detected on any of the heads other than a mild 'sandbasting' effect, even though both sizes were used repeatedly on different pushes.

Comments.

Throughout the trials, a separate pilot push-head and disposable end-cap were employed, mainly because each required distinct thread types and dimensions (Photo Figures 4A, 4B). However, there is merit in combining the functions of pilot push and screen emplacement in a single head by converting the pushfit part of the disposable head into a thread adaptor, Figure 5 shows the recommended final head design, incorporating improvements arising from the project's experiences. Its use would simplify the procedure in the well as the head, once it has driven out the mortar plug into the formation, would never be completely retracted back into the main shaft. The changeover from one head to another is a delicate operation, and results in a short period during which the access hole has to be unblocked, providing an opportunity for sand ingress while the pipe-jack jaws are changed to accommodate the larger radius of curvature of the steel temporary casing. A combined head would practically eliminate the problem and minimise sand ingress during the transfer from rod to casing, as the head could be chocked in the access hole as a temporary plug while the pipe-jack jaws are changed over.

Also, the head could be usefully fabricated in aluminium to reduce weight and minimise the tendency towards downward deflection by gravity which is a risk in any horizontal drilling operation in unconsolidated formations; the materials cost of mild steel or aluminium combined head would be about £14 and £23 respectively (UK 4/91 prices). A two-part dual function push-head would involve overall no more machining than separate heads, although the cost per radial would be slightly higher as both parts would in effect be disposable.

Scale approx 1:2



DESCRIPTION: 73mm diam. head, 45mm ND rod coupling

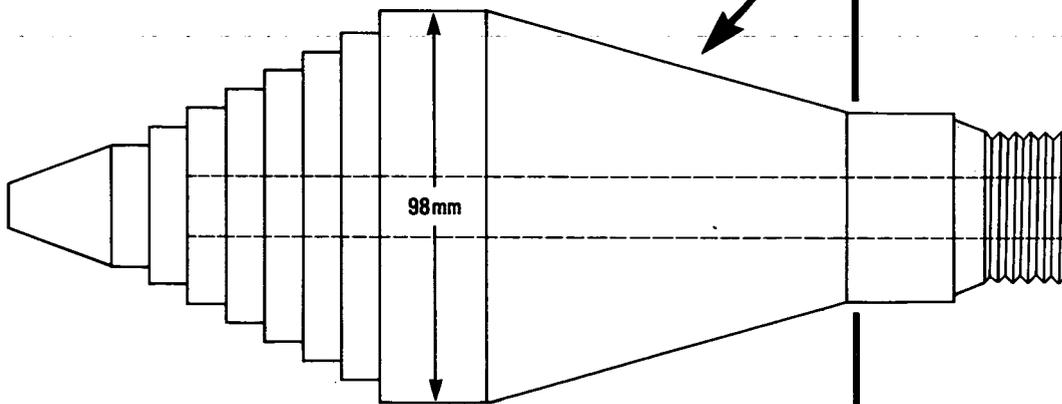
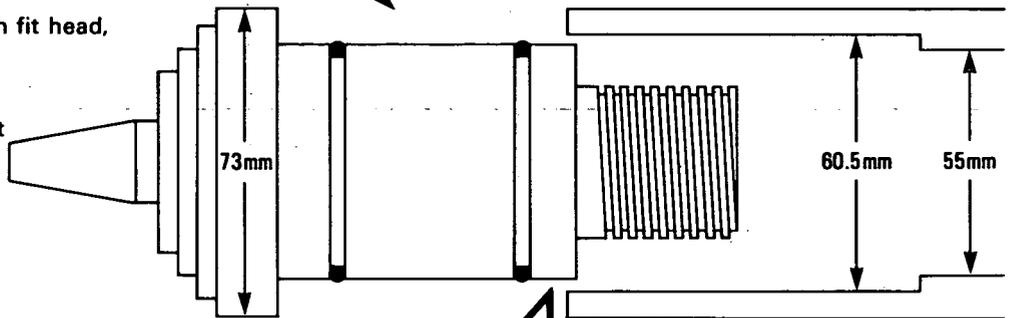
FUNCTION: Pilot push

PERFORMANCE: Successful, low formation resistance during both advance and retraction

DESCRIPTION: 73mm diam. flush fit head, push fit retention in BW casing, 38mm ND screen coupling

FUNCTION: Screen emplacement

PERFORMANCE: Unsuccessful, excessive formation resistance on advance



DESCRIPTION: 98mm diam. oversize head, 45mm ND rod coupling

FUNCTION: Pilot push

PERFORMANCE: Successful; disproportionately small increase in resistance over 73mm head

DESCRIPTION: 98mm diam. oversize head, HD BW casing coupling

FUNCTION: Simulated screen emplacement (exterior geometry would be identical)

PERFORMANCE: Significant improvement over flush fit version, formation resistance reduced even further if preceded by pilot push

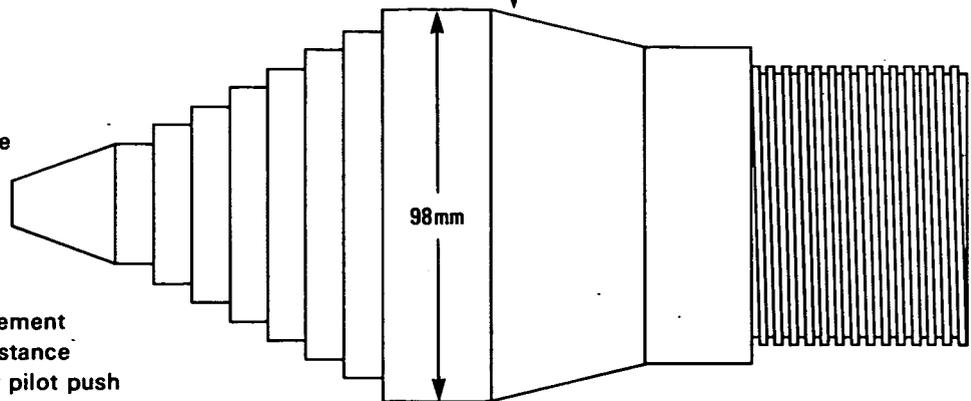


Figure 3 Developmental sequence of push-head design

Figure 4A

Pilot push-head with 45 mm ND push rods.

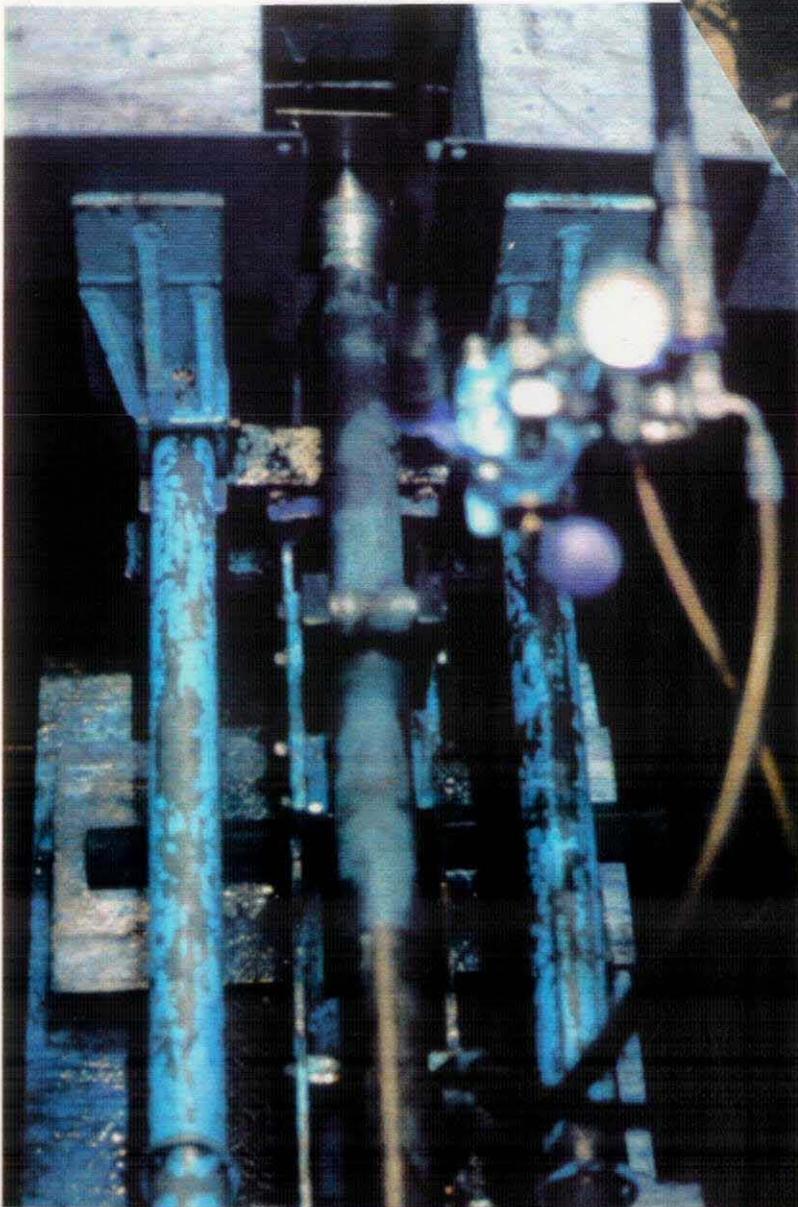
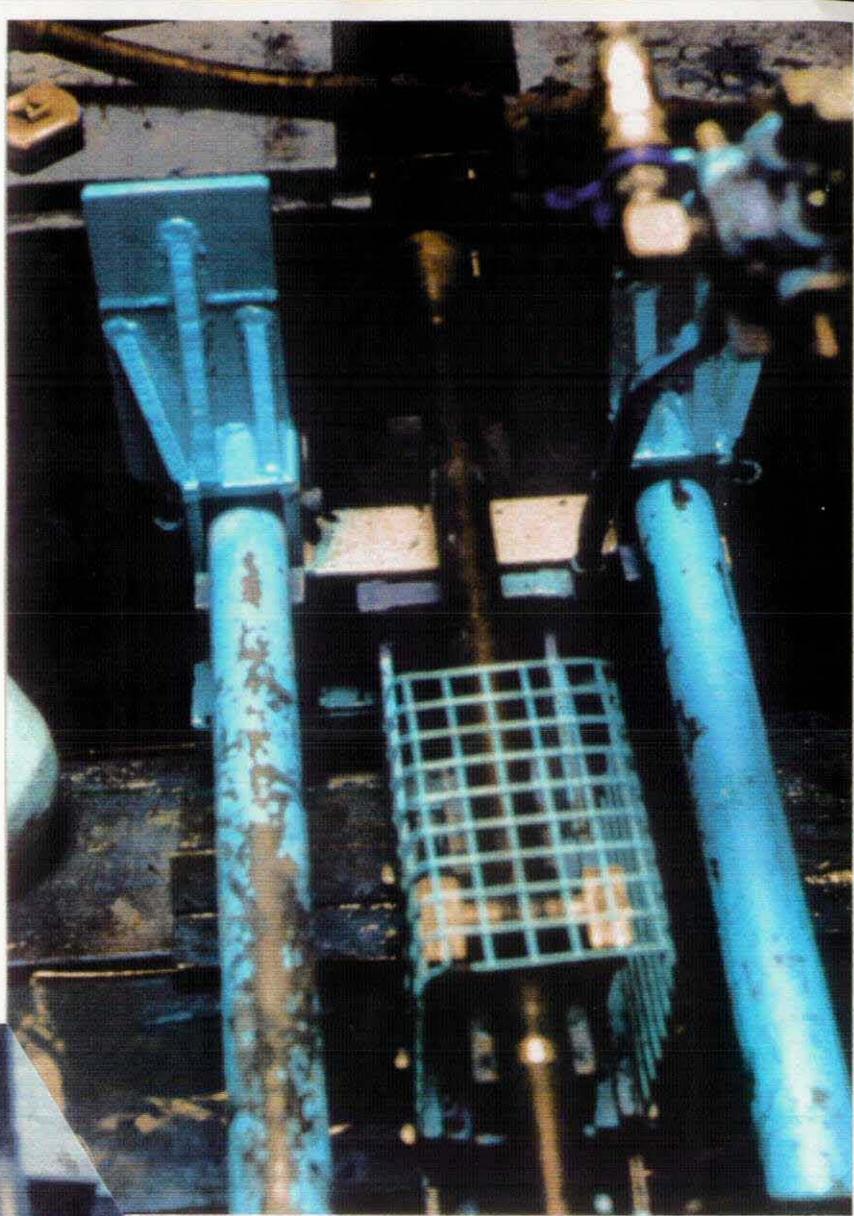
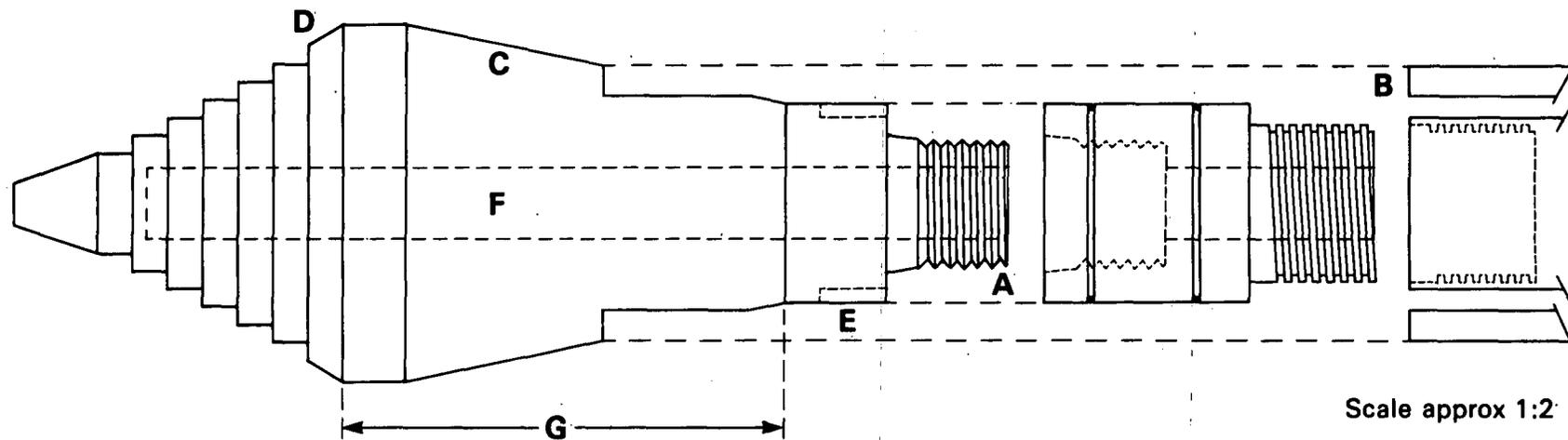


Figure 4B

Screen emplacement end-cap with 73 mm OD steel casing.



FEATURES

- A** Pilot push and screen emplacement functions united in single head to minimise sand ingress to well; after pilot push with 45mm ND rods, combined thread adaptor and positive head push fit device is coupled for emplacement phase
- B** Thick walled 73mm OD casing pipe, First length butts against shoulder of push head
- C** Head OD-to-shank ratio maximised to ≈ 1.8 to take advantage of pressure relief effect and minimise formation resistance on both advance and withdrawal
- D** Bevel on outer most step to act as guide during mortar plug displacement, to minimise risk of driving out plastic access hole liner in front of push-head
- E** Shank widened and tool flats added to help grip head during final rod uncoupling and change over to adaptor
- F** 20mm diameter hole bored out of centre and complete head fabricated in aluminium to reduce weight by $>50\%$ and to minimise tendency to downward deflection by gravity
- G** Dimension G to coincide with actual thickness of concrete well wall so that push-head functions as temporary plug during change over from pilot push to screen emplacement phase

Figure 5 Final push-head design, incorporating improvements suggested during field trials

3.2 Disposable End-cap

Description.

