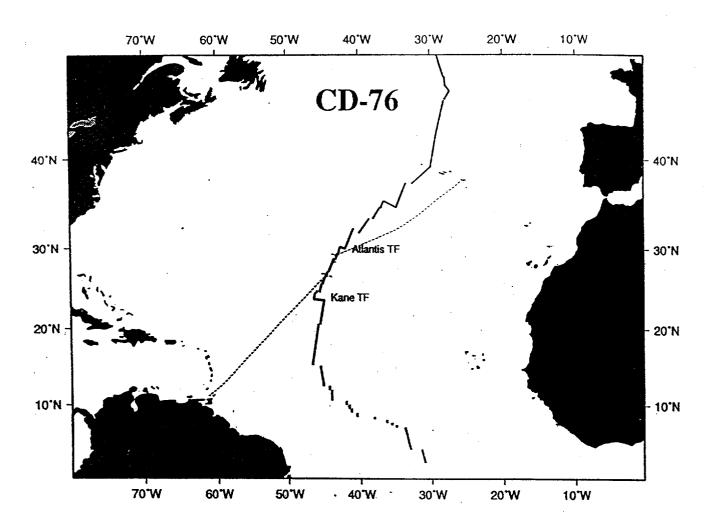


RRS Charles Darwin Cruise 76 04 Feb - 11 Mar 1993

Geological and geochemical investigation between 27°N and 30°N of the Kane-Atlantis segment; the Mid-Atlantic Ridge

Cruise Report No 236 1993



INSTITUTE OF OCEANOGRAPHIC SCIENCES DEACON LABORATORY CRUISE REPORT NO. 236

RRS CHARLES DARWIN CRUISE 76 04 FEB - 11 MAR 1993

Geological and geochemical investigation between 27°N and 30°N of the Kane-Atlantis segment; the Mid-Atlantic Ridge

Principal Scientist B J Murton

1993

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Signed:

Dr B.J.Murton



Eggshell seamount, at 27°15N, 43°35'W on the eastern side of the axial valley of the Mid-Atlantic Ridge. The seamount is approximately 1 km in diameter. It was imaged from the starboard side of IOSDL's TOBI deep towed sidescan sonar during the recent RRS Charles Darwin cruise (CD 76)

DOCUMENT DATA SHEET

AUTHOR MURTON, B J et al	PUBLICATION DATE 1993	
TITLE		
RRS Charles Darwin Cruise 76, 04 Feb-11 Mar 1993. Geological and geochemical investigation between 27°N and 30°N of the Kane-Atlantis segment; the Mid-Atlantic Ridge.		

REFERENCE

Institute of Oceanographic Sciences Deacon Laboratory, Cruise Report, No. 236, 34pp., figs & appendices. (Restricted circulation)

ABSTRACT

A survey during February and March 1993 along the slow spreading Mid Atlantic Ridge between 27-30°N assessed the regional extent of hydrothermal activity. The IOSDL Towed Ocean Bottom Instrument (TOBI) was used as the platform for sidescan sonar imagery, water column properties and real time submarine chemical analysis. The most dominant signals for high-temperature hydrothermal activity were found at 29°N, and were examined in detail using Dr. Gary Klinkhammer's Zero Angle Photo Spectrometer (ZAPS) sledge and IOSDL's Wide Angle Submarine Photograhy sledge (WASP). Both water column and bottom observations confirmed the presence of a high-temperature vent field, named here as the Broken Spur Vent Field.

KEYWORDS

BROKEN SPUR VENT FIELD

"CHARLES DARWIN" - cruise(1993)(76)
EGGSHELL SEAMOUNT
HYDROTHERMAL ACTIVITY
MID-ATLANTIC RIDGE
TOB
WASP

ZAPS SLED
ZERO ANGLE PHOTON SPECTROMETER

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1 KASP: THE KANE TO ATLANTIS SUPERSEGMENT PROJECT RRS CHARLES DARWIN CD76 CRUISE REPORT

(By Bramley J Murton)

Port of Spain, Trinidad - Ponta Delgada, Azores 4th February 1993 - 11th March 1993

1.1 Introduction

Hydrothermal activity on the worlds mid ocean ridge system plays a unique role in the physical, chemical and biological development of young oceanic crust. Hydrothermal vents make a major contribution to the geothermal and geochemical flux from the lithosphere to the global ocean; cooling the newly formed volcanic crust, affecting chemical exchange between the seafloor and water column, and often forming massive metalliferous sulphide deposits. They also support aphotic life forms that are uniquely associated with high-temperature hydrothermal activity (e.g. Corliss et al., 1979; Macdonald et al., 1980; Cann & Strens, 1982; Rona et al., 1983; Cann et al., 1985; Grassle, 1986; Tunnicliffe, 1991).

Unlike fast- to medium-spreading rate mid-ocean ridges, such as the East Pacific Rise where hydrothermal venting is relatively common (Haymon et al., 1991), on slow spreading ridges it remains more elusive. According to Klinkhammer et al (1985) and Charlou et al (1991) water column measurments taken from the axial region of the MAR between 11°N and 30°N have shown either Mn and/or CH4 enrichment, indicating that high-temperature hydrothermal activity is pervasive. However, until recently only three active vent sites on the have been verified: TAG (Trans-Atlantic Geotraverse) at 26°08'N (Rona et al., 1984, 1986), Snake Pit at 23°22'N (Detrick & Honnorez et al., 1986), and Lucky Strike at 37°17'N (Klinkhammer et al, 1992). The Broken Spur Vent Field, at 29°22'N, is only the fourth and most recent hydrothermal vent system to be located on the Mid Atlantic Ridge, discovered on the 4th of March this year during cruise CD76 of the RRS Charles Darwin.

Cruise CD76 of project KASP aimed to assess the extent of high-temperature hydrothermal activity along 300 km of the Kane to Atlantis Supersegment of the MAR. The work began with a systematic study of 4000^2 km of the axial valley, between 27°N and 30°N, using the IOSDL Towed Ocean Bottom Instrument (TOBI). This was used to assess the extent of chemical and physical effects of plume activity in the water column above the ridge crest, while imaging the tectonic and volcanic character of the axial valley. We then targetted the strongest plumes with deep-towed sledges carrying water physics sensors, chemical sensors and cameras in order to locate the active vent sites. Final work involved geological sampling in the vicinity of the vent site by dredging.

This was the first time that a combined systematic and real-time geophysics, geochemical and geological survey for hydrothermal activity has been made along the MAR. This integrated approach was an essential aspect of our experimental technique which aimed to collect data on the chemistry and physical distribution of plumes, and the volcanic and structural environment in which hydrothermal venting is active.

The scientific party on cruise CD76 comprised a multinational team from the UK, USA, Germany, France and Japan. In addition the work depended entirely on the expertise and superb seamanship of the officers and crew of the RRS *Charles Darwin*, from the Master to the Stewards. Their ability in maintaining an excellent working platform, and manouvering the vessel in unseasonally poor weather conditions over stations that required location precision to within a few tens of metres can not be overstated. And finally, but by no means least, the work could not have been attempted without the tenaceous persistence of the engeneering personnel of Research Vessel Services, Barry, who not only overcame many unforseen technical difficulties, but also cheerfully built and modified pieces of equipment at short notice.

Methodology

Unlike previous deployments of TOBI, when the vehicle has been towed at 500-800 m above the seafloor, during cruise CD76 we towed at an altitude of between 200m and 300 m. This was to attempt to pass through, sense and map the distribution of particulates and total concentration of dissolved manganese within hydrothermal plumes which elsewhere on the MAR and the EPR typically develop neutral buoyancy at 200 m to 400 m above their sources (Nelson and Forde 1991, Baker et al. 1985, Baker and Massoth 1987). Two survey tracks were made along the axial valley, a northerly pass over the western side and a southerly pass over the eastern side (Fig. 1.1) The base bathymetry charts used to navigate TOBI close to the bottom were 1:50,000 scale raw SeaBeam data from Purdy et al. (1990) contoured at a 25 m interval. Although low altitude towing exaggerated the acoustic shadowing effect of rugged topography on the sidescan sonographs, the vehicle survey lines were navigated so that the inner axial valley wall faults were at the edge of the 3 km swath range. Because the axial valley between the Kane and Atlantis fracture zones is on average only 9 km wide, we were able to image 4000 km² of the valley floor and inner valley walls including typically a 40% central overlap, while passing within a three to four kilometre range of any axial vents.