These were fabricated from mild steel and comprised three main elements (Photo Figure 6):

- (i) A leading edge whose general geometry approximated to a stepped cone. The stepped design is widely employed on muling tools, where ambient conditions may involve operation in pebbly soils or in made ground containing rubble or backfill. Industry experience has shown that deflection in non-uniform granular materials by larger fragments is less with a stepped cone than with a smoothed conical shape. 73 mm and 98 mm diameter heads were used in 75 mm and 100 mm access holes respectively. The larger diameter heads were developed towards the end of the project when little field time and funding remained, and so for operational reasons they were made up threaded to fit the casing. This was in order to concentrate on the problem of formation resistance (Photo Figure 7).
- (ii) A loose-fitting shank was made sand- and water-tight with a double O-ring channel. The diameter of the preliminary version was kept constant at 60 mm to fit standard BW casing throughout the modification stages in order to reduce project machining costs, but the shank would normally be turned 0.5 mm undersize to fit the heavy-duty casing bore of 55 mm.
- (iii) A 6 tpi square thread was required to fit the commercially available 38 mm ϕ plastic casing which was used throughout the screen-in-casing trials.

Comments.

If the pilot head and end-cap were combined, parts (ii) and (iii) of the push-head would be made up with a 6 tpi 1½" UNC female thread in the form of an adaptor, to be coupled to the forward part of the head prior to the screen emplacement phase and after the pilot push. The snug fit in the shaft access hole engendered by a leading edge only 2 mm undersize permitted the head to serve as a temporary plug during rod to casing changeover, but one operational problem resulted, in that in one instance the plastic mould which is set in the access hole during chamber ring construction was driven out in front of the push-head, causing excess formation resistance during the advance and increased sand leakage into the shaft. The risk of this occurring would be much reduced by bevelling the outermost step of the push-head (feature D of Figure 5).

3.3 Plastic Permanent Casing and Screen

Description.

47.8 mm OD x 38.2 mm ID plastic pipe was used as both plain casing and perforated basepipe for the mesh-wrapped screen. The MGS Geoscreen comprised 0.75 m lengths of basepipe slotted at 750 μ m and sleeved with 150 μ m double mesh Georap geotextile plastic mesh. The arrangement during insertion and withdrawal phases is shown schematically in Figures 8A and 8B.

Comments.

Coupling the first length of screen directly behind the disposable push-head was found to cause problems during temporary casing withdrawal, as the screen array would not stay in place while the casing was retracted around it. The reason was that outflow through the screen into the aquifer from the positive head system was so effective that it created fluidised bed conditions at the

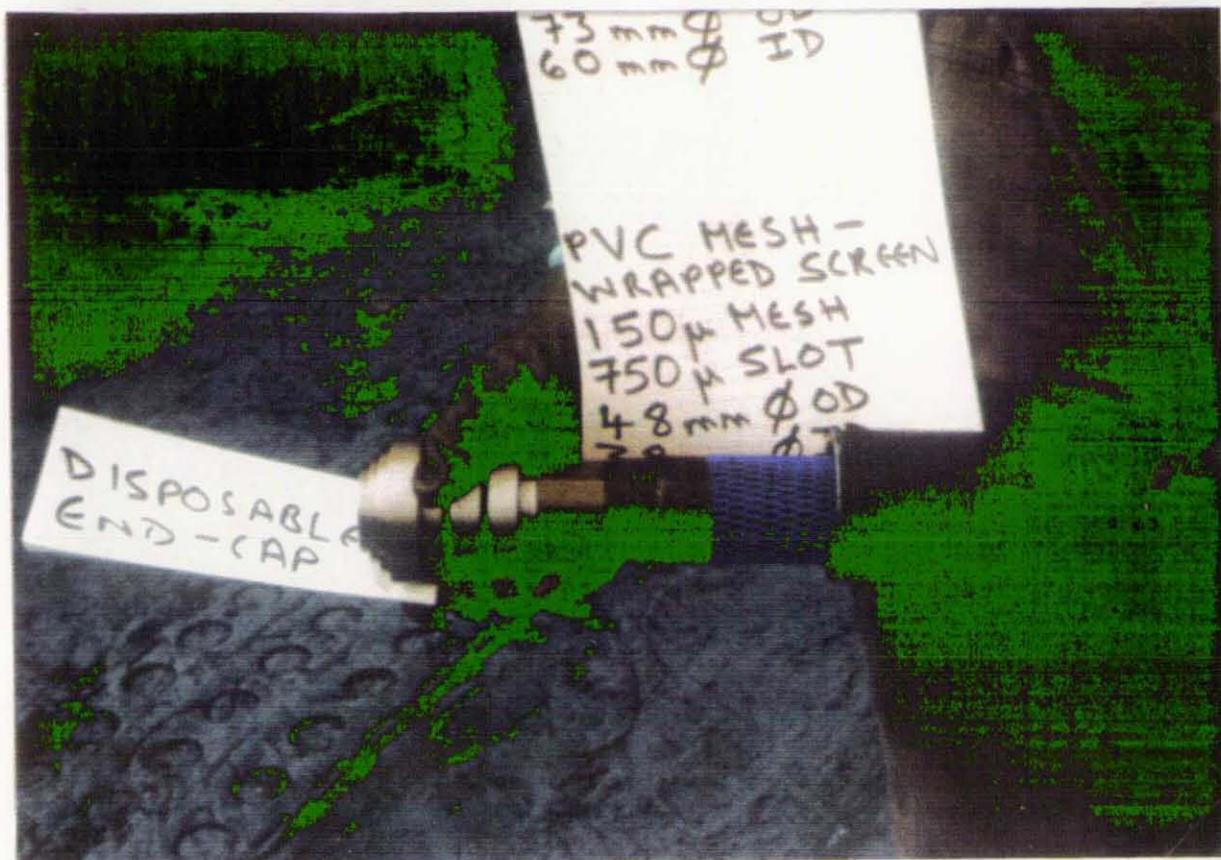


Figure 6. Disposable end-cap is a sliding fit inside leading temporary casing, made sand- and watertight with O-ring seals.

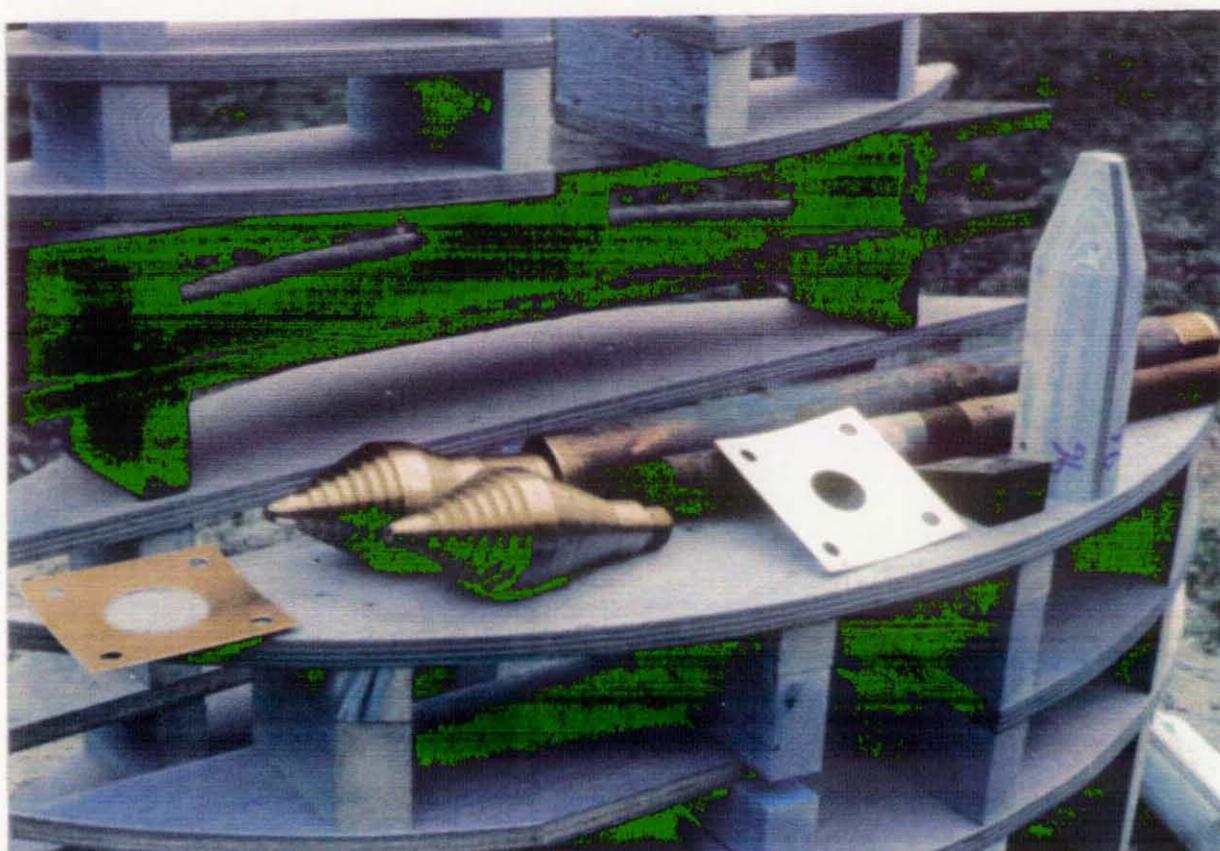
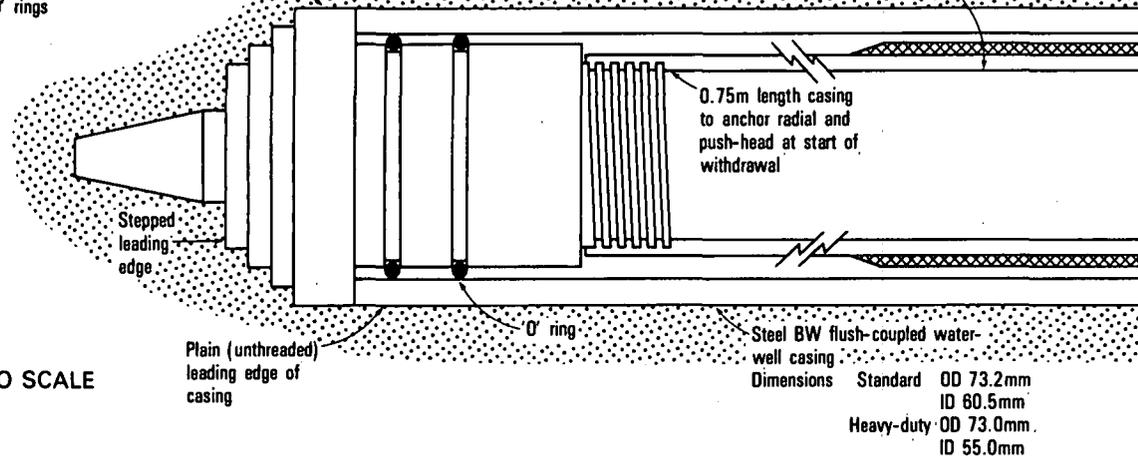


Figure 7. 98 mm Ø pilot and simulated screen emplacement push-heads, access plates, quadrant sections and plug; used to test efficiency of oversize head design.

A). During Insertion

Sacrificial push-head, sliding fit inside BW casing; impermeable seal provided by 'O' rings

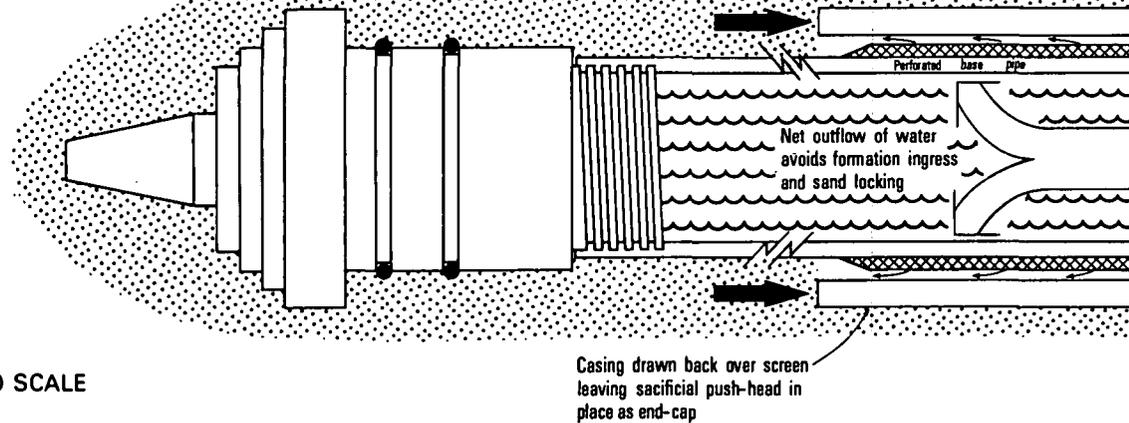
Plastic mesh-wrapped well-screen
Screen OD 48mm
Screen ID 38mm
Approx. screen and mesh OD 54mm



NOT TO SCALE

B). During Withdrawal

SATURATED AQUIFER FORMATION



NOT TO SCALE

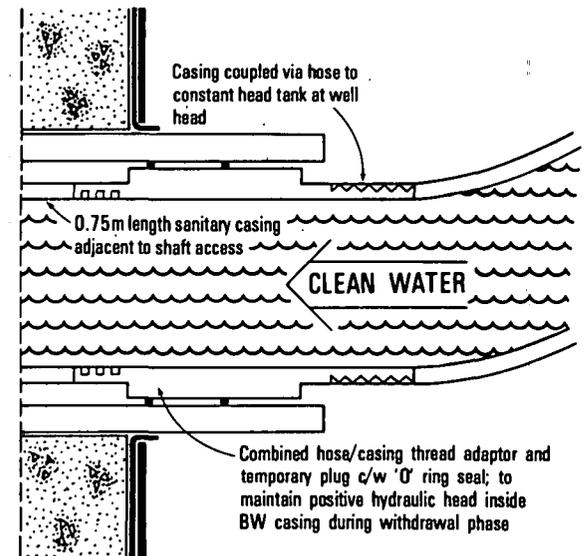
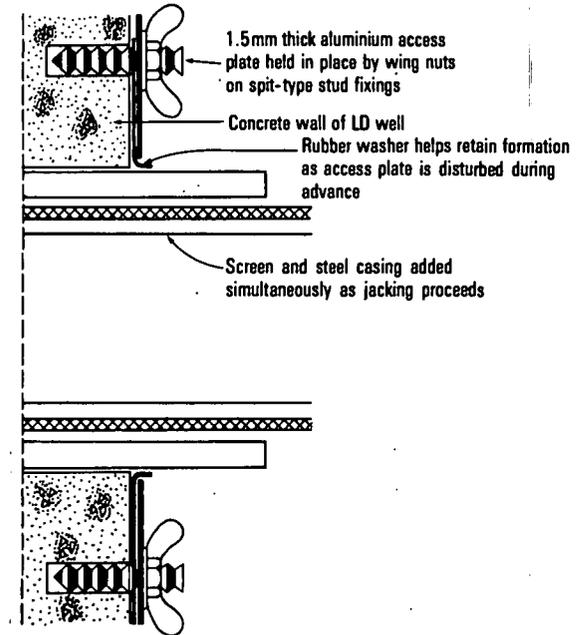


Figure 8A/B: Schematic arrangement of array to emplace 38mm ID mesh-wrapped plastic screen collectors

screen/aquifer interface, preventing the formation from collapsing back against the filter to hold it in place. As the outflow along the screen cannot be easily controlled, this problem was overcome by coupling a 0.75 m length of plain casing as the first length behind the push-head; the absence of outward flow along this section enabled the formation to collapse back against it, so it could act as an anchor (Photo Figure 9A).

The system of screen emplacement by simultaneous addition of permanent inner screen and temporary outer casings functioned well from the outset (Photo Figure 9B), and was in marked contrast to the rod-within-screen method, where the procedure was unwieldy because of interference by the screen with the rod jaws.

The geotextile sleeve was found to be a very effective method of screening radials emplaced in fine sands. Sieve analysis of the aquifer horizons around the collectors at the site showed that the formation comprised uniform fine sands with D_{50} of 215-270 μm and uniformity coefficients of 1.8-2.1. Even so, it was observed that the collectors could be left to autodevelop after installation was completed just by removing the end-cap and allowing the radial to flow; no other method of development was required. The transition to low turbidity discharge, free of suspended solids, was completed in less than 30 minutes in each case (Photo Figure 10). The sleeving is however delicate, and care is required during handling and emplacement to avoid tearing the outer mesh or stripping off the taped sleeve ends.

3.4 Push Rods

Description.

These comprised 45 mm x 18.7 mm cold-rolled steel pipe in 0.725 m lengths. The couplings use a 6 tpi 1½" UNC parallel thread with a 0.015" dirt tolerance together with a 10 x 9 mm tapered shoulder to produce a rigid fit.

Comments.

This thread design performed much better than the square section BS 4019 threads employed for the casing, the rods being easy to couple and uncouple, rigid, very robust and tolerant of sand.

3.5 Steel Temporary Casing

Description.

For the early work, standard BW casing to DCDMA specification was used. This pipe was selected for reasons of economy and international availability. BW flush-coupled casing has the thickest walls available in production grade water well casing (6 mm). However, the casing was found to distort unacceptably. Severe slippage of the pipe in the thrust borer's rod jaw occurred at about 5 tonnes push force. This was thought originally to be due to poor contact with the jaw roller and supporting vee blocks, which were designed for push rods with a much smaller radius of curvature. However the problem persisted even after modification of the jaw assembly, and diametric measurements of the casing in-situ at high formation resistances eventually showed the problem to be due to elastic deformation. By using disposable aluminium slips, higher push forces were obtained with the casing but dimpling occurred between 5 and 7.25 tonnes force (Photo Figure 11). At this point the pipe deformed permanently into an elliptical cross section. As a result, it became very difficult to uncouple casings and the danger arose that the distorted sections might grip the screen sleeving and peel it back off the slotted basepipe during the temporary casing retraction phase.

A greater wall thickness was called for, within the practical constraints on the pipe dimensions occasioned by the OD of the mesh-wrapped screen (54 mm)

Figure 9A

Disposable end-cap, plastic anchor casing and first length of screen telescoped inside leading temporary casing.

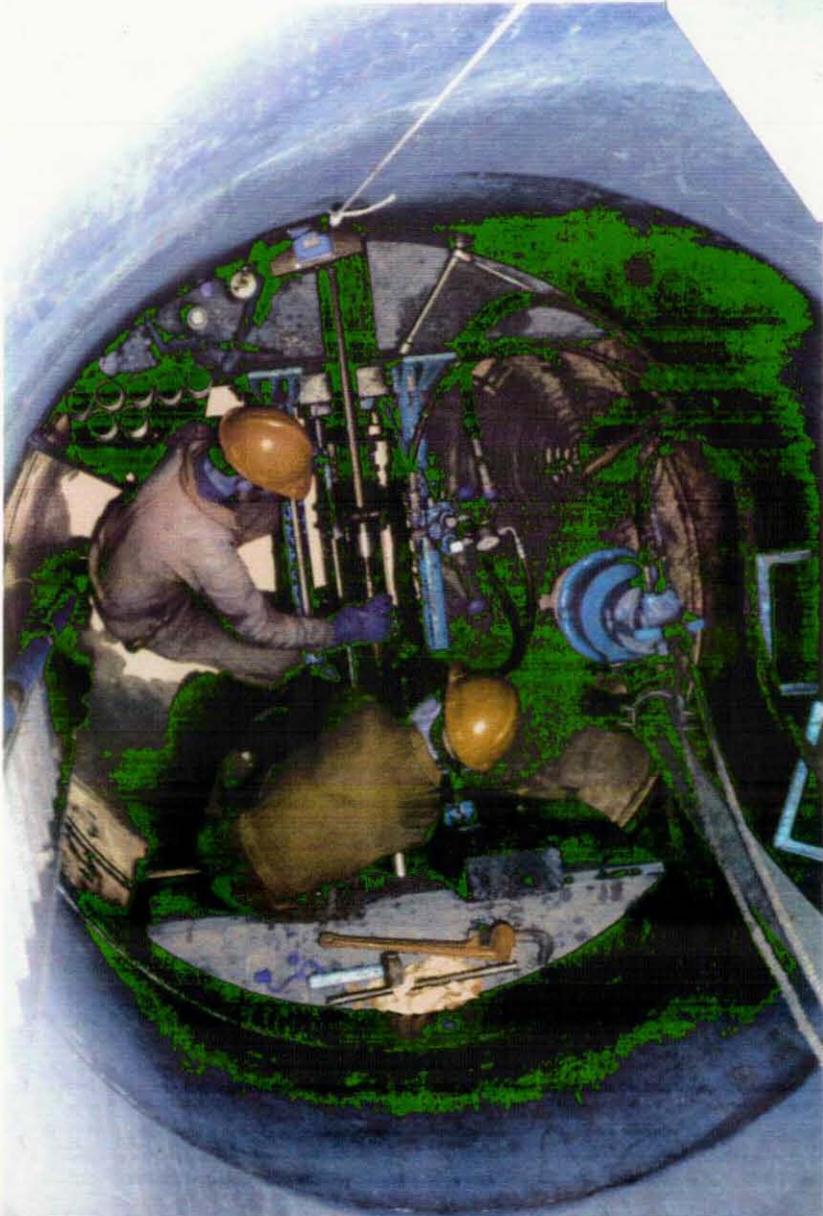


Figure 9B

Connecting subsequent lengths of inner screen and outer casing.

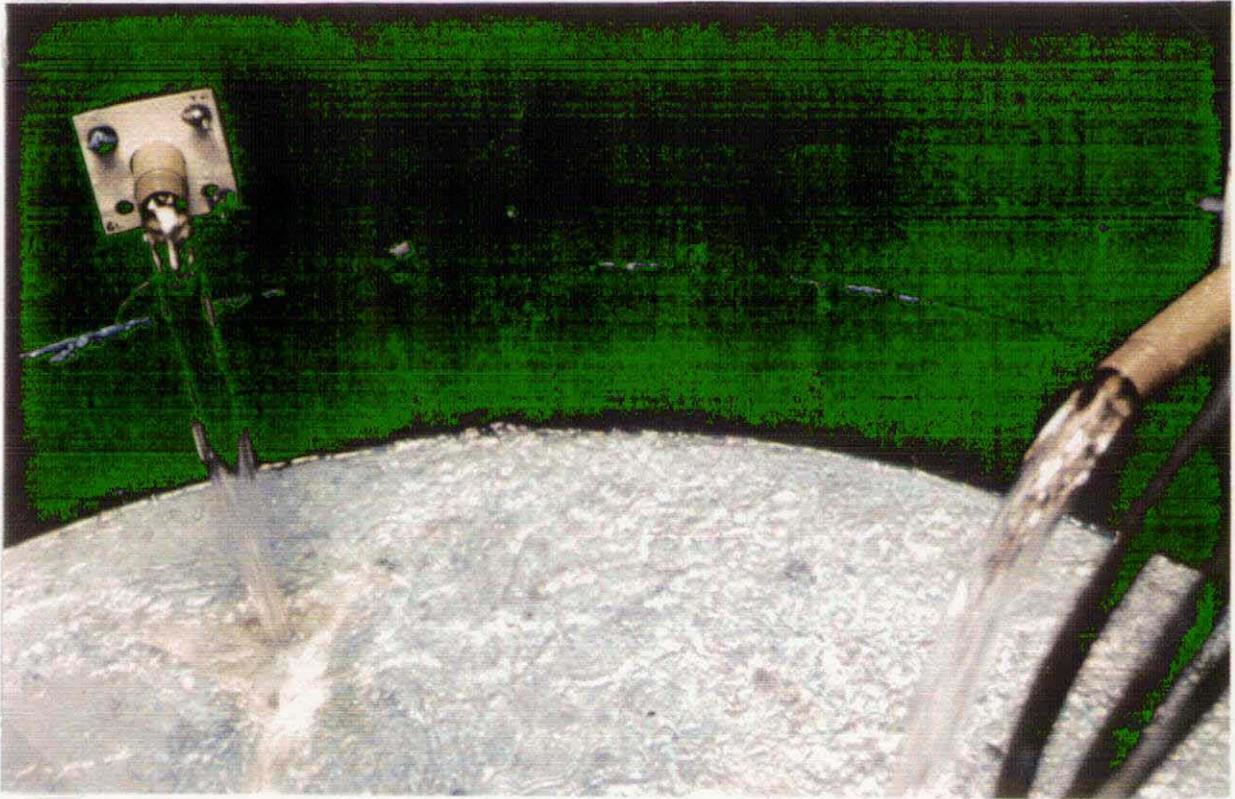


Figure 10. Radial development by free flow. Note low turbidity and suspended solids content after only 20 minutes development.

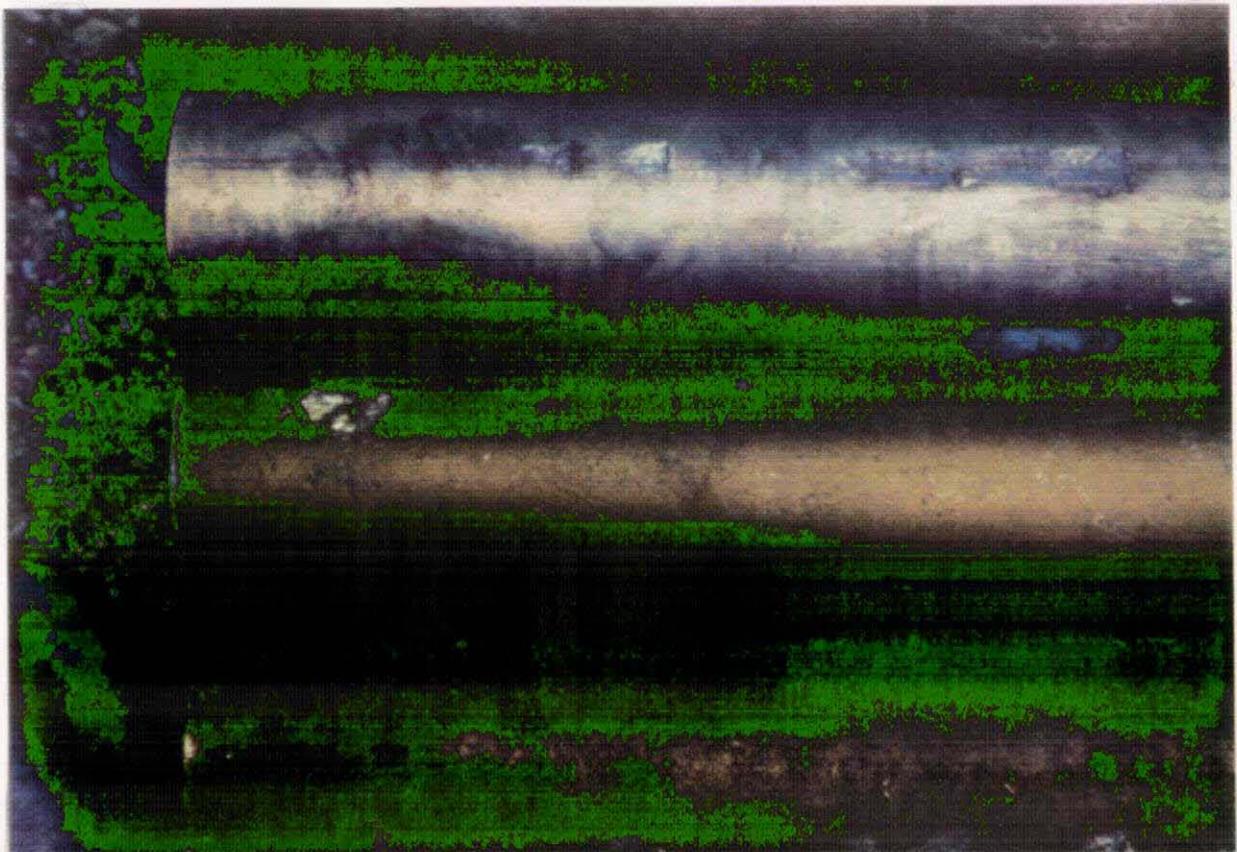


Figure 11. Standard weight BW casing deformed, scored and dimpled by moderate thrust-borer jaw pressure.

and the ID of the access holes in the perforated chamber ring (75 mm). The nearest available stock pipe size of 55 mm ID and 73 mm OD in machining grade steel was used to fabricate a non-standard heavy duty casing, producing a 50% increase in wall thickness to 9 mm. A sample of this pipe tested on the thrust-borer prior to threading showed negligible plastic deformation over the anticipated working range of 0-14 tonnes force, although dimpling occurred at about 11 tonnes force.

Comments.

Although the heavy duty casing did not fail even though subjected to 14 tonnes push force during the trial push of 15 January 1991, its routine use at formation resistances greater than about 10 tonnes is not possible. The onset of dimpling is a much severer handicap with thickwall pipe as the screen is a close fit inside, the clearance being only 0.5 mm compared with 4.5 mm using standard gauge BW casing. In practice therefore no dimpling is permissible, and as the jaw grips the pipe in proportion to the resistance encountered, an emplacement method which avoids subjecting the casing to formation resistances in excess of about 9-10 tonnes force is a prerequisite. This was achieved by redesign of the head (see section 4).

It had been noted that there occurred a disproportionate increase in formation resistance between pilot push with 73 mm ϕ head and 45 mm ϕ rods and screen emplacement push with the same diameter head and 73 mm ϕ casing (i.e. a head flush with the casing). The requirement to keep formation resistance as low as possible led to reconsideration of the geometry of the original push head array, to see whether, by redesign, the disproportionately high formation resistances could be overcome. In the event this was achieved by increasing the head maximum diameter, so that a pressure relief effect was created immediately behind the outermost step (see Feature C, Figure 5). A head-to-shank diameter ratio of 1.8 was found to be effective.