The second phase of the study involved station work with the ZAPS sledge concentrating on a 14 km length of the axial valley that coincided with the strongest plume signals observed during the TOBI survey. Stations were selected over elevated neovolcanic areas of the ridge that lay 200 m to 300 m below the base of the strongest plumes. Several seafloor sites were identified which proved to have strong transmissometer, nephelometer and total oxidisable manganese signals in the overlying water column. We spent several days homing in on the vent site by bracketing the search area and assessing the plume structure from up-, down- and towed- casts through the water column.

After locating the source of the strongest plume to within an area of $1~\rm km^2$, and deploying an Oceano acoustic transponder net of four beacons enclosing an area of $25~\rm km^2$, a near bottom (<10 m altitude) search strategy was adopted during which we sought temperature anomalies of several hundredths of a degree centigrade above an ambient background of $2.3~\rm ^{\circ}C$. Once these were found, an upcast through the water column was made with the ZAPS sledge to examine the plume structure and hence confirm the close proximity of the vent.

Having identified an area of a few hundred square metres within which the active vent was located, phase three of the study involved deploying the WASP at an altitude of between 8-15m above the bottom. This was followed by nine dredge deployments aimed at geologically sampling the vent and its vicinity.

1.2 Results

Regional extent of hydrothermal plumes

At least three areas along the Kane to Atlantis Supersegment near 27°N, 29°N, and 30°N, identified from the TOBI suvey, revealed transmissometer and/or ZAPS indications of plumes within 400 m of the bottom. Two plumes, near 27°N and 29°N, are located above axial neovolcanic ridges aligned along the western margin of the axial valley. They are not evident 4 km away on the eastern side of the valley at the same latitude, suggesting that the plumes are restricted to the western valley wall, probably by axial bottom currents. The plume at 30°N, principally defined by an increase in the concentration of total oxidisable manganese, is also located over a neovolcanic ridge that extends into the nodal deep basin at the western end of the Atlantis Transform Fault.

The strongest TOBI transmissometer and ZAPS indications among the three plume areas were found along a 14 km section of the Mid-Atlantic Ridge. This 14 km section, along the crest of a second order ridge segment centred on 27°05'N and aligned parallel to the western axial valley wall, contains several distinct hydrothermal plumes at depths of between 2650 to 2750 m (Fig 1.2). Within this section, the maximum plume intensity observed by the TOBI transmissometer corresponded to 0.2% light attenuation and was the first indication of what was later to become known as the Broken Spur Vent Field (BSVF).

Plume Structure at 29°N; the Broken Spur Vent Field

A total of 14 vertical up and down casts with the ZAPS sledge, in an area of 30 km² centred on 29°N, revealed a complex vertical and horizontal plume structure (Fig. 1.3). Although the plumes are vertically stable with time, remaining within 5% of the water depth, their strength is variable. For example, at station 1 (6 km from the BSVF) the plume caused about 0.03% attenuation of light transmission when first measured but it had decreased to 0.005% attenuation of light transmission by 30 hours later. Elsewhere, we observed the reverse, with an increase in plume strength over a similar time period. From the shape of the hydrothermal plume, 10 km long 3 km wide and elongated parallel to the axial valley we infer the presence of diurnal bidirectional bottom currents probably flowing parallel to the ridge axis. We attribute these currents to a tidal origin.

The Broken Spur site contains a composite vertical plume structure comprising both relatively thick (>100 m) and thin (<50 m) plumes. Two ~50 m thick plumes, with sharp nephel maxima, occur at 2700 m and 2825 m. Their nephel profiles are closely matched by their transmissometer profiles. A thicker plume occurs between 2810 m and 2975 m and has a broad and symmetric nephelometry profile, with a sharp decrease in nephels at the base. In contrast, its transmissometry profile is asymetric with a sharp maximum in attenuation and rapid increase in transmission at the base. The temperature profile through the depth range enclosing the three plumes is almost isothermal suggesting that this near bottom water mass is well mixed.

These data are evidence of several neutrally buoyant plumes that emerged from the seafloor with different potential temperatures which suggests the presence of more than one active vent. The two thin plumes with sharp nephel and transmissometer profiles are probably advected features from a distal source. The thicker plume with its broad nephel and transmissometer profile is probably a convected feature from a proximal source. This interpretation is supported by the increase in the nephelometer to transmissometer signal ratio for the base of the thicker plume indicating an increase in the particle diameter. Larger diameter particles, from Stokes Law, will settle faster than smaller diameter ones and are thus likely to be found at the base of a young non-turbulent neutrally-buoyant plume and absent altogether from an old non-turbulent neutrally-buoyant plume. If the plume was bouyant then it is likely that turbulent mixing would prevent settling of the particulate load.

Following the location of the strongest plume, at a depth of 2700 m, the ZAPS sledge was deployed in a near bottom mode to search for perturbations in potential temperature caused by high-temperature venting. Several traverses of 1-2 km long were made along the crest of an axial volcanic ridge at an altitude of 8-10 m and a depth of 3050 m. A number of positive temperature anomalies of up to 0.3° C were encountered over a horizontal distance of 200 m. An upcast through the water column was made at the location of the temperature anomalies, and high nephel counts were encountered at 50 m above the bottom, at a depth of 3000 m. This is the deepest level at which a plume had been encountered, and we believe it to represent a buoyant column located within several tens of metres from an active vent.

During subsequent photography in the area of the temperature anomalies with the WASP sledge, towed at an altitude of 10-15 m above the seafloor and a depth of 3035 m, the buoyant plume column was again observed. Shortly afterwards the WASP sledge ran in to a sulphide chimney, recovering fragments of material which were subsequently collected on the vehicle's return to the surface. The best position of this active vent in the Broken Spur Vent Field, determined from the acoustic navigation net, is 29°10.15'N, 43°10.28W.

Geological setting

The Broken Spur Vent Field lies within the neovolcanic zone of a second order segment at the northern end of the first order supersegment between the Kane and Atlantis fracture zones on the Mid Atlantic Ridge. This second order segment is one of the bathymetrically shallowest in the supersegment, and has a periclinal shape (Purdy et al, 1990) with a marked mantle Bouguer gravity low at its centre (Lin et al, 1990).

Variations in the acoustic texture and backscatter intensity of the TOBI sidescan sonar images allowed us to map the extent of the neovolcanic and neotectonic zones within

the axial valley, as well as distinguishing variations in the volcanology. On TOBI images the neovolcanic zone is defined as strongly backscattering hummocky sediment free terrain that is essentially devoid of faults and fissures resolvable by the sonar. At 29°N the neovolcanic zone lies adjacent to the western valley wall where it forms an elevated axial-parallel volcanic ridge up to 20 km long, 5 km wide and 200 m high (Fig. 1.4). This asymetric position of the neovolcanic zone is common in the Kane to Atlantis Supersegment, which also has an asymetric rift valley structure with the highest fault scarps forming the western valley walls. The neotectonic zone, defined on TOBI images as densely fissured and faulted terrain with fissures or gjas up to 30 m deep and areas of smooth low backscatter intensity indicating patchy sediment cover, forms the eastern valley floor at 29°N, as generally elsewhere along the Kane to Atlantis Supersegment.

Both TOBI and WASP imagery show that the Broken Spur Vent Field is located at the crest of an axial volcanic ridge, adjacent to an axial summit caldera (Fig. 1.5). The axial summit caldera is a graben-like structure, 1.2 km long and 35-60 m wide. Acoustic altimetry data from WASP indicate that the axial summit caldera, where it is adjacent to the Broken Spur Vent Field, is 30 m deep by 30 m wide. The axial summit caldera has a single vertical wall on its western side, and a stepped wall on its eastern side.

Although relatively common on the fast spreading East Pacific Rise (Lonsdale,1977; Haymon, et al. 1991), axial summit caldera have not been reported from the Mid Atlantic Ridge before now. On the East Pacific Rise, where they are associated with the most volcanically active parts of the ridge crest and ascribed to subsidence of shallow magma chambers, hydrothermalism occurs within 20 m of the caldera margins (Haymon op cit.). Therefore, it is perhaps not surprising that there should be hydrothermal activity adjacent to an axial summit caldera at the Broken Spur site. By comparison with the EPR, the presence of the axial summit caldera adjacent to the Broken Spur site suggests that the axial volcanic ridge at this location currently hosts, or has recently been host to a shallow magma chamber.