3.6 Access Plates and Wall Mountings

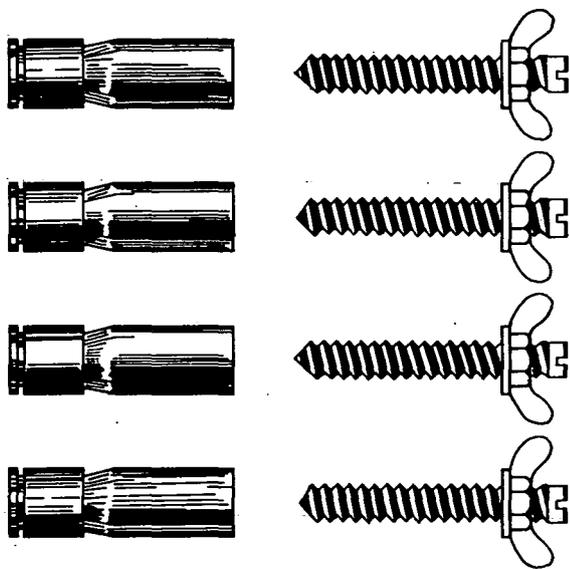
Description.

The plates were fabricated from 1.5 mm thick aluminium so that they could deform slightly if necessary during advance or retraction, without scoring the rods or casings. Two sizes were required for each radial, with 49 mm ϕ and 73 mm ϕ centre holes to fit push-rod and steel casing respectively (Figure 12A). The 49 mm ϕ plate size was also used on completion of the collector as a convenient means of retaining the permanent annular spacer.

Initially wall mountings were drilled using an air hammer and expanding bolts but this was found to be laborious and imprecise because the drill centre point could not be controlled. As the chamber ring around each access hole is heavily reinforced with iron reinforcing bars set in the concrete during casting, it was important to be able to drill each mounting accurately with the minimum hole size to avoid spalling of the access hole edges. This was achieved using a proprietary drop-in fixing and 110v lightweight rotary percussion drill (Spit drill and anchors) together with stainless steel 8 mm ϕ studs cut to size (Figure 12A). Excellent rigid mountings were rapidly obtained using this method.

Comments.

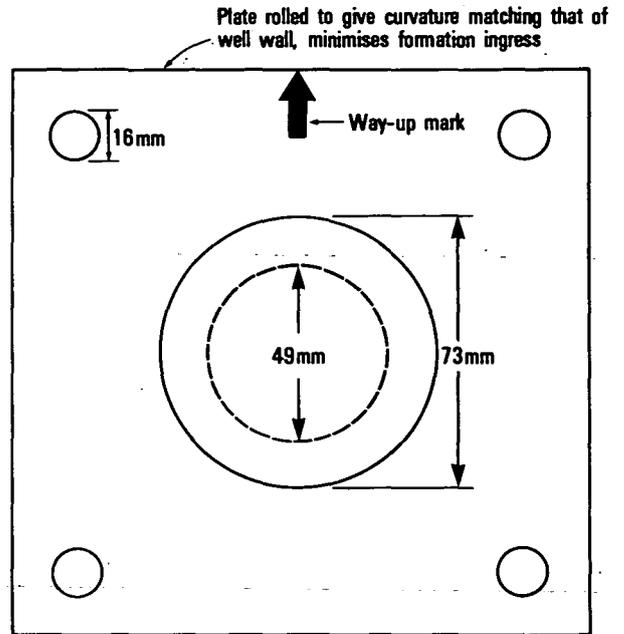
It was found that the ingress of formation sand around and through the access plates could be cut quite drastically by the simple expedients of (a) placing a sheet rubber slightly undersize gasket between plate and well wall and (b) rolling the plate to give a slight curvature matching that of the well wall. As a result sand ingress was reduced by over 75% from about 1 m³ per traverse during the early trials.



Not to scale

DESCRIPTION: 4 nos. proprietary brand steel female thread drop-in fixings (Spit Anchors); 4 nos. stainless steel threaded 8mm diam. studs c/w wide shoulder washers and wing nuts.

FUNCTION: retention of access hole cover plates



Scale approx 1:2

DESCRIPTION: 3 nos. aluminium 1.5mm thick access hole cover plates; 2 nos. with 49mm diam. centre hole, 1 no. with 73mm diam. centre hole.

FUNCTION: Formation retention;
 1). during pilot push
 2). during screen emplacement
 3). on completion of radial, to retain permanent annular plug

Figure 12A Accessories developed during field trials to facilitate radial collector emplacement by thrust-boring method

There is a strong incentive to reduce sand entry at all stages of collector construction. Excessive wellhead subsidence could cause differential settling and stress on the chamber rings comprising the main well shaft. Also, each m³ of wet sand weighs 2 tonnes. Its removal has to be performed manually to avoid damage to the protruding pipes of previously installed radials and it is a laborious task. It is necessary to clean the well at the completion of each radial, in order to be able to set up the thrust-borer correctly opposite the next access hole, so with the limited space available in a 2 m ϕ shaft, excessive sand requires that all shuttering and accessories be removed in order to clean out the well.

While an efficient means of constructing wall mountings was developed for these trials, there is no reason why the wall mountings should not be cast into the perforated chamber ring along with the access holes in a large scale collector well programme, or drilled into the perforated ring section prior to well construction.

3.7 Screen Emplacement Accessories

Description.

A temporary adaptor fabricated from PVC was required, to be coupled in-line to the final length of plastic casing (Figure 12B). Its function was to maintain the slight positive head inside the temporary casing/screen annulus during retraction, by preventing water washing back out of the screen into the well. A flushfit bleed device using an Allen screw and a hose thread adapter were combined into the same fitting.

On completion of temporary casing retraction around the header tank hose (Photo Figure 13), a PVC annular permanent plug was pushed into place by the thrust-borer as a loose sliding fit around the plastic sanitary casing, before mounting the fitted access plate (Figure 12B).

A threaded collector end-cap was used to cap each radial after completion and development.

Comments.

Early adaptor couplings without the bleed device suffered from airlocks due to the air trapped in the casing array after the water-filled hose had been coupled.

Unlike the standard BW casing which was used initially and had to be rejected, the heavy-duty casing which replaced it was found to have an irregular bore, and the original 1.5 mm diam medium density rubber O-rings were replaced with a 5 mm diameter soft variety which functioned adequately. For rapid and troublefree retraction however, a smooth uniform bore temporary casing is considered indispensable.

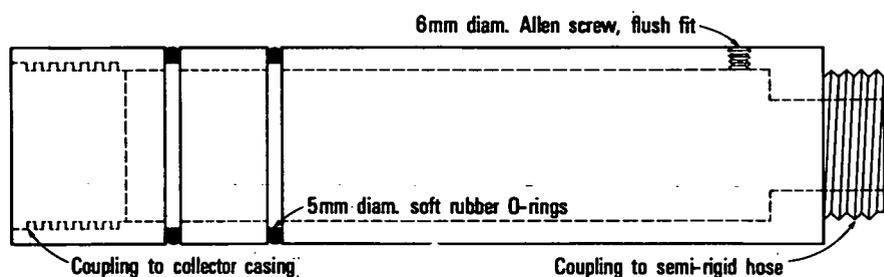
A quickly-detachable 48 mm ϕ wooden casing clamp which could be held manually or with chocks would assist retention of the screen array in place during retraction of the first few lengths of temporary casing (Figure 12B).

3.8 Shuttering

Description.

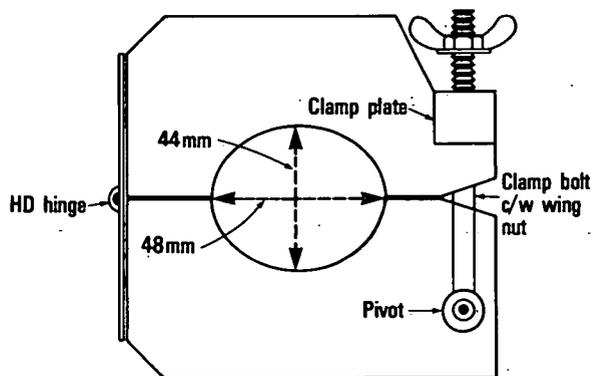
Arc-shaped wooden quadrants with heavy-duty plywood vertical backing boards were fabricated to provide a stable perpendicular face to jack against. Flexible steel sheeting was inserted between quadrant and perforated chamber ring to help spread the jacking force, and timber baulks used to protect the backing boards from the alignment jacks. The arrangement is shown in Photo Figures 7, 9A and 9B.

Scale approx 1:2



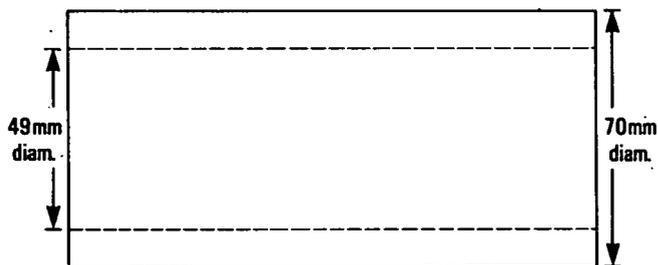
DESCRIPTION: Plastic combination temporary plug, bleed device and hose thread adaptor

- FUNCTION:** 1). to maintain positive hydraulic head inside temporary casing/screen annulus during retraction
 2). to bleed air from system prior to retraction
 3). DIN/BSP thread adaptor



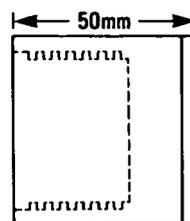
DESCRIPTION: Wooden casing/hose coupling clamp

FUNCTION: To assist retention of screen array in place during retraction of first lengths of temp. casing



DESCRIPTION: Plastic permanent annular plug

FUNCTION: To retain formation once temp. casing withdrawn



DESCRIPTION: Plastic collector end-cap

FUNCTION: To stop flow while other radials installed

Figure 12B Accessories developed during field trials to facilitate radial collector emplacement by thrust-boring method

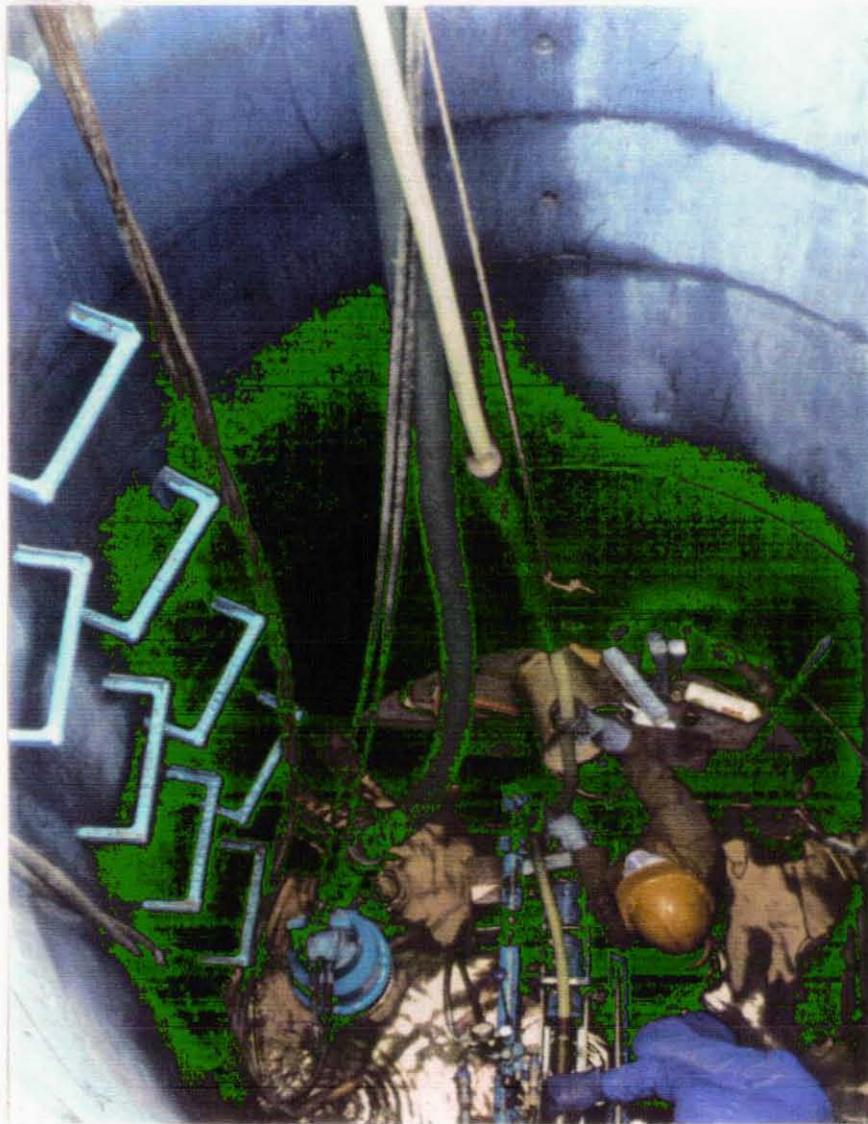


Figure 13. Retraction of temporary casing while maintaining inflow to avoid sand-locking.

Comments.

The arrangement worked well, and the materials were still in usable form after 14 emplacement episodes, some of which were severe. The quadrants should continue to be designed in sandwich form, so that, if necessary, completed radials can protrude into the shuttering without being damaged by subsequent jacking operations.

4. RESULTS

The illustrative graphs used in this section plot the jacking force required to advance or retract an array against depth of penetration into the formation. In practice, the jacking force was measured in the field as a pressure reading from a gauge installed in the thrust-borer hydraulic system which gripped and propelled the pipe. A 100 psi increment was equivalent to approximately 0.58 tonnes force (5.65 kN).

4.1 Thrust-boring with Pilot Push-head

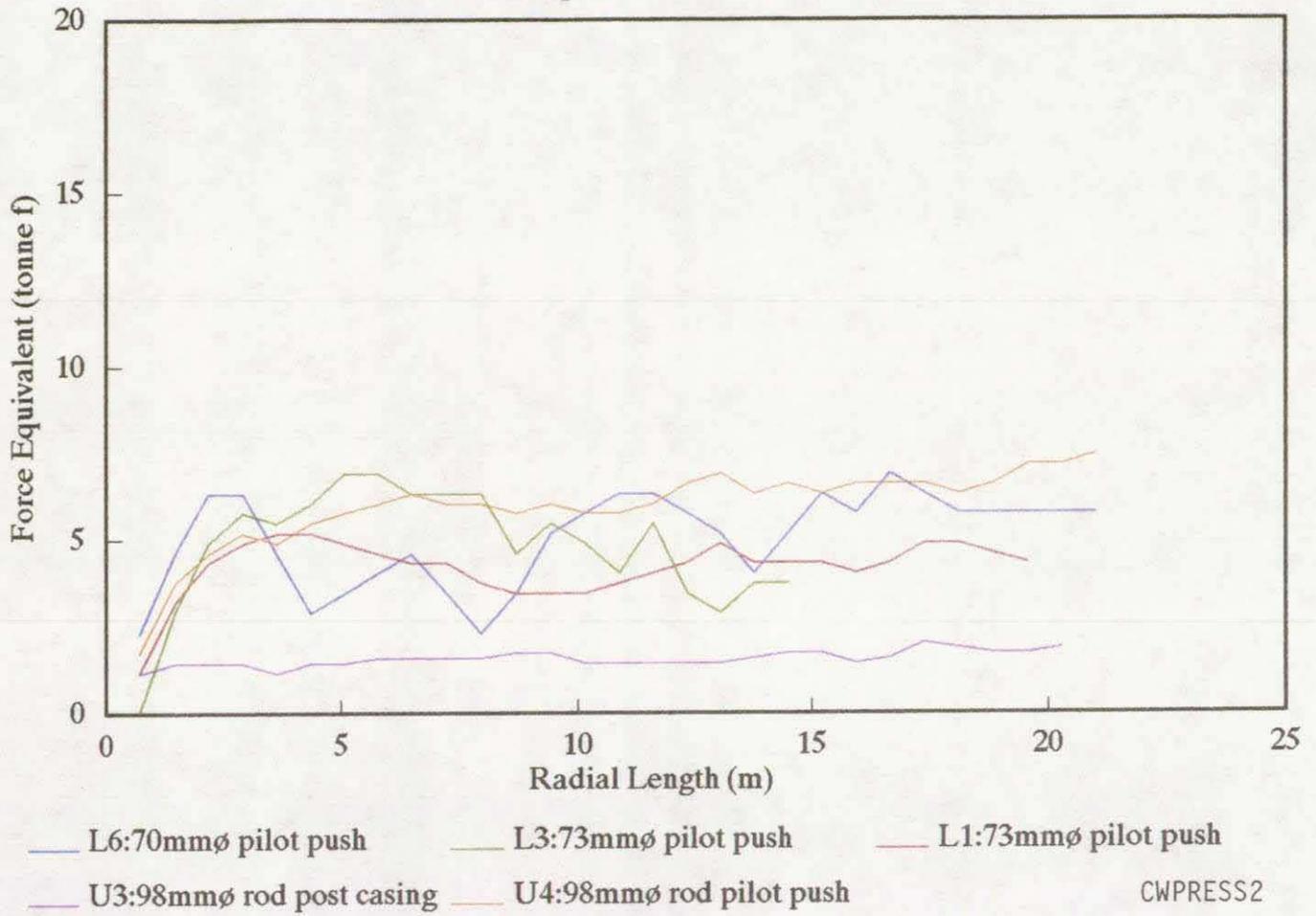
The combination of 70 mm ϕ pilot push-head and 45 mm ϕ push-rods was the first thrust-boring array tried at Carmer Wood. The low formation resistances and rapid jacking rates found at the first trial were subsequently replicated with similar combinations bored out in different directions from the central shaft. In Figure 14 the average force per complete push rod increment (0.725 m) up to approximately 20 m distance is shown for 5 separate rod pushes. L6, L3 and L1 had 70/73 mm diam. pilot heads while 98 mm diam. heads were used in U3 and U4. The following features are noteworthy:

- (i) The envelope of thrust-boring resistances of all 5 pushes was less than 7 tonnes. This was well within the capacity of the thrust-borer (about 45% of quoted maximum jacking force), and implied a moderately low tensile loading on the perforated chamber ring (less than 80 kN/m² assuming that the imposed stress was distributed across the whole contact area of the quadrant arc opposite the radial in question).
- (ii) L6, L3, L1 and U4 were pilot pushes and the shape of their force/advance curve was similar. An initial steep rise in formation resistance occurring over the first 3 metres was followed by a flattened and variable section. The variability of response along individual radial orientations was marked and rather surprising. One might have expected to observe a progressive rise in jacking force proportional to the length of bore, as frictional resistance to the head and pipes increased. No such trend was observed. U4 showed a very modest increase in resistance at the rate of about 0.1 tonnes force/m; L1 and L6 were irregular but showed no overall upward trend; while in L3 the formation resistance actually decreased as the radial length increased.

As jacking speeds along each radial were kept fairly constant, differences in penetration rate can be excluded as a causal factor. One plausible explanation is that the observed variations in required jacking force were more strongly related to localised differences in formation resistance than to the increase in frictional resistance as more rods were inserted. Formation effects could have masked the relatively small increase in resistance due to rod friction. Rapid lateral and vertical cross-formation changes in grain size distribution and bulk density could give rise to formation variations, and they are characteristic of riverine alluvium. They occur during deposition as a response to differences in cross- and down-channel stream energy profile.

L1, L3 and U3, U4 etc. refer to the numbered access holes in the perforated chamber ring, 75 mm and 100 mm ϕ respectively.

Figure 14 CARMER WOOD THRUST-BORING TRIALS 90/91
 Pilot push head + 45mm ϕ rods



- (iii) U3 was a secondary push with 45 mm rods after a pilot push using the same size head and casing. It was notable for the very low jacking force required throughout the push. The inference is that even though the aquifer is totally unconsolidated, a repacked cylindrical zone of lower density (and presumably higher porosity) is created which remains for some time after the pilot array has been retracted. A pilot push with a dummy disposable push-head is therefore a most valuable preliminary to screen emplacement with temporary casing.
- (iv) There was only a minor increase in jacking force using a 98 mm ϕ pilot head instead of a 70/73 mm ϕ head. This was a surprising result. The frictional force to be overcome during jacking at any given radial length is proportional to the sum of the resistance of the head and of the push-rods installed at the time. As the cross-sectional area of the larger of the 2 push-heads is almost twice the smaller, two contrasting inferences can be drawn:
 - (a) either the head resistance alone was only a small component of the total, so a doubling of its magnitude only marginally increased the total frictional resistance, or
 - (b) the head resistance was significant but the geometry of an oversize head on a slimmer pipe offset the scale effect.

It was not practicable to measure directly the two different resistance components, but towards the end of the trials, when the 98 mm head was in use, a method of measuring the jack retraction force was devised (the feed lines to the pressure gauge on the thrust-borer's hydraulic feed were changed over). While the force needed to advance (measured on the gauge as feed pressure) equals the sum of head and pipe frictional resistance, during withdrawal pipe friction is dominant, and the difference between the two values is a crude measure of the resistance of just the head assembly.

Advance and withdrawal data for only two of the pilot rod pushes are available in this way, but they indicate that inference (a) is incorrect. In Figure 15 advance, withdraw, and advance-minus-withdraw jacking force is traced for the U4 push. The graph shows that, beyond the first metre or so, the head and pipe resistance are of about equal magnitude. A similar plot for the U2 pilot push (Figure 16) is more complex, as there is a strong lithological variation superimposed, but the head resistance component appears to be rather greater than the pipe resistance. Both sets of data confirm that formation resistance to the head is significant in relation to the total frictional force acting on the array.

An important inference which can be drawn from the pilot push data is that, in uniform saturated uncemented sands, more important than either the diameter or the target length of the push is the geometry of the head/rod array, and specifically the ratio of the head diameter to the following rod or pipe.

4.2 Thrust-boring with 73 mm OD Casing

4.2.1 73 mm ϕ Head and 73 mm ϕ Casing.

In contrast to the pilot push-head array, the combination of 73 mm ϕ casing and flush end-cap was much more difficult to emplace. Figure 17 shows force/advance curves for four different radials using a 73 mm ϕ head and 73 mm ϕ casing:

- (i) Although the design of the forward part of the end-cap, and its overall diameter were identical to the pilot push-heads used in the pushes described above in section 4.1, jacking force requirements increased rapidly within the first few metres to over 14 tonnes in L3, L1 and L5. This resulted in rapid deformation of, and permanent

Figure 15 CARMER WOOD THRUST-BORING TRIALS 90/91
U4:rods + 98mm head: pilot push

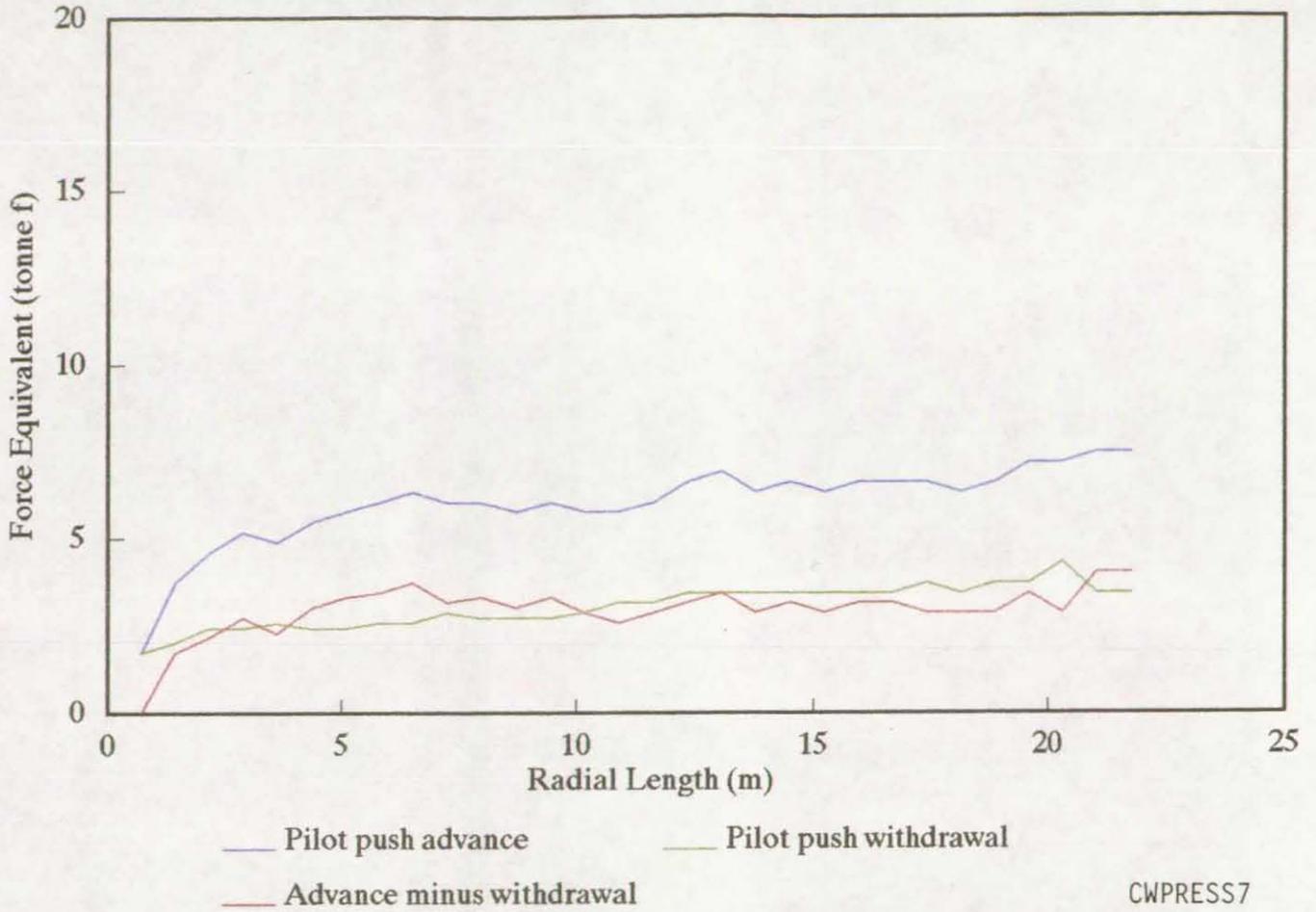


Figure 16 CARMER WOOD THRUST-BORING TRIALS 90/91
U2:casing + 98mm head : pilot push

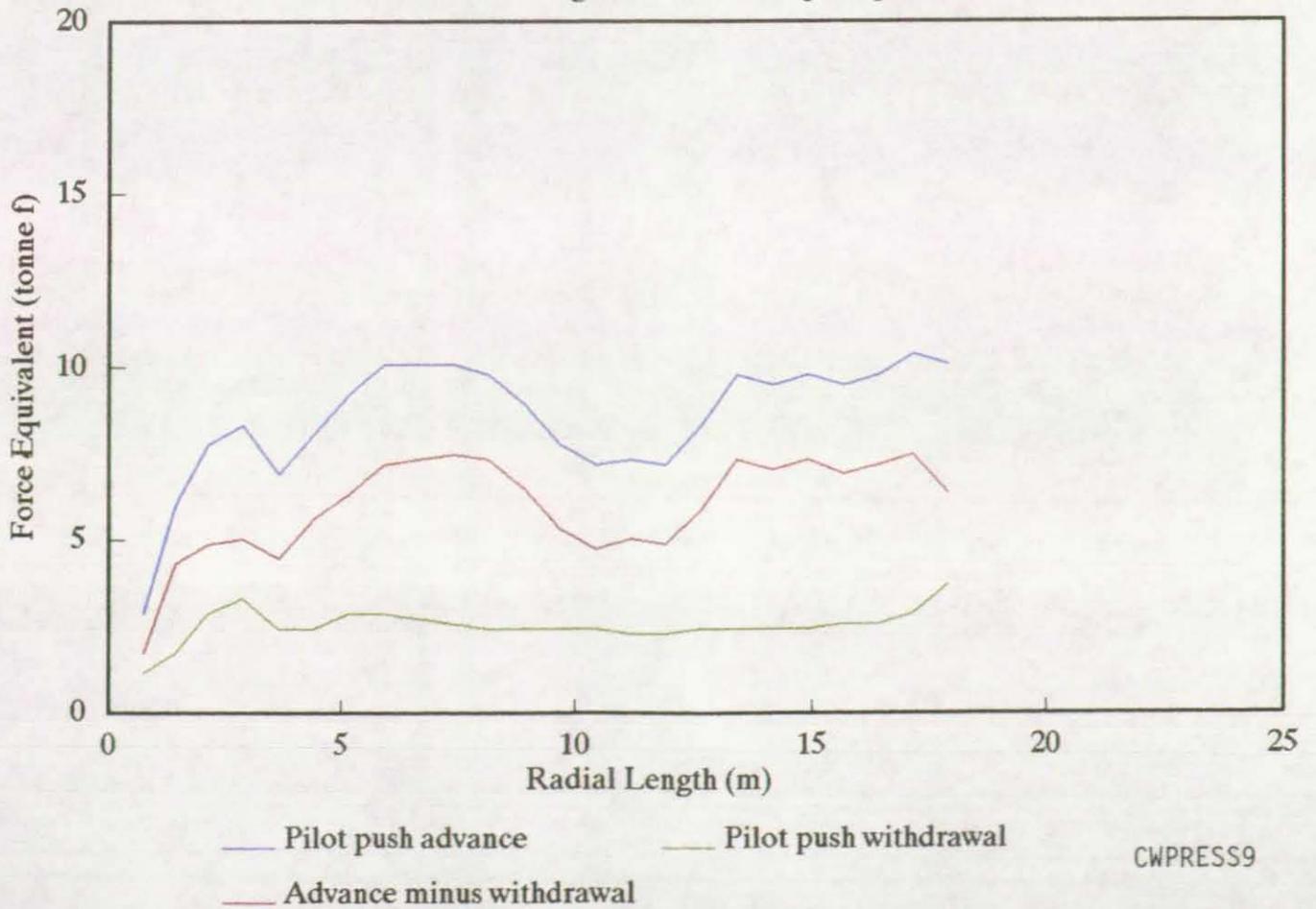


Figure 17 CARMER WOOD THRUST-BORING TRIALS 90/91
73mm ϕ end-cap flush with 73mm ϕ casing