This interpretation is supported by photographs of sediment free pillow and sheet-flow lavas and the recovery of unaltered glassy basalt from the site. Dredge deployments at the vent site recovered a diverse range of basalt compositions. These include some fresh, unsedimented glassy aphyric basaltic sheet-flows that are young (probably less than several hundred years), as well as plagioclase phyric (~30% by volume) glassy basaltic pillow lavas. The presence of fresh neovolcanic sheet flows indicates recent eruptive activity and the 30% plagioclase phyric basalts demonstrates that there is, or recently has been, a magma chamber capable of supporting fractional crystallisation in the vicinity of the vent.

Sulphide samples recovered from the Broken Spur Vent Field have been analysed by X-Ray diffraction, X-Ray fluorescence, reflected light microscopy and scanning electron microscopy. Results reveal the samples comprise mainly sphalerite, pyrite, chalcopyrite, marcasite, phyrrotite and wurtzite, indicative of precipitation temperatures of 250-300 °C. The coexistence of both phyrrotite and marcasite, which together are readily oxidised on the seafloor (Haymon et al. 1991), is evidence that the vent site is very young and almost certainly active when we sampled it.

WASP photographs of the ocean floor from within 25 m of the vent reveal brecciated angular rubble, probably of weathered iron and copper sulphides, pillow lavas and a dusting of iron and manganese oxide and hydroxide sediment from the vent. Photographs also reveal abundant particulate material in the water column over the vent itself.

Biological Activity

Several photographs, that coincide in time with the encounter with the buoyant plume column and chimney, reveal abundant biota including what appears to be a vent ecosystem containing a number of individual worm-like creatures (probably semi-recumbent polychetea, Paul Dando pers. comm.) attached to a substrait of talus which is covered in places with a mat of fibrous material of possibly the bacterial origin. Also photographed were white squat lobsters (Munidopsis, Tony Rice, pers. comm.), large bottom grazing fish and some anemones. The vent ecosystem imaged resembles the biology found at the periphery of the other Mid Atlantic Ridge vents such as the TAG hydrothermal field (Grassle 1986, Tunnicliffe 1991).

1.3 Discussion and Conclusions

The success of using real-time geophysics, geochemical and water-column physics sensors in regional surveys of mid-ocean ridges for hydrothermal plumes has been demonstrated by the discovery of the Broken Spur Vent Field at 29°N on the Mid-Atlantic Ridge. However, it remains to be verified whether the other plumes observed at 27°N and 30°N are also of hydrothermal origin.

The regional extent of the plume at 29°N, being over 14 km long, and at least 3 km wide, and its vertical and horizontal complexity indicate that the area hosts a vent field rather than just a single active vent site. The vent that was sampled at 29°10.15′N, 43°10.28W is probably just one of a number of vents, each exhaling fluids with different potential temperatures. The two thin plumes at the Broken Spur site with sharp nephel and transmissometer profiles are probably advected features from a distal source. The thicker plume with its broad nephel and transmissometer profile is probably a convected feature from a proximal source. This interpretation is supported by the increase in the nephelometer to transmissometer signal ratio at the base of the thicker plume, indicating an increase in the partical diameter. Because larger diameter particles settle faster than smaller diameter ones, they are likely to be present at the base of a young non-turbulent neutrally-buoyant plume and absent from an old non-turbulent neutrally-buoyant plume. If the plume was bouyant then turbulent mixing would prevent settling of the particulate load.

We suggest the diurnal fluctuations in the plume strength and its ridge-axis parallel structure are caused by tidal sloshing parallel to the trend of the axial valley of the near-bottom water mass.

The geological structure of the ridge axis along the Kane to Atlantis Supersegment influences the location and dispersion of the hydrothermal plumes. At 29°N the Mid-Atlantic Ridge is assymmetric with the highest axial valley walls on its western side, at the base of which is a neovolcanic ridge. The hydrothermal plume from the Broken Spur Vent Field is localised in the vicinity of a neovolcanic ridge where it rises 200-300 m above the seafloor is elongated parallel to the western axial valley wall.

Fresh unsedimented glassy lavas, porphyritic lavas and an axial summit caldera along the crest of the volcanic ridge are evidence of recent eruptions and a shallow magma chamber. We suggest that the latent heat of crystallisation and the residual heat of the magma body drive the hydrothermal circulation at Broken Spur. We also note the periclinal shape, shallow depth and negative Bouger gravity anomaly at the centre of the second order ridge segment in which the Broken Spur Vent Field is located, and suggest that this is probably the most magmatically active part of the Kane to Atlantis Supersegment, fed by a prominant upwelling asthenospheric plume, and hence has the highest energy flux.

The Kane to Atlantis Supersegment is subdivided into closed basins (Purdy et al., 1990) which contrast with the crestal shape of the East Pacific Rise. Unlike hydrothermal plumes, which easily disperse on the East Pacific Rise, it is likely that the basins along the Supersegment trap the plumes and restrict their chemical and biological dispersal.

Figure Captions

- Fig. 1.1 Ship's track showing the TOBI survey along the Mid Atlantic Ridge between 27°N and 30°N.
- Fig. 1.2 TOBI transmissometer (heavy line) and depth data (thin line) for approximately 14 km along the western side of the axis of the MAR, centred on 29°05'N. The plume signals from the Broken Spur Hydrothermal Field give the largest shifts in light attenuation at around 29°08'N and a depth of about 2600 m. Other transmissometer signals at 29°02'N and 29°05'N, indicate that hydrothermal activity is widespread at the Broken Spur Vent Field.
- Fig. 1.3 Contoured nephel density map of the extent of the Broken Spur plume from a combination of ZAPS sledge and TOBI vertical and towed profiles through the water column. Contours are in Formazin Turbidity Units (FTU \times 10⁴), TOBI transmissometer data for the eastern side of the area gave background values (equivalent to 40 FTUs).

- Fig. 1.4 Gridded bathymetry of the Broken Spur Ridge from *HYDROSWEEP* multinarrow beam sonar system (courtesy of J-Christophe Sempere).
- Fig. 1.5 TOBI sidesscan sonar image, 2 km x 2 km, of the Broken Spur Vent Field. The image is similar to a monochrome photograph with bright areas being strong echos and dark areas being weak echoes and shadows. Broken Spur Vent Site (BSVS) lies at the top of an axial volcanic ridge and adjacent to an axial summit graben (ASC) running along the length of the ridge.

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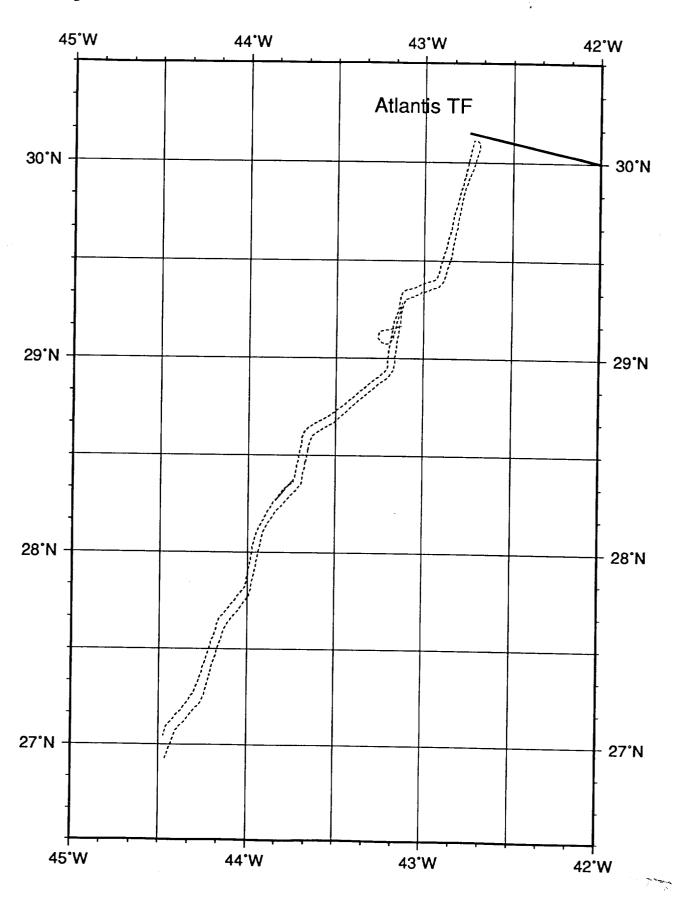
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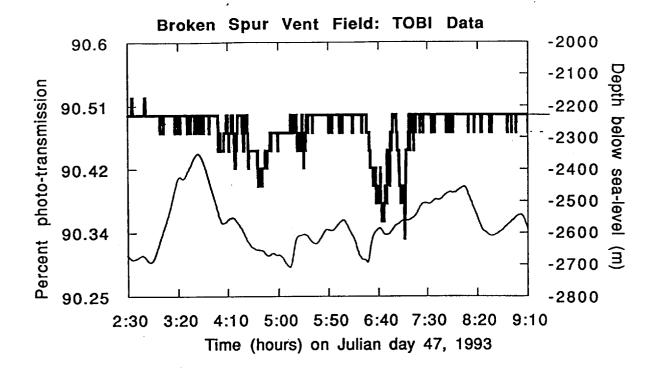
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CD-76 TOBI's Track