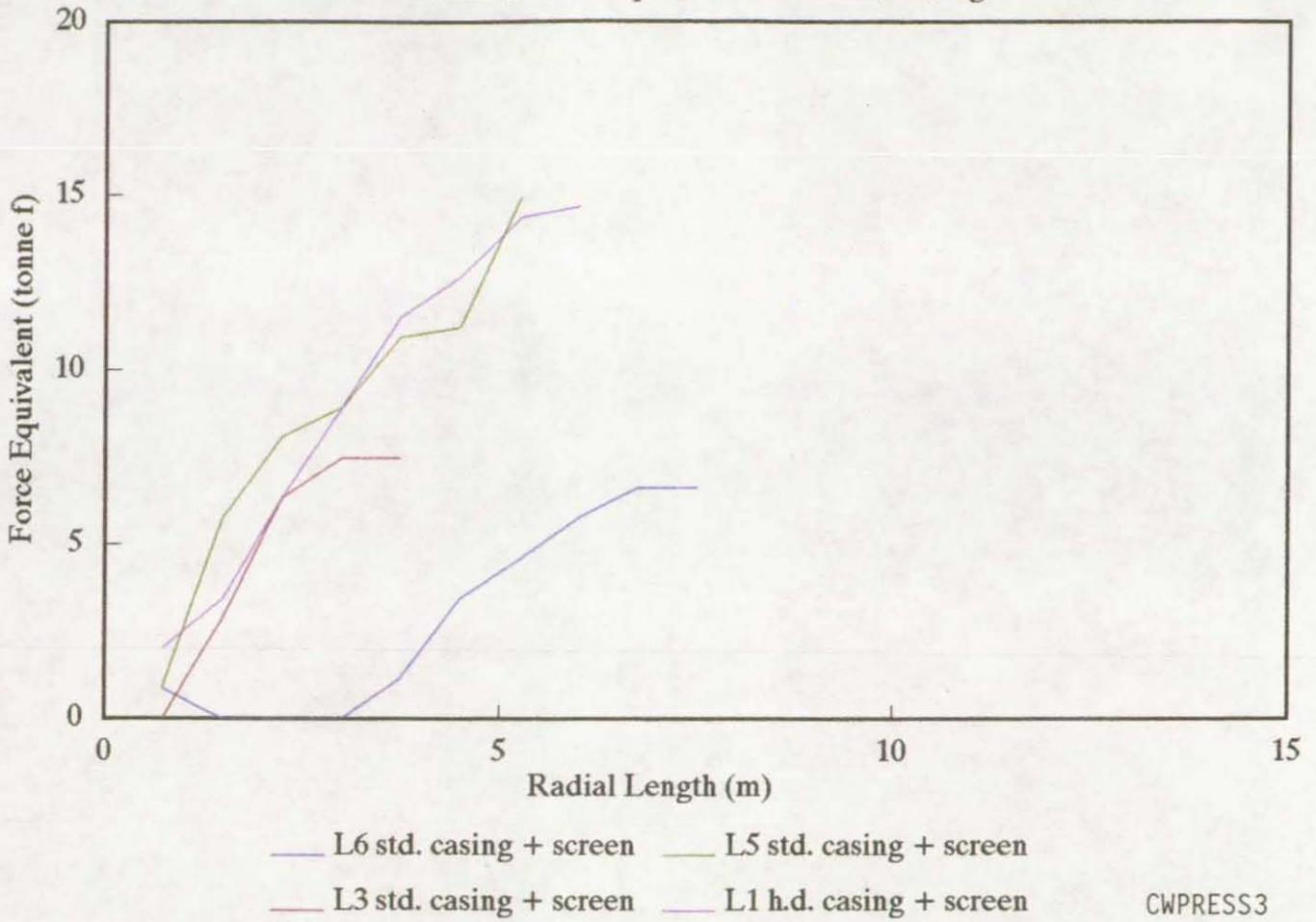
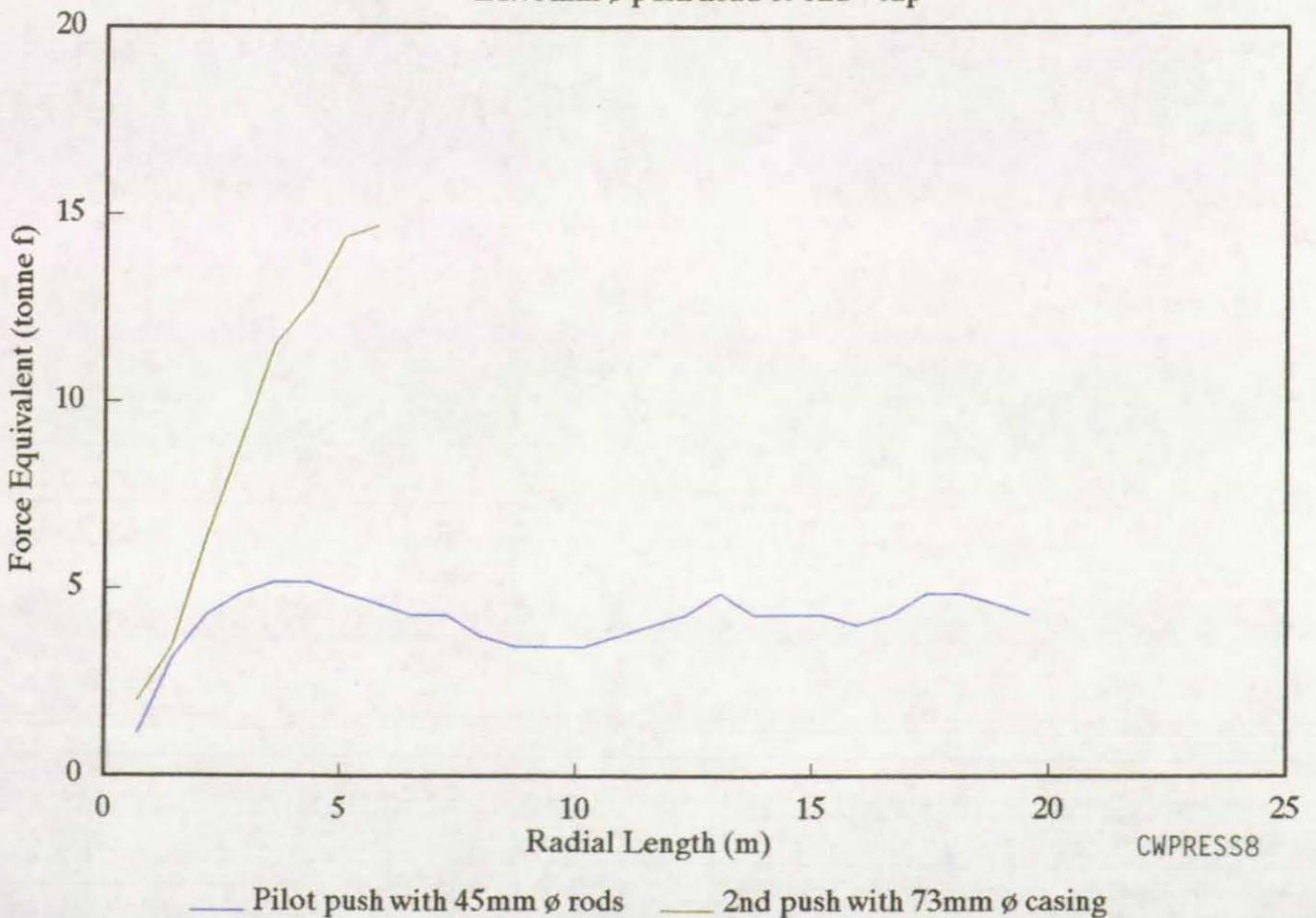


Figure 18 CARMER WOOD THRUST-BORING TRIALS 90/91
L1:73mm ϕ push head & end-cap



damage to, the casing, and caused in turn severe, abrupt and potentially dangerous slippage of the pipe jaw. The steep rate of increase in jacking force showed no signs of diminishing when the array could be advanced no further, which occurred at less than 6 m penetration at each attempt.

- (ii) The very high formation resistance was encountered both when the casing array was the first used and when it had been preceded by a pilot push using the same diameter head. The L1 pilot push with 45 mm ϕ rods is plotted on Figure 18 together with the subsequent casing push. It can be observed that jacking force did not exceed 5 tonnes during advance yet when the casing array was substituted immediately afterwards, the force requirement almost tripled to 14 tonnes.
- (iii) L6 appears anomalous, in not showing the steep increase in push force within the first 4 metres. In fact several previous pushes up to 8.5 m length had been made through the same access hole during previous experiments with the rod-in-screen array, in the course of which several cubic metres of aquifer had been displaced into the central shaft. The zone penetrated by this radial was therefore considered a disturbed non-representative case.

Although observation (ii) above appears to contradict the results of the pilot push work (where subsequent pushes were greatly facilitated by a pilot push) it in fact just confirms the importance of the head to pipe ratio; attempting to install a tube using a head of the same diameter engendered high formation resistance which even the repacking effect of a pilot push could not counteract.

4.2.2 98 mm ϕ Head and 73 mm ϕ Casing.

The third array used at the Carmer Wood site was developed in response to the problems described above. Four pushes were carried out with a 98 mm ϕ oversize head and the same heavy-duty casing used in the latter part of the flush end-cap work described above. All four were successful, reaching more than 17.5 m penetration (Figure 19). In U3 and U2 no rod pilot push was employed, so the oversize head and casing entered undisturbed ground in pilot fashion; in U2 a second push used the same array; and in U4 a preliminary pilot push with 45 mm ϕ rods and oversize head preceded the casing push. The following features are of note:

- (i) The pushes encountering greatest resistance (U2 and U3 casing pilot pushes) were made without the benefit of a pilot push, yet even they did not exceed about 10 tonnes push force (the maximum permissible which would avoid dimpling of the pipe and casing/screen damage).
- (ii) U4 casing push was greatly facilitated by the rod pilot push with oversize head; as a result the array was easily emplaced with a push force barely exceeding 5 tonnes. The same effect was even more marked during the second casing push in U2, where much of the emplacement to pilot push distance was achieved at less than 4 tonnes force. The advance and withdrawal curves for U2 have been extracted in Figure 20 for clarity. The steep increase in formation resistance during the second push advance as the head approached undisturbed ground beyond 17.5 m is well illustrated, the force required rising to pilot push values again beyond 18 m. Although the two pushes were both carried out the same day, the repacking of the formation in a zone around the radial is clearly not a transient phenomenon. In typical construction conditions, it would be normal and prudent practice to conduct a pilot push and follow-up casing push on the same day.

Figure 19 CARMER WOOD THRUST-BORING TRIALS 90/91
98mm ϕ oversize head + 73mm ϕ casing

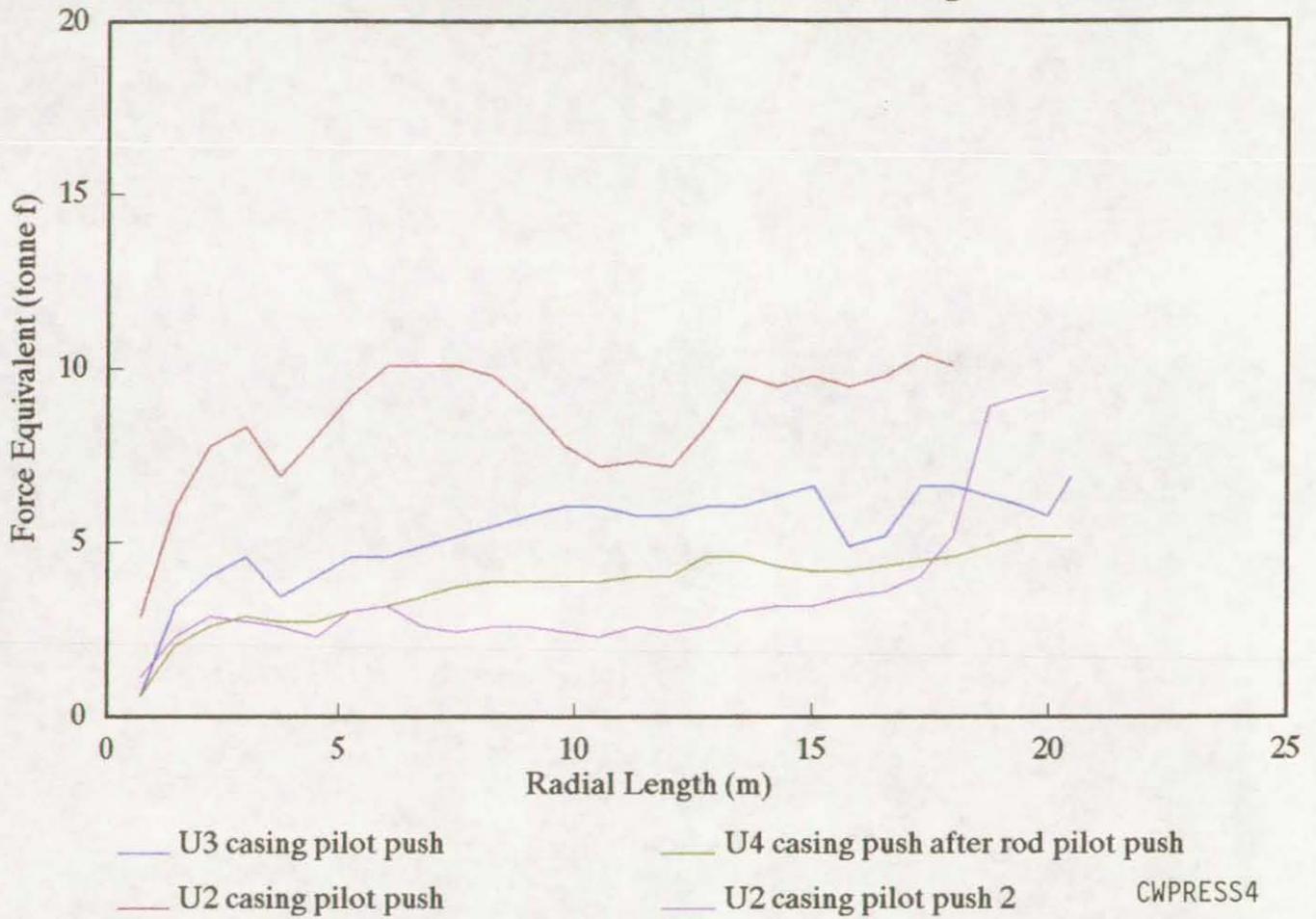
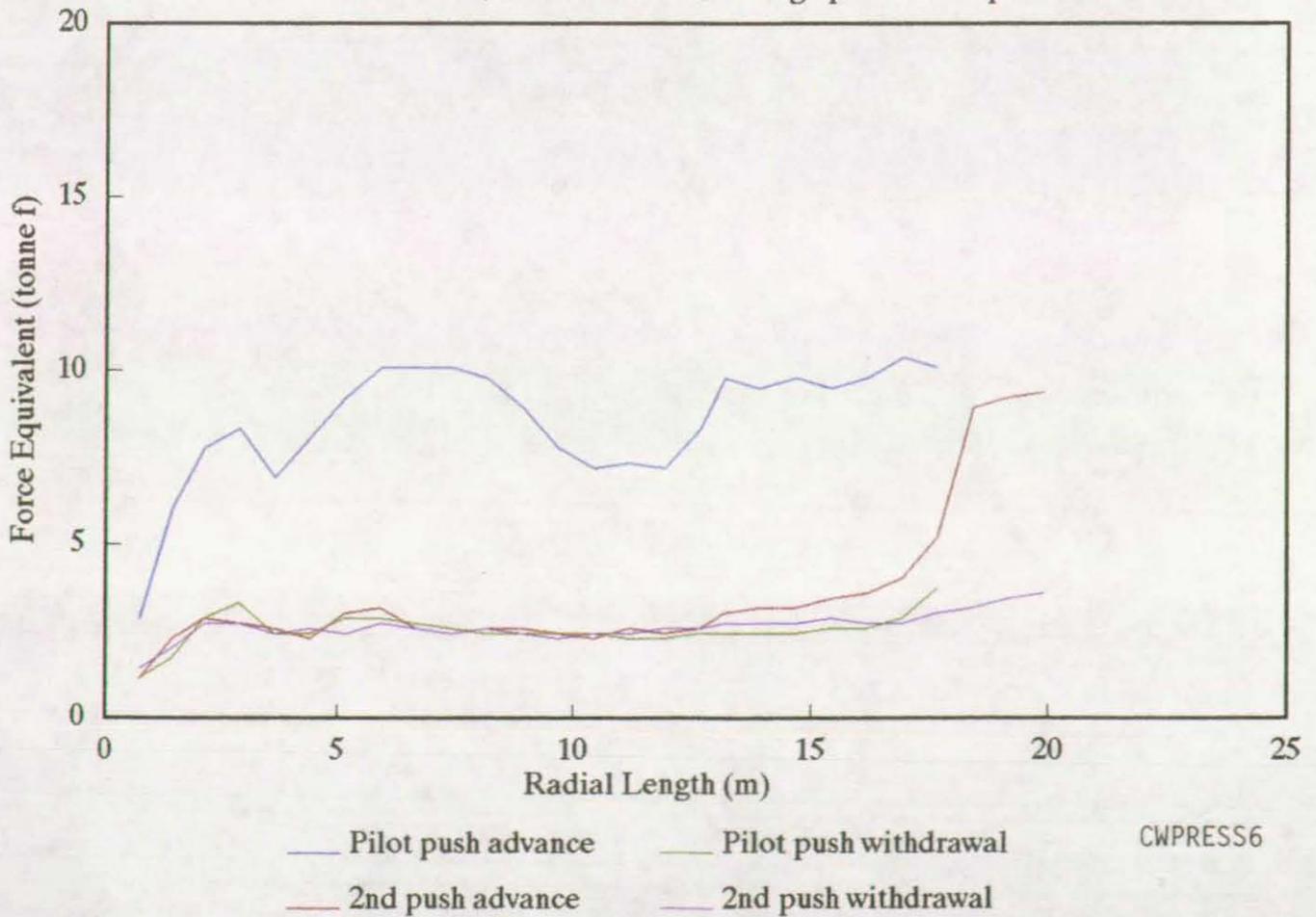


Figure 20 CARMER WOOD THRUST-BORING TRIALS 90/91
U2:98mm ϕ head + 73mm ϕ casing : pilot & 2nd push



- (iii) The shape of the force/advance curves was similar to the pilot rod pushes, with an initial steep rise followed generally by a flattened section. The latter showed a progressive but gentle increase in push force in three of the four pushes, and an irregular increase (partly masked by probable formation changes) can be observed in the fourth. The rate was about 0.12 tonnes force/m, which is similar to that observed in the U4 pilot rod push. By extrapolation, construction of collectors of up to 30 m length would be routinely within the capacity of the equipment, provided a rod pilot push was employed.

4.3 Productivity Rates of Radial Construction

Mean rates of penetration for 18 advance and withdrawal episodes using pilot head with rods or oversize head with casing are shown in Figure 21. For ease of comparison, the penetration rates logged do not include time taken to simultaneously telescope the plastic mesh-wrapped screen inside the casing; in practice screen coupling took only a couple of minutes per section. Rates of advance and of withdrawal averaged about 1 m/min excluding coupling time. By the end of the trials, when operator dexterity and techniques had improved, a 20 m pilot push advance and withdrawal was typically taking under 2 hours, including mortar plug removal and coupling/uncoupling time. A secondary advance with casing and screen would take about 2 hours, including changeover of pipe-jack jaws to accommodate the pipe. Casing withdrawal was generally much slower as preparation time was necessary to set up the positive head system.

4.4 Summary of Thrust-boring Results

The main features of the thrust-boring trials using different arrays are summarised in Figure 22.

- (i) Jacking-in rods or casing behind a head of a larger diameter was much easier than using a head of a similar size.
- (ii) Subsequent advances were generally much easier than the initial advance into the undisturbed formation.
- (iii) Although it is not clear whether a pilot push with 45 mm ϕ rods results in lower peak jacking force requirement than a similar pilot push with the 73 mm ϕ temporary casing, the former is much easier and faster to do and results in significantly less wear on the casing. The pilot push rapidly confirms to the operator whether a collector emplacement is feasible along the orientation of that particular radial.

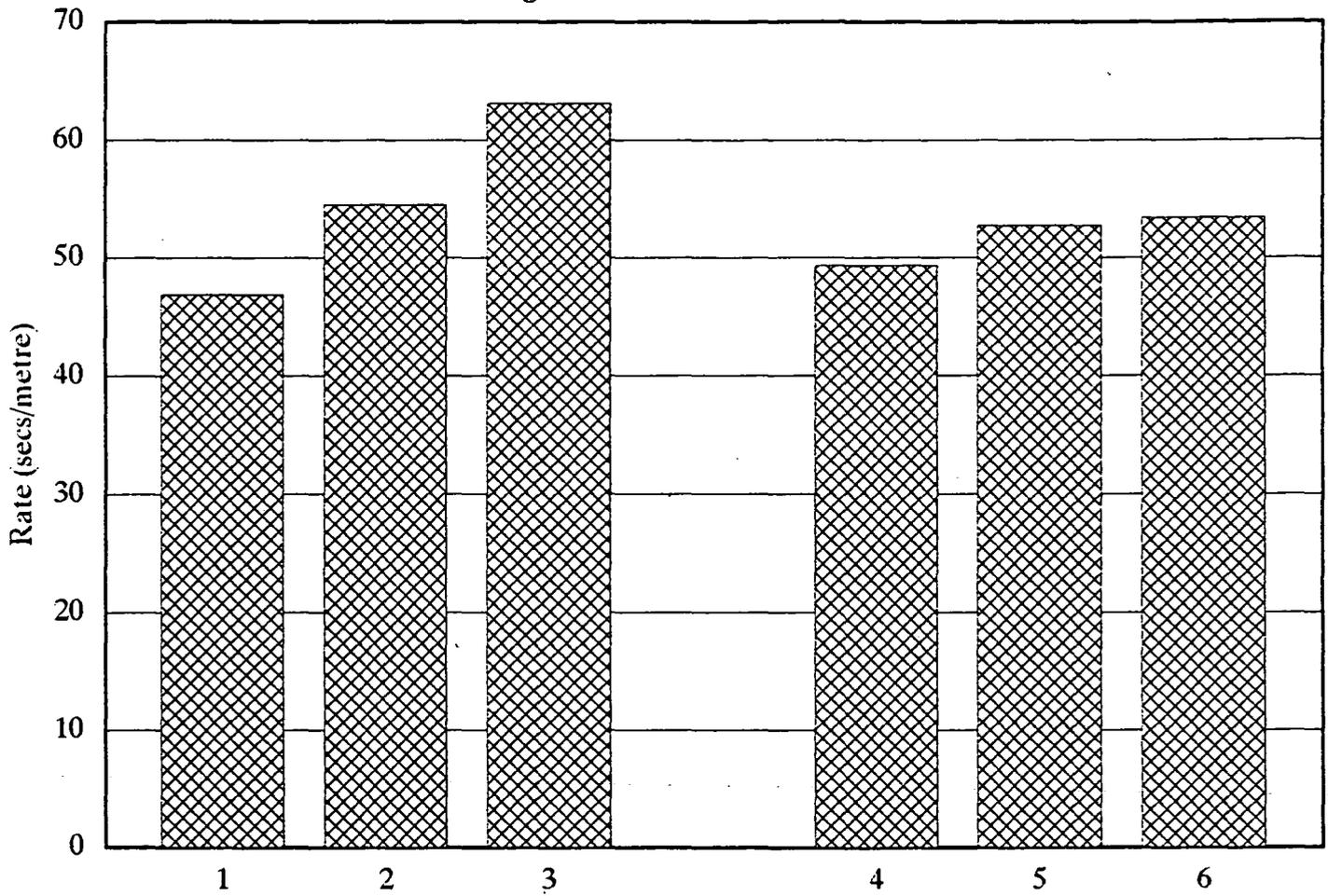
4.5 Timetabling Collector Construction by Screen-Within-Casing Method

Summarising the various stages involved in constructing a radial in a pre-prepared shaft-only dugwell, it took about a working day to dewater the well, install the thrust-boring equipment in the shaft and level it up opposite an access hole. Pilot push, screen-in-casing emplacement and casing withdrawal would typically take a further 2 working days. Subsequent radials would also take up to 3 days, as sand removal by hand from the main shaft would be required on completion of each collector. With experienced operators and prepared access hole mountings, it is estimated that the conversion of a shaft-only dugwell into a 3 radial collector well would take about 2-3 working weeks for a 3/4-person team. A typical timetable of operations would be as follows:

Day 1: Mobilise to well, install opposite access #1.

Day 2: Pilot advance/withdraw; emplace screen; prepare casing retraction.

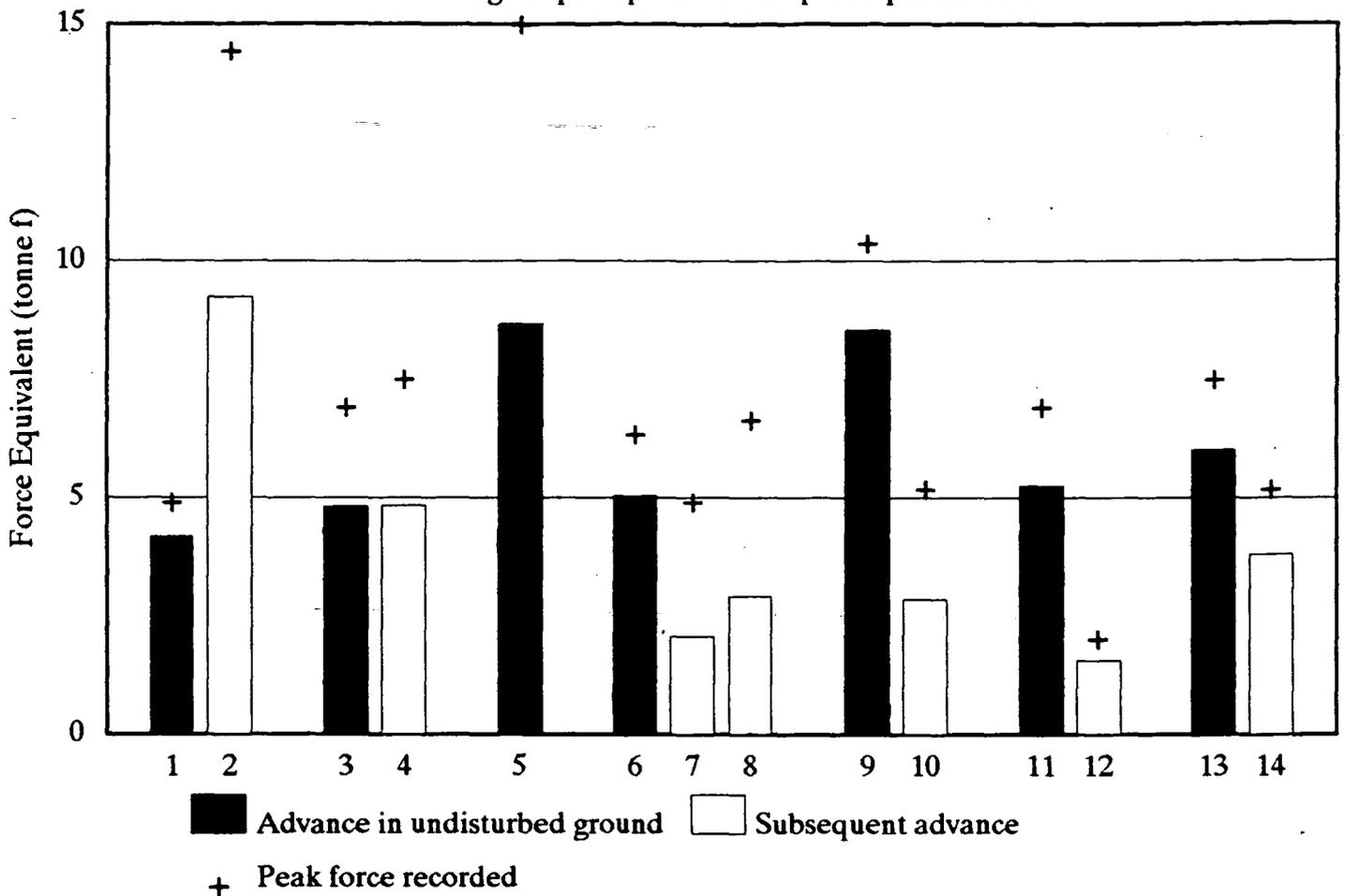
Figure 21 CARMER WOOD THRUST - BORING TRIALS 90/91
Average rate of advances and withdrawals



1. 70/73 mm ϕ Head + push rods advance (3 nos)
2. 98 mm ϕ Head + push rods advance (2 nos)
3. 98 mm ϕ Head + casing advance (4 nos)
4. 70/73 mm ϕ Head + push rods withdrawal (3 nos)
5. 98 mm ϕ Head + push rods withdrawal (2 nos)
6. 98 mm ϕ Head + casing withdrawal (4 nos)

Figure 22

CARMER WOOD THRUST-BORING TRIALS 90/91
Average & peak push force required per advance



- | | |
|---------|---------------------------------------|
| 1 = L1 | 73 mm ϕ head + push rods |
| 2 = L1 | 73 mm ϕ head + casing |
| 3 = L3 | 73 mm ϕ head + push rods |
| 4 = L3 | 73 mm ϕ head + casing* |
| 5 = L5 | 73 mm ϕ head + casing |
| 6 = L6 | 70 mm ϕ head + push rods |
| 7 = L6 | 73 mm ϕ head + push rods |
| 8 = L6 | 73 mm ϕ head + casing** |
| 9 = U2 | 98 mm ϕ head + casing |
| 10 = U2 | 98 mm ϕ head + casing to 17.65 m |
| 11 = U3 | 98 mm ϕ head + casing |
| 12 = U3 | 98 mm ϕ head + push rods |
| 13 = U4 | 98 mm ϕ head + push rods |
| 14 = U4 | 98 mm ϕ head + casing |

* Not representative; push aborted early
 ** Not representative; push in disturbed zone

- Day 3: Withdraw temporary casing; develop radial #1.
- Day 4: Clean well; install opposite access #2.
- Day 5: Pilot advance/withdraw; emplace screen; prepare casing retraction.
- Day 6: Withdraw temporary casing; develop radial #2
- Day 7: Clean well; install opposite access #3.
- Day 8: Pilot advance/withdraw; emplace screen; prepare casing retraction.
- Day 9: Withdraw temporary casing; develop radial #3.
- Day 10: Clean well; disinstall equipment; clear site; demobilise.

5. CONCLUSIONS

- (1) Extensive field trials have been conducted to test the viability of thrust-boring in the saturated zone as an inexpensive means of constructing collectors in unconsolidated thin fine-grained alluvial aquifers. A concrete dugwell with a perforated lower ring sunk in a shallow fine running sand aquifer has provided testing conditions for the method. With suitable precautions to guard against excessive sand ingress, it was demonstrated that thrust-boring could be routinely carried out at depths up to 3.5 m below the water table. Head diameters up to 100 mm were jacked out and back at an average rate of 1 m/min in unstable fine sands to lengths of over 20 m using a lightweight construction-industry thrust-borer which had undergone only minor modifications.
- (2) Initial trials to emplace collector well screen by jacking out standard thrust borer rods telescoped inside inexpensive slotted pipe were unsuccessful, as autodevelopment of the formation led to insurmountable sand-locking problems.
- (3) As a result, an inverted (screen-within-casing) system has been developed in which mesh-wrapped plastic screen is emplaced inside temporary steel casing which acts as drive pipe. Sand-locks and excessive formation ingress into the main shaft are avoided by a simple positive head system which reverses the flow of water along the collector until the temporary casing has been successfully withdrawn. The system was successfully tested in the field and collectors installed.
- (4) The resultant 38 mm ID collectors, which were set in fine to medium sands of low uniformity coefficient, were able to autodevelop without the need for any other well development method. Yields of about 1.5 l/s/radial with negligible sand content were obtained after short development periods of less than an hour.
- (5) It was found initially that a disproportionate and excessive jacking effort was required to emplace the 73 mm ϕ casing sheathing the screen, in comparison with pushes which employed 45 mm ϕ rods. Not only would unacceptable damage to the temporary casing result, but also the reaction force on the chamber ring opposite wall would be higher than necessary. Chamber ring design criteria would therefore need to be more stringent and the extra materials/construction cost of the central shaft would be reflected in a higher total cost for the collector well.