Fig 1.1





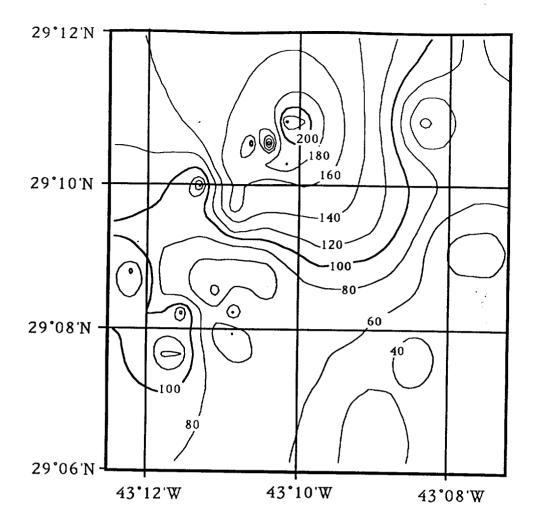
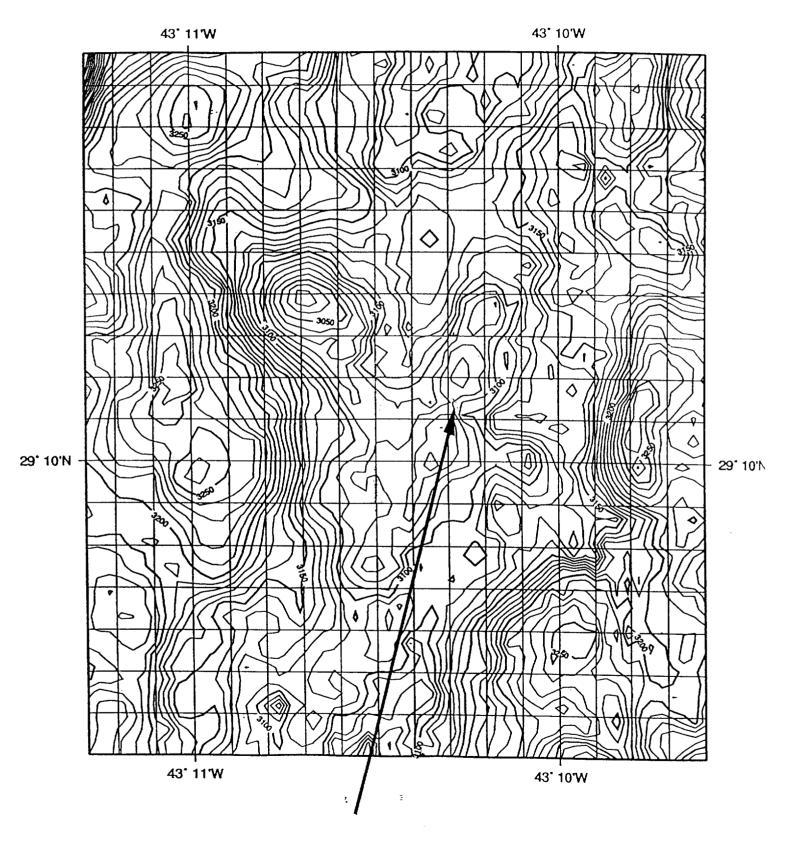


Fig 1.3

Gridded Bathymetry of the Broken Spur Ridge



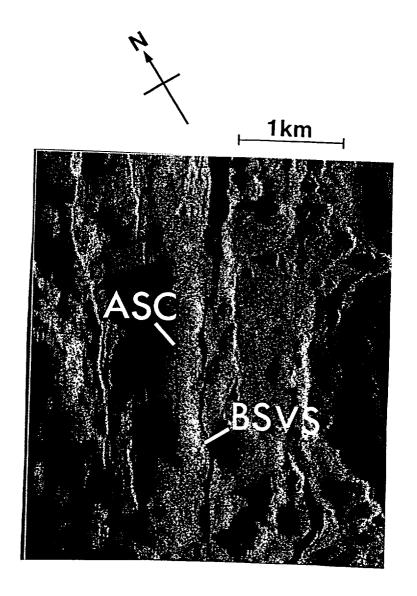


Fig 1.5

2 CRUISE CD76 INSTRUMENTATION REPORTS

2.1 TOBI Instrumentation

(by Nick Millard and Ian Rouse)

2.1.1 Narrative

The main objective for the TOBI system was to provide a sidescan survey of the MAR axis between 27°N and 30°N. The vehicle was to be "flown" at a low altitude (where possible below 300 metres) to give the plume detecting sensors the best chance to see a signal. In addition to the usual thermistor probe and transmissometer, there were two sensors fitted especially for the cruise. These were a nephelometer configured to measure backscatter and the ZAPS probe to measure disolved manganese. The plan was to make one run of about 10 days, running first north up the eastern side of the ridge axis followed by an overlapping southerly line down the western side.

In the event the survey was completed with three separate runs. The first took three attempts to get under way due to instrument problems and lasted two days before recovery to repair a short circuit down the towing cable. The second run provided most of the data, lasting 7 days, and being recovered at the southern end of the survey at 27°N. The third, 18 hour, run was deemed necessary to fully image the Broken Spur Vent Field (Fig. 1.5).

Day 041, the first day of TOBI operations, was warm and calm during which a number of launch and recovery operations took place. After 11 hours the ZAPS instrument was removed from the vehicle for repairs. The weather remained good for Day 042 when TOBI (with ZAPS) was again launched. Although ZAPS failed again, the systems were lowered to the seafloor to establish the seriousness of the acoustic interference, which had become evident on the sidescan records, from both the nephelometer and ZAPS. Both these instruments produce an electronic 'click' when their xenon flash tubes fire which was picked up by the sonar transducers. The 5.5Hz. signal from the nephelometer proved much more of a problem than the 25Hz. ZAPS noise. It was decided that the nephelometer had to be removed from TOBI to achieve acceptable sidescan data and the vehicle was thus recovered.

In the early hours of day 043 TOBI was again launched for Run 1, which lasted for 2 days. This was despite the fact that 12 hours after launching, with the vehicle flying at 350 metres, a pinnacle of rock, seen neither on the Simrad precision echosounder nor on the swath bathymetry charts, rose more than 350 metres in less than 8 minutes. Hitting it was inevitable but luckily the collision must have been close to its peak as contact time was short. All instruments on the vehicle continued working and no excessive loads were observed on the wire and so the survey resumed, thirty-six hours later the system failed with a short circuit appearing on the cable. On recovery, this was traced to a damaged umbilical cable which had to be replaced. During this run the pressure gauge first gave erratic readings and eventually failed. It was found to have leaked and also had to be replaced. The chemical cartridge on ZAPS was recharged during this time. Damage caused by the collision was observed in the form of scores on the depressor weight and swivel unit. There was also slight damage to (and a small rock sample embedded in) the lower bumper of TOBI.

Day 046 saw the launch for Run 2 which went smoothly with all systems apparently working. Persistently strong winds made life difficult for the officers on the bridge and the low altitude flying continued to tax the TOBI watchkeepers. This part of the Mid Atlantic Ridge was found to have many pinnacles which did not show on echosoundings made from the surface. This run continued for 7 days until the end of the planned survey.

The short 18 hour TOBI Run 3 commenced on Day 063. ZAPS was not fitted on this occasion and a higher altitude (400-500 m) survey of the vent field was carried out. The area was insonified from two directions. An acoustic navigation beacon was attached to the vehicle for this run but proved to be of little use as both the ship and TOBI were not inside the network at the same time.

During TOBI Run 2 there were inexplicable variations in the gain observed on the starboard sidescan during both lowering and recovery. At depth the gain settled to a value

only a little less than that of the port side. It was also felt that the resolution on this starboard side was also not as good as it should have been and a faulty sonar array section was suspected. Before Run 3 started an open circuit connector was replaced on the centre section of the starboard array. This action restored the full resolution and gain at depth but there is still a pressure dependent problem affecting the starboard gain that has to be resolved.

During TOBI deployments the vehicle position was estimated from a knowledge of its depth, the amount of wire paid out and its altitude. These positions were used to produce replays of the sidescan data at a scale of 1:50,000, corrected for the vehicle speed over the ground and for geometric slant range. A recently developed bend correcting routine was also used to produce curved track replays for a total of 21 bends so that more accurate mosaics could be produced. Selected areas were replayed at a large scale in which every data point in each sweep was displayed. Although not corrected for ship speed these images gave impressive results with a great improvement in the observable detail.

The TOBI data for the cruise is contained on 10 magneto-opical discs making a total of about 5.6 G bytes of data.

2.1.2 TOBI Instrumentation Configuration

TOBI is IOSDL's deep-towed instrumented sonar platform. The system consists of a neutrally buoyant underwater vehicle towed from the ship on a 10km long conducting cable via a 600kg depressor weight and a 200m umbilical. The shipboard system consists of data logging and display, system control and data reply. The vehicle's main scientific instruments are a double-sided 30kHz sidescan sonar with a swath width of 6km and a 7.5kHz sub-bottom profiler capable of penetrating up to 60m of sediment. Other scientific instruments used on the cruise were a tri-axis flux-gate magnetometer, temperature probe, transmissometer, ZAPS manganese sniffer and a nephelometer.

The vehicle is designed to be operated at depths of up to 6000m. On this trip the profiler was used mainly as an altimeter for the vehicle as there was little or no sedimentation in the area under study. The data logging/display system uses an IBM PS/2 model 80 computer and stores the sonar and instrument data on 600 M byte magneto-optical disks. After formatting, the disks are capable of storing 800 minutes of data on each side. Sidescan data were displayed on a video monitor corrected for slant range distortion in real time and printed out using a Raytheon TDU650 thermal recorder. Profiler data were displayed on an EPC 3200 line scan recorder. Two channels of instrument data (ZAPS and transmissometer) were displayed on a chart recorder. The replay system uses a similar IBM computer and produces scaled and corrected sidescan, profiler and instrument data.

2.1.3 TOBI System Specifications (CD76)

Sonar Instruments

Sonar system	Transducer Frequency	Beam Angles	Range
Port Sidescan: Ceramic stack motors driving face plate.	32.15kHz	0.80 x 40°	3km
Stbd Sidescan: Ditto	30.37kHz	0.80 x 40°	3km
Profiler: 7 x ceramic rings.	7.5kHz	25° cone 60m	2km

Other Scientific Sensors:

Instrument	Output	Range	Digitization	
Tri-axis fluxgate	+/- 5V	+/- 40960n Tesla	3 x 12bit +polarity magnetometer	
Temperature +polarity probe	+/- 5V	1 - 22 °C	12bit	
Transmissometer	0 - 5V	0 - 100%	12bit	
ZAPS	0 - 5V		12bit	
Nephelometer	0 - 5V		8bit	
Vehicle Instruments:				
Pitch Roll Depth (Pressure) Compass Impeller log (Speed)	0 - 5V 0 - 5V 1Hz/m Gray code 0 - 5V	+/- 20 degrees +/- 20 degrees ≤6000m 360 degrees 0 - 2. 5knts	8bit 8bit 16bit 10bit 8bit	

2.1.4 Major Computer Programmes Used

Programme Name and description:

TOBILOG. EXE

Logs all TOBI data, displays sidescan data on video monitor and thermal printer hard copy and outputs analogue signals to chart recorder.

ERASDISC. EXE

Reads TOBI sidescan data from magneto-optical discs and produces a scaled and slant range corrected file on hard disc.

DISSCRAY. EXE

Reads scaled and slant range corrected sidescan files and outputs data to Raytheon thermal recorder.

BEND. EXE

Reads selected TOBI sidescan data from magneto-optical discs and scales, corrects and fits data to a predetermined curve storing the result on hard disc.

DISCBRAY. EXE

Reads scaled, corrected and curve fitted sidescan files and outputs data to Raytheon thermal recorder.

REPTST76. EXE

Reads instrument data from magneto-optical disc and displays on video monitor in numerical form.

2.2 ZAPS Instrument Deployments and ZAPS Sled Operations (by Gary Klinkhammer)

2.2.1 Introduction

Venting of hot, chemically-rich, buoyant fluids from mid-ocean ridge spreading centres produces hydrothermal plumes with thermal, physical, and chemical signatures quite different from background deep sea water. These plumes rise several hundred meters above the sea floor where they reach neutral buoyancy and begin to spread laterally. The marine geochemistry group at Oregon State University has designed and constructed an instrument package, the ZAPS sled, that carries state-of-the-art, in situ sensors capable of

detecting such plumes. This vehicle was used as a survey tool in the search for hydrothermal activity, in an active segment of the Mid Atlantic Ridge, identified during the TOBI long-line survey. This work led to the identification of an active hydrothermal vent field within this segment.

2.2.2 The ZAPS Sled Frame

The ZAPS Sled towed vehicle (Fig. 2.1) is an open framework of 5 cm Type 316 SS pipe. The ZAPS Sled stands 90 cm wide, 90 cm tall, and is 210 cm long with a tapered bow 86 cm wide. This frame hangs from a standard conducting cable by an adjustable 3-point chain bridle to ensure that the sled attains a forward facing, level attitude in the water. The two vertical sides of the sled aft section have 0.95 cm thick polycarbonate panels attached to serve as rudder vanes and give structural hydrodynamic stability while being towed at 1-2 knots through the water. On Cruise CD76 the sled was deployed from the starboard hydrographic A-frame both vertically and during slow "drift" surveys. The weight of the sled in air is about 350 kg.

2.2.3 ZAPS Sled Instrumentation

The central instrument on board the ZAPS Sled is a Sea-Bird 9/11 plus CTD sampling at 24 Hz, fitted with modular temperature and conductivity sensors and a Paroscientific Digiquartz Pressure Sensor. Four analog instruments are interfaced through the Sea-Bird underwater unit. These include:

- (l) A SeaTech Transmissometer to measure 660 nm wavelength beam transmission through a $25\ \mathrm{cm}$ path length.
- (2) A Chelsea Aquatracka Mk III Fluorometer operating as a nephelometer at a wavelength of 420 nm to measure scattered light at 90 degrees to the incident light beam.
- (3) A Zero Angle Photon Spectrophotometer (ZAPS) that uses solid-state chemistry with analog fluorescence to measure the concentration of total oxidizable manganese (TOM).
- (4) A SIMRAD Mesotech Systems Model 807 Echo Sounder / Altimeter to determine the height of the sled off the bottom within a 500 meter range.

The ZAPS Sled also carries a General Oceanics Rosette array interfaced to the CTD and capable of holding 12 5-litre Niskin sample bottles for collecting sea water samples for laboratory measurements of such parameters as methane, helium, and trace metals. The bottles are tripped by signals from the CTD deck unit at any time without interrupting the data steam.

In addition the sled can be fitted with an acoustic transponder that is interrogated with a transducer at the surface to determine the direct slant range and computed horizontal range to the sled. On CD Cruise 76 a pinger was fit to the sled to aid in near bottom surveys and a relay transponder was used to position the sled within an Oceano transponder net.

2.2.4 CTD Data Acquisition and SLED Navigational System

The ZAPS sled is powered through a Sea-Bird deck unit that also receives frequencies from the underwater unit and sends converted data via an RS232 port to a Silicon Valley 486 computer that supports an Introl optical disk. Raw CTD data files are stored on the optical disk and echoed to a second, identical computer. This second, navigational computer also receives ship positions from a Garmin MRN 100 GPS Satellite Receiver and imports this data into a proprietary SLED navigational programme developed at Oregon State University. This navigational programme plots in real time the ship's position and trackline and the computed horizontal range and position of the sled as projected onto the trackline of the ship. The SLED navigational programme also shows a diagrammatic cross-sectional view of the ship, the towed vehicle, and a calculated "bottom depth" derived from the sum of the CTD pressure data and the concurrent altimeter data (height above bottom) from the package. This calculated bottom depth beneath the sled can then be compared to the depth records and/or bathymetric maps of the area to help in locating the sled with

respect to bottom features or obstacles. The ZAPS Sled was not used for towing during CD76. Much of the positioning of the package was accomplished by monitoring the trace from the IOS pinger using the "waterfall display".

2.2.5 Field Performance

ZAPS on TOBI

ZAPS was on the TOBI vehicle during four deployments. The instrument failed to respond during the first deployment. It turned out that in the process of closing up the pressure case after calibration the wire supplying trigger voltage to the flash tube was pulled loose from its connector. ZAPS signals during the second lowering were erratic and eventually died. Upon recovery it was discovered that there was a problem with the main wiring harness on the signal board. Unfortunately the signal board was exposed to sea water while attempting to repair the instrument on the deck. The instrument was then removed from TOBI and the backup signal board installed. After the faulty connector was resoldered the instrument seemed to respond normally. Reasonable signals were transmitted from the ZAPS instrument during the first successful run but the umbilical cable for the vehicle failed and the run was aborted after 2 days.

ZAPS was deployed with TOBI during the second run without further electronic modification but the chemical cartridge was recharged during this time. The second and longest TOBI run lasted from 16:30 (local time) on the 14th of Feb. until 18:30 on 22 Feb. Transmissometer data from this tow were used to identify the hydrothermally active area that was explored with the ZAPS Sled, WASP Sled and dredges in the second part of the cruise.

ZAPS data from this second TOBI run was affected by an apparent artifact produced by moving the vehicle rapidly through the water column. The exact nature and extent of this problem will require a further analysis of the data set. Discounting this artifact there was not a general correlation between the signal from ZAPS and readings from the tansmissometer although anomalies from these instruments did sometimes overlap. This result is expected since ZAPS measures dissolved manganese and light transmission indicates particulates in the water column. Alternatively, if one discounts any part of the ZAPS record that may have been affected by the motion of the vehicle then two deep water features remain: a large signal near the Western Atlantis Ridge Transform Intersection and a gradual, systematic, decrease of the signal during the tow. Unfortunately time did not allow for a further investigation of the Western RTI ZAPS anomaly. The background deep water signal decreased from about 1.9 V at the beginning of the tow to about 1.6 V at the end. At least some of this decrease resulted from reagent bleed from the cartridge with time. In a way this was a reassuring result as it suggests that the probe was active during the entire deployment. It was possible to verify this result at the end of the tow when the ZAPS signal produced the TOM (total oxidizable manganese) profile shown in Fig 2.2. This profile is consistent with the structure of the water column in this area and our general understanding of the geochemistry of manganese in the oceans.

ZAPS on the ZAPS Sled

After the second TOBI run, ZAPS was recalibrated and we began a detailed investigation of the Broken Spur Vent Field. This work began with ZAPS being deployed on the ZAPS Sled but it was obvious from the first lowering that there were serious problems with the instrument. The signal was noisy and erratic; eventually the probe stopped working altogether. It was then determined that the second electronics board had been damaged beyond repair by water penetration during the process of recalibration. It was not possible to use the ZAPS probe for the remainder of the leg.

Altogether the ZAPS Sled was deployed 14 times in an area 5.5 km along strike and 3.7 km across strike. The hydrothermally active ridge was identified during the 12th of these lowerings. The downcast designations and their locations before drifting are indicated in the following table.

CD76SD01	29° 08.20' N; 43° 10.80' W	CD76SD08	29° 09.30' N; 43° 10.91' W
CD76SD02	29° 08.15' N; 43° 11.52' W	CD76SD09	29° 08.15' N; 43° 11.25' W
CD76SD03	29° 08.58' N; 43° 12.30' W	CD76SD10	29° 08.60' N; 43° 10.75' W
CD76SD04	29° 09.50' N; 43° 10.90' W	CD76SD11	29° 07.80' N; 43° 11.00' W
CD76SD05	29° 10.33′ N; 43° 11.00′ W	CD76SD12	29° 10.30' N; 43° 10.40' W
CD76SD06	29° 08.40' N; 43° 11.20' W	CD76SD13	29° 10.65' N; 43° 10.16' W
CD76SD07	29° 09.02' N; 43° 10.91' W	CD76SD14	29° 10.21' N; 43° 10.32' W

Except for the ZAPS probe, the equipment on the sled worked flawlessly during these deployments. Fig. 2.3 is an example of the light transmission and nephel profiles that were used to locate the hydrothermal site discovered during CD76.

2.2.6 ZAPS Navigational System

The graphical display of the ship's position and track presented by the SLED Program turned out to be a valuable resource during all CD76 operations. Positions from this display were used for scientific logs during underway watches and TOBI tows. The Garmin antenna and receiver proved to be extremely reliable and offered accurate positions 98% of the time. The capability of accurately recording ship's positions and the locations of events during ZAPS Sled lowerings, WASP deployments, and dredges proved to be a valuable compliment to navigational information logged on the bridge. Fig. 2.4 is a screen dump from WASP 04, the deployment that encountered a hydrothernmal chimney. This information helped us pinpoint the location of at least one vent site and gave us a better chance of sampling sulfides during subsequent dredging operations.

2.3 The WASP System (by David Edge)

2.3.1 Narrative

Despite the late funding for the development of this system the WASP vehicle was deployed on 5 occasions resulting in over 1000 seabed photographs.

A deployment early in the cruise was essential to test the system, since the anticipated 11 day TOBI survey would allow time to correct any problems before the WASP system was needed operationally. On Julian Day 039 the WASP system was tested resulting in 32 seabed photographs. Problems with the acoustic telemeter were corrected and subsequent 2nd, 3rd and 4th deployments were successful.

Before the 3rd WASP survey, a transmissometer was interfaced to the telemeter to assist in locating an active hydrothermal vent. To ensure a change in transmissometer output could be positively detected, the acoustic telemeter was configured to transmit an expanded scale of between 4 and 5V. During the 3rd WASP survey, the transmissometer signal remained steady.

During the 4th WASP survey a strong transmissometer signal indicated a particulate plume near the seafloor. The computer waterfall display of acoustic telemetry data showed a transmissometer signal variation of at least 0.5 V (i.e. a 20% reduction in light transmission). This information was correlated with the sonar altimeter which revealed a seabed feature some 15m high and adjacent to a graben 30m deep and approx 30m wide. On recovery the vehicle was found to have sulphide deposits encrusted on its frame. Approx 400 seabed photographs were recorded during this survey. During the 5th WASP survey, the transmissometer reading remained steady.

2.3.2 WASP Developments

Several key components were used on WASP for the first time during cruise CD76. The IOSDL acoustic telemeter had been redeveloped to include a microprocessor for programming of control and data logging functions and to simplify sensor interfacing. Communication to the unit to set time, enter calibration coefficients, set camera interval and down-load logged data has been achieved via an RS232 deck cable connected to a PC.

A Mesotech 200kHz acoustic altimeter was interfaced to the acoustic telemeter via an RS232 link, and provided accurate seabed detection from a range of up to 200m above the seafloor.

The IOSDL oil filled pressure balanced battery packs, used for the first time to power the WASP instrument, were designed to take advantage of relatively low-cost, gel-type automobile batteries. These worked well and compare favourably both in performance and price with the alternative commercially available electrical sources.

During the cruise, software was written to utilise the telemeter processor card facilities. The IOSDL pulse position acoustic transmission technique can now be accomplished using the processor card timers. This makes redundant a counter/timer card resulting in a significant power saving of 2 watts. Software was also written for the PC to improve set-up and data acquisition facilities. The telemeter-logged information can now be down-loaded directly into a Microsoft Excel spreadsheet.

2.3.3 Photographic Processing

Processing of film was limited to topping, tailing and developing of negatives. The remaining film had to be processed and printed at IOSDL.

2.3.4 Waterfall Display

Once again, this cruise proved that the IOSDL computer "waterfall display" was better than the Simrad Echo Sounder for monitoring deployed instrumentation. It was often used for monitoring the altitude of the rock dredge and ZAPS sled in addition to WASP.

2.3.5 Recommendations

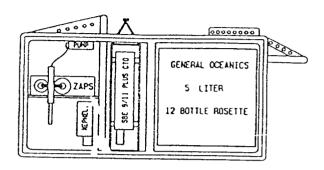
Operating the WASP system in areas of rough topography, trying to image specific hydrothermal targets, and processing photographic film indicated requirements for:-

- (a) Improved vehicle framework to withstand impacts and protect instrumentation from seabed collisions.
- (b) Addition of a sensor suite to include transmissometer, CTD, compass, roll, yaw and pitch
- (c) Real time video
- (d) Altimeter controlled camera aperture setting
- (e) Shipborne image processing system.
- (f) 35mm Photographic film digitiser
- (g) High resolution electronic printer
- (h) Acoustic navigation To aid repeated, accurate location of specific sites, an expendable transponder attached to the WASP vehicle could be deposited on command.

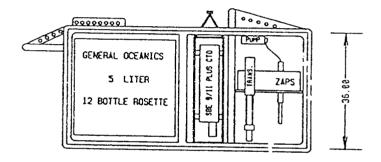
ZAPS SLED



PORT VIEW



STARBOARD VIEW



TOP VIEW OF FRAME WITH DIMENSIONS IN INCHES

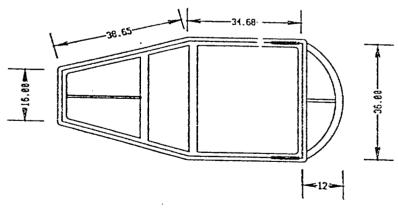


Fig 2.1



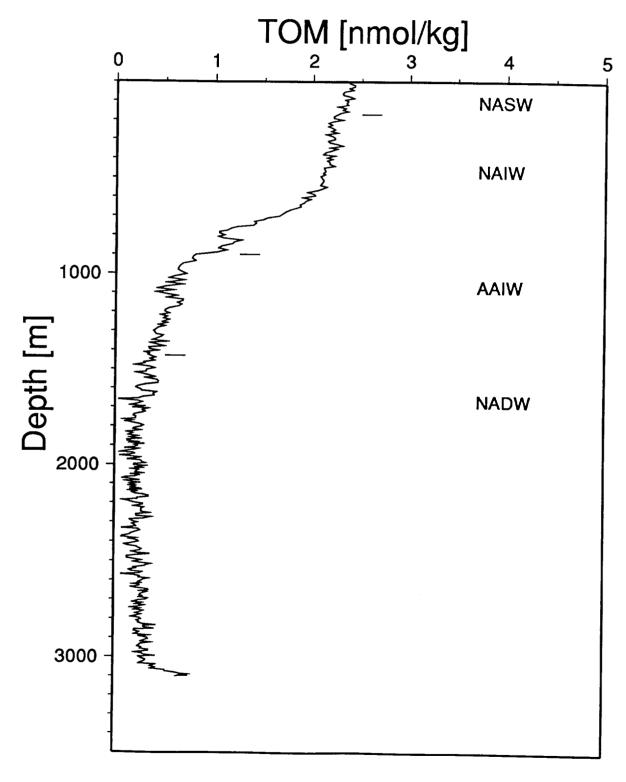
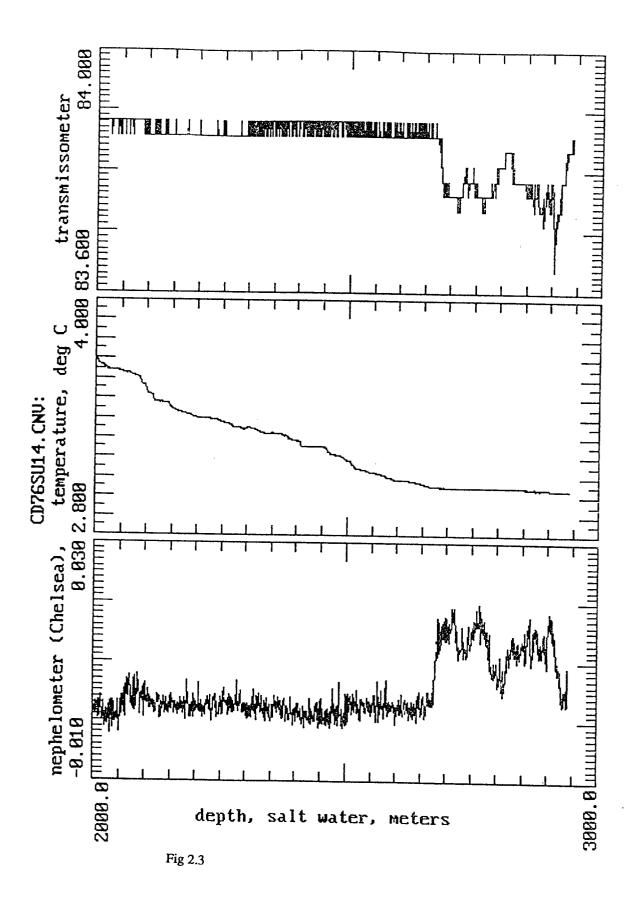


Fig 2.2 ZAPS Profile 053/16:01 - 18:25 26° 52.05' N 44° 29.38' W



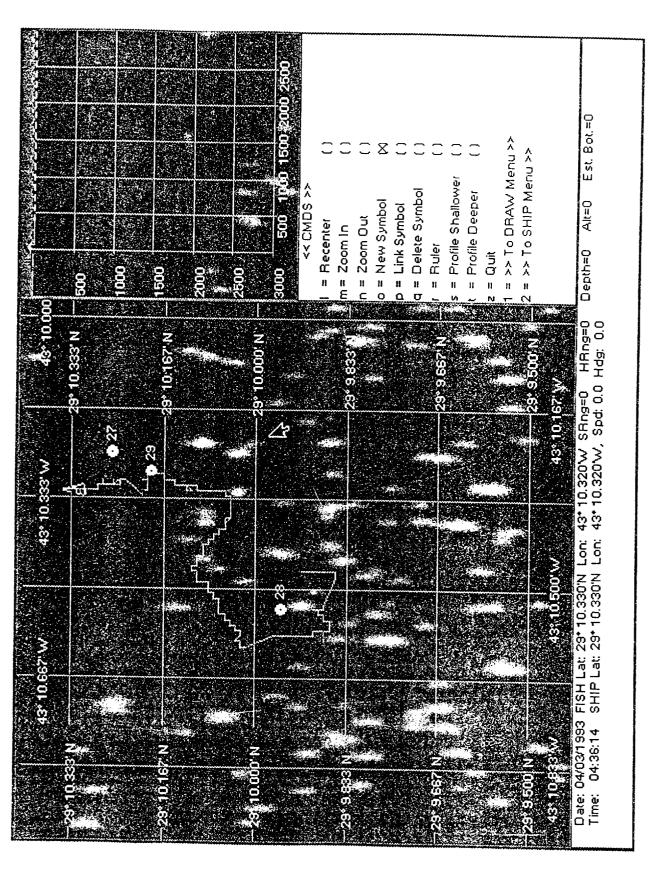


Fig 2.4

2.4 Measurement of Vector Geomagnetic Field By STCM (by Keizo Sayanagi)

2.4.1 Introduction

Vector data of the geomagnetic field were collected with the Shipboard Three Component Magnetometer (STCM) during this cruise except when the ZAPS, WASP, and dredging surveys were conducted over the Broken Spur Vent Site. The vector magnetic data provide more detailed information than total intensity data to understand the magnetic structure of oceanic crust, because the amplitude of vector magnetic anomalies is not affected by the direction of the ambient geomagnetic field or the strike of magnetic lineations. The STCM system has been developed and improved since 1977 (Isezaki et al., 1981; Isezaki, 1986; Seama et al., 1990). It has been used in many oceanic regions to successfully measure the geomagnetic field vector (e.g. Seama and Isezaki, 1990; Nogi et al., 1990; Seama et al., 1993). The geomagnetic field observed by the STCM are superimposed on the magnetic field produced by the induced and permanent magnetic moments of the ship. The ambient geomagnetic field vector are calculated by reducing those artificial magnetic fields. For this calibration, we ran the ship along a track in a figure "8" at 4 sites and in a circle at one site.

2.4.2 Principle of Measurement

The observed geomagnetic field is superimposed on the magnetic field produced by the induced and permanent magnetic moments of the ship.

$$\mathbf{H}_{ob} = \mathbf{F} + \mathbf{H}_i + \mathbf{H}_D \qquad (1)$$

where \mathbf{H}_{OD} and \mathbf{F} are the observed and ambient geomagnetic fields. \mathbf{H}_i and \mathbf{H}_D are the magnetic fields produced by the induced and permanent magnetic moments of the ship. The induced magnetic field \mathbf{H}_i is proportional to \mathbf{F} , since \mathbf{F} is a weak field. Therefore equation (1) can be rewritten as;

$$\mathbf{H}_{ob} = \mathbf{F} + \mathbf{AF} + \mathbf{H}_{p} \qquad (2)$$

where **A** is a 3x3 matrix which depends on the magnetic susceptibility of the ship, the shape of the ship and the position of the sensor. Because the sensor is fixed to the ship, the equations must be written in the ship's coordinate system. **F** is transformed into the ship's coordinate system from the geomagnetic coordinate system (Fig. 2.5). The expression is **(RPY)F** where **R, P** and **Y** are coordinate transform matrices due to the roll, pitch and yaw of the ship. The ship's coordinate system axes are along the heading, starboard and downward direction, respectively.

$$\mathbf{H'}_{\mathrm{Ob}} = (\mathbf{RPY})(\mathbf{1} + \mathbf{A})\mathbf{F} + \mathbf{H'}_{\mathrm{D}} \tag{3}$$

where $\mathbf{H'}_{OD} = (\mathbf{RPY})\mathbf{H}_{OD}$, and $\mathbf{H'}_{p} = (\mathbf{RPY})\mathbf{H}_{p}$. From equation (3)

$$\mathbf{F} = ((\mathbf{RPY})(\mathbf{1} + \mathbf{A}))^{-1}(\mathbf{H'}_{Ob} - \mathbf{H'}_{D}) \tag{4}$$

 ${f F}$ is a linear function of ${f H'}_{OD}$. Therefore, ${f F}$ can be obtained from the observed magnetic field.

The transform matrix $\mathbf{A} = (A_{ij})$ and $\mathbf{H'p} = (H'_{ph}, H'_{ps}, H'_{pv})$ can be defined where the data $\mathbf{H'}$ ob are obtained in all ship directions. In practice the data for determining the transform matrix are collected while the ship sails along a track forming a figure "8". There are 12 unknown values (9 in \mathbf{A} , 3 in $\mathbf{H'p}$) that are determined by the least squares method. The heading angle varies from 0° to 360° while the pitch and roll -5° to 5° during calibration. Therefore $\mathbf{A_{i1}}$ and $\mathbf{A_{i2}}$ are determined better than $\mathbf{A_{i3}}$ and $\mathbf{H'p}$. To avoid this defect several figure "8" rotations are needed at places with varying downward components of the geomagnetic field. The STCM calibration sites and 12 constants are shown in Tables 1 and 2.

2.4.3 Instrument and Data Acquisition

STCM consists of a flux-gate magnetometer, two gyro-compasses and a personal computer (Fig. 2.6). The sensors of magnetometer consist of three-axial flux-gate coils. The sensor package was rigidly mounted on the "Monkey Island" with a wooden board and ropes. All of the other instruments were installed in the Plotting Room. The flux-gate magnetometer measures individual x, y, z component of the magnetic field with accuracy of about 0.5 nT. The gyro-compasses obtain the ship's yaw, pitch and roll data. The personal computer collects the magnetic (x, y, z) data and the yaw data through a PIO (Parallel I/O) board, and the pitch and roll data via a RS-232C interface. Those data are sampled every second. The data are stored on a hard disk in binary code. Header information of Cruise ID, Date, and Time is attached to the binary records every minute. These STCM data are also stored on a 5 inch floppy disk in ASCII code to check the collected data.

In this cruise, the STCM was not linked to the ship's navigation and geophysical data acquisition system, which provides the ship's position, speed and yaw data, water depth data and magnetic total intensity data obtained by the proton precession magnetometer. We combined those data with the STCM data as follows:

- (1) STCM data in binary code are translated into the data in ASCII code and are saved on a 5 inch floppy disk. The data are edited if there are some irregular data.
- (2) The ASCII data are copied from an IBM personal computer to the ship-board SUN workstation. The copied data are checked for the format and number of records.
- (3) The ship's navigation and geophysical data every 30 seconds, except for the yaw data, are added to header information of the STCM data. The yaw data are appended to a STCM data record every second.
- (4) The completed STCM data set is stored on a 150 Mbyte cartridge tape by "tar" command.

The above processing was conducted for the STCM data obtained between 6 Feb and 27 Feb, while the vent surveys of Station 1 were carried out. The other STCM data were not processed because the STCM system was running until arrival at Azores.

2.4.4 Sample Data

Figure 2.7 shows a sample of STCM data on 14 Feb, obtained along a magnetic survey line almost perpendicular to the direction of magnetic lineations. X, Y, Z indicate the northward, eastward and downward component of the vector geomagnetic anomalies, respectively. Tp indicates total intensity anomalies obtained by proton magnetometer. The vector magnetic data were calculated by using 12 constants from R1 STCM calibration data. The vector and total intensity magnetic anomalies were calculated by subtracting IGRF 90 from the observed magnetic field. X component anomalies have relatively smaller amplitude than Y and Z components. Y and Z component anomalies have similar variations. Their phases are, however, different by a quarter period.

References

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Figure Captions

Fig. 2.5 The geographic coordinate system (x,y,z) and the ship's coordinate system (h,s,v). a₁, a₂ and a₃ are heading, roll and pitch angles, respectively.

Fig. 2.6 Block diagram of the system of STCM

Fig. 2.7 A part of vector and total intensity magnetic anomaly profiles on 14 Feb 1993. This magnetic survey line was almost perpendicular to the direction of magnetic lineations. X, Y, Z indicate the northward, eastward and downward components of the ambient geomagnetic field, respectively. Tp indicates total intensity magnetic anomalies obtained by proton magnetometer.

Table 1. STCM Calibration Sites

```
06 Feb. 93, 14:15 -> (Right turn) -> 14:42 -> (Left turn) -> 15:04
16°35.66'N, 55°21.31'W
Ship speed = 7.9 \sim 10.7kts (av. 9.1kts), Water depth = 5816.6 \sim 5791m (av. 5795.4m)
10 Feb. 93, 04:26 -> (Left turn) -> 04:50 -> (Right turn) -> 05:16
26°31.41'N, 43°35.27'W
Ship speed = 8.4 \sim 11.3kts (av. 9.4kts), Water depth = 3060.0 \sim 3791.0m (av. 3277.1m)
14 Feb 93, 09:38 -> (Right turn) -> 09:42 -> (Left turn) -> 09:47
28°15.97'N, 42°58.07'W
Ship speed = 2.4 ~ 7.9kts (av. 5.0kts), Water depth = 3683.2 ~ 3728.7m (av. 3706.6m)
14 Feb. 93, 09:51 -> (Right turn) -> 10:06, no Left turn
28°15.71'N, 42°59.31'W
Ship speed = 5.0 \sim 10.3kts (av. 7.5kts), Water depth = 3387.8 \sim 3824.1m (av. 3620.6m)
R5
08 Feb. 93, 10:00 -> (Right turn) -> 10:21 -> (Left turn) -> 10:41
32°00.51'N, 35°16.99'W
Ship speed = 7.0 \sim 11.5kts (av. 9.0kts), Water depth = 3687.2 \sim 3713.0m (av. 3700.7m)
```

Table 2. List of '12 Constants'

Rl				
(1 + A) =	1.4261 0.0529 0.0632	-0.0759 1.5893 0.2452	-0.0373 -0.0795 0.7363	-9609 H' p = -16925 -5506
R2				
(1 + A) =	1.4216 0.0598 0.0623	-0.1479 1.5183 0.1994	-0.2261 -0.2690 0.6285	-964 H'p = -7754 223
R3				
(1 + K) =	1.4415 0.0369 0.0452	-0.0570 1.5984 0.2321	-0.0353 -0.0382 0.7064	$\mathbf{H'p} = \begin{array}{r} -9371 \\ -18036 \\ -2920 \end{array}$
R4				
(1 + A) =	1.4401 0.0767	-0.0784 1.6077	0.0307 0.0011	-12095 H' p = -19918
0.07	51	0.2747	0.8921	-11290

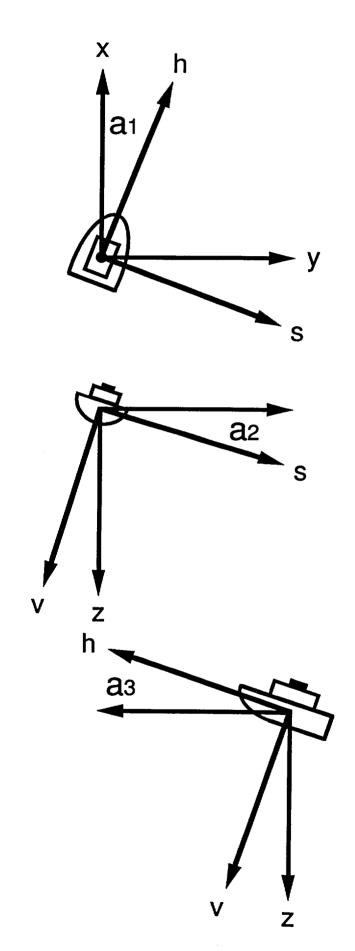