- (6) It was found by experimentation that excessive jacking force could be avoided by two simple expedients:
- (a) Increasing the push head diameter in relation to the following pipe. For the 73 mm ϕ pipe used in the trials, a sacrificial push-head with a head-to-shank ratio of 1.8 was found to be a successful combination. This enabled a 38 mm ID mesh-wrapped collector to be emplaced through a 100 mm ϕ access hole in the perforated concrete chamber ring of the well.
 - (b) Conducting a pilot-push with the disposable head coupled to standard 45 mm ϕ rods before jacking out the screen-in-casing array. A simple redesign of the head would permit it to be used during both jacking operations, and serve as a safety plug during the critical changeover period from rods to casings.
- (7) As a result, the jacking requirement for a 20 m screen-in-casing emplacement was reduced to less than 7 tonnes force. This was well within the capacity of the equipment used, and was equivalent to a stress of less than 80 kN/m² on the chamber ring wall contact area opposite the radial being installed.
- (8) Basic design criteria for the dugwell were developed. The minimum internal well diameter in which collectors could be constructed by thrust-boring would be 2.0 m. As penetration into the saturated unconsolidated aquifer of more than 3-4 m is unlikely to be achieved by typical well-digging methods, the perforated access hole ring should either comprise the upper part of, or immediately follow, the leading (cutting) ring. All rings should be connected by tiebars to maintain shaft integrity during radial construction. The perforated ring should be strongly reinforced with integral reinforcing bars, in order to withstand both the inherent weakness due to the cast access holes and transient stresses from the jacking operations. Sand ingress during collector construction should also be controlled as far as possible, in order to minimise stresses arising from differential settlement around the well. Much time and effort could be saved by setting access plate anchor points in the perforated ring during the casting process. Soft brick-rubble with mortar was perfectly acceptable as temporary plug to the access holes during main shaft construction.
- (9) The trials at Carmer Wood were carried out inside a dugwell constructed from reinforced concrete chamber rings, with each ring interconnected by integral tie bars to provide vertical rigidity. Construction using precast caisson rings would probably be the only practical method of lining a dugwell in an unconsolidated sand aquifer, and it is not envisaged that thrust-boring would be employed in a well lined by any other means. No problems of main shaft deterioration were encountered during thrust-boring. It was estimated that provided the reaction stress was distributed by the shuttering, jacking forces in the range anticipated by the method (<10 tonnes f) would result in loadings of less than 115 kN/m².
- (10) However the concrete rings typically found in a developing country well construction programme would be significantly cruder than the geotechnical rings employed for the UK work; poor control over cement and fines content and reinforcing rod work can for instance drastically reduce the strength of a cast caisson ring. Even though the indicated loadings are light, further trials, preferably in the context of an actual rural well-digging programme, are indicated in order to confirm that perforated reinforced caisson rings cast using standard methods appropriate to a developing country would be strong enough in practice to withstand the stresses which collector well construction can impose on a well lining.

- (11) An integral activity of thrust-boring is efficient dewatering, and it was found that pumping water with high suspended solids content at the lifts required was too difficult for most standard site trench pumps. After experimentation with several different methods, a hydraulic submersible pump of the Flygt type was found to be the most serviceable. A thrust-boring equipment package for collector well construction should include a similar dewatering system as a standard component.
- (12) Although artificial ventilation was not found necessary at the Carmer Wood site, a portable air ducting system would be required in a tropical environment. A gas sensor should be included as a standard component of an equipment package.
- (13) The thrust-boring equipment used, together with its accessories, was transportable by pick-up/Landrover type utility vehicle and trailer. A thrust-boring equipment package does not require heavy lifting equipment for mobilisation purposes; the utility vehicle or trailer would be fitted with a travelling arm and light winch to facilitate equipment installation and sand removal at the well head, as no single item exceeds 125 kg in weight. The dewatering equipment and header tank would require a further utility vehicle or second trip.
- (14) The safety measures to be employed whilst working in an excavation are well documented elsewhere (e.g. UK Health and Safety legislation guidance notes), and should be followed closely when main shaft and collector construction are being carried out. As in any engineering operation involving the breakout from a closed shaft, particular attention should be paid to those procedures which involve operator safety, such as dewatering capacity, toxic/flammable gas detection, shaft ventilation, emergency evacuation and movement of accessories/materials into and out of the well. In this respect collector installation by thrust-boring methods is neither more nor less hazardous than analogous operations in an excavation or mine.

6. RECOMMENDATIONS

- (1) The project has developed and demonstrated a practical method to install small diameter horizontal radials to 20m+ in a fine-grained running sand aquifer using a simple pipe-jacking technique. This method is particularly suited to the construction of collector wells in aquifers which would be marginal for exploitation by borehole or shaft-only dugwell. The methodology has been taken to an advanced stage as part of the current research and development project, but has only been employed at one site in UK, albeit in a testing environment. There is a need now to test the method in pilot wells sunk in a range of aquifer conditions. Of particular interest would be the performance of the radials when emplaced in silty sands, and thrust-boring experience in coarser and more variable sands. It may be possible to thrust-bore in unconsolidated sands with a gravel or pebble content of a few percent, but this also remains to be tested.
- (2) It is recommended that the technique now be incorporated in a dugwell construction programme as a pilot project. A suitable programme would be one in which a significant number of wells need to be excavated in shallow unconsolidated sandy alluvium which either has only a thin saturated zone, or in which the hazard of upconing from an inferior quality lower horizon needs to be controlled.
- (3) As the thrust-boring screen-within-casing method complements the telescoped jetting rotary drilling technique already developed by the same project, it may be suitable to include both elements in a pilot

programme. Thrust-boring is likely to be suited mainly to loose fine sands of moderately low permeability while telescoped jetting can install larger diameter radials of correspondingly greater potential yield in coarser more permeable alluvium. In many rural water projects, the saturated thickness and grain size distribution of the underlying alluvial aquifer is not known with any precision before the construction programme begins, and so the completed dugwell shaft at different sites may be sunk in formations of radically different properties which would require different approaches to collector well construction.

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Appendix Table 1. Summary of Data Availability for Thrust-boring Episodes

Radial Number	Date	φ of Head (mm)	Type	Screen	Push Distance (m)	Measurements Taken			
						Time	Advance Pressure	Time	Withdrawal Pressure
L6	23/2/90	70	Push-rods	No	21.00	✓	✓	✓	x
L6	27/2 + 27/3/90	70	Push-rods	Outside	8.50	x	✓	x	x
L6		73	Casing	Inside	7.50	✓	✓	x	x
L5	16/5/90	73	Casing	Inside	5.25	x	✓	✓	x
L3	24/7/90	73	Push-rods	No	14.50	✓	✓	✓	x
L3	24/7/90	73	Casing	Inside	3.75	x	✓	x	x
L1	15/1/91	73	Push-rods	No	19.57	✓	✓	✓	x
L1	15/1/91	73	Casing	Inside	5.50	x	✓	x	x
U3	5/2/91	98	Casing	No	20.45	✓	✓	✓	✓
U3	5/2/91	98	Push-rods	No	20.30	✓	✓	✓	✓
U4	6/2/91	98	Push-rods	No	21.75	✓	✓	✓	✓
U4	6/2/91	98	Casing	No	20.00	✓	✓	✓	✓
U2	7/2/91	98	Casing	No	17.90	✓	✓	✓	✓
U2	7/2/91	98	Casing	No	19.90	✓	✓	✓	✓

Appendix Table 2. Budget Estimate: Equipment Package

Description

Thrust-boring equipment package to convert dug wells lined with concrete caisson-type rings into collector wells by screen-within-casing method. Excludes service vehicle (4WD utility/pickup).

<u>Item</u>	<u>Approx. Cost £ (11/91)</u>
Hydraulic thrust-borer c/w wellhead powerpack (e.g. PD-4 Powrmole and Power Stinger)	7,500
Boring tools (35 m sets of push-rods and HD temp. casing)	5,000
Other accessories (slings, tools, shuttering, etc.)	1,000
Site construction equipment (drill, portable generator, travelling arm, winch, clean water pump)	2,500
Safety/amenity equipment (blower ventilator, gas sensor, harness, ladder, etc.)	1,500
HD hydraulic dewatering pump c/w diesel powerpack (e.g. Flygt HB2102 3" ϕ and STI unit)	5,000
2250 l water bowser c/w semi-rigid hose and fittings	2,000
HD double-axle 2 tonne trailer	2,000
	<hr/>
Total	£26,500
	<hr/>

Figure 9A

Disposable end-cap, plastic anchor casing and first length of screen telescoped inside leading temporary casing.

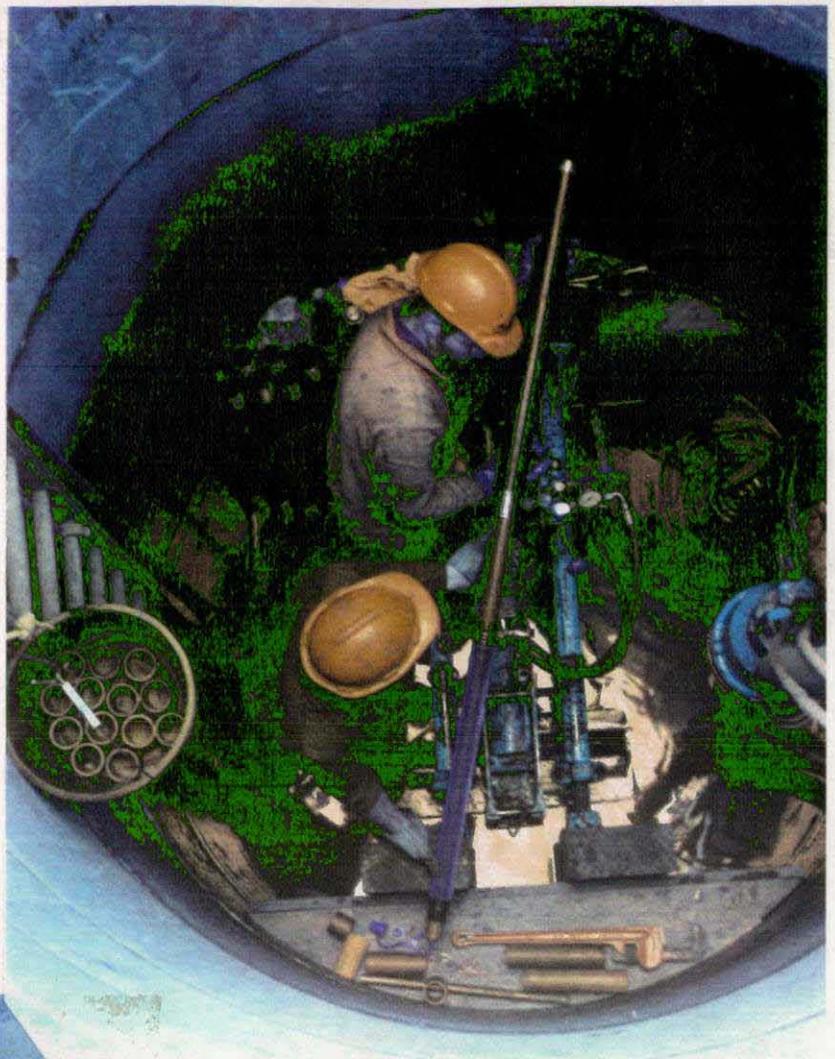


Figure 9B

Connecting subsequent lengths of inner screen and outer casing.

Figure 4A

Pilot push-head with 45 mm ND
push rods.

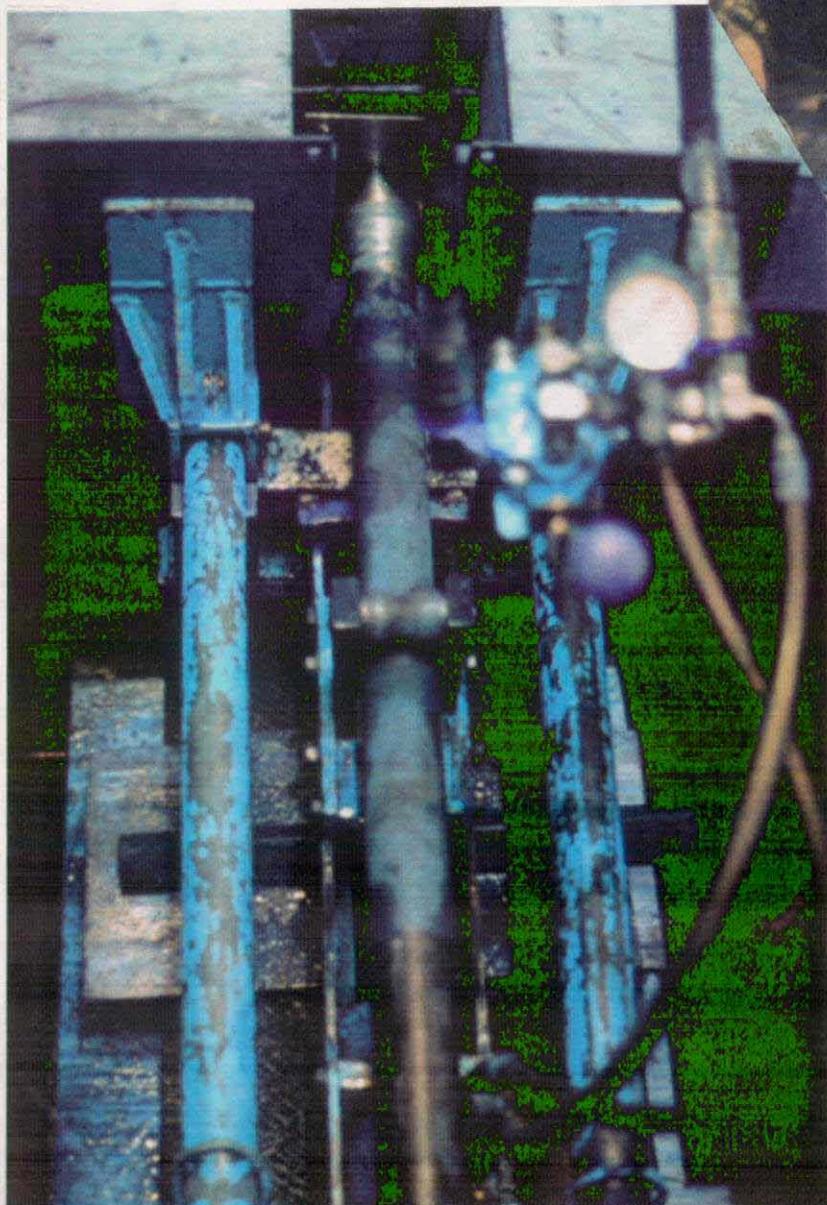


Figure 4B

Screen emplacement end-cap
with 73 mm OD steel casing.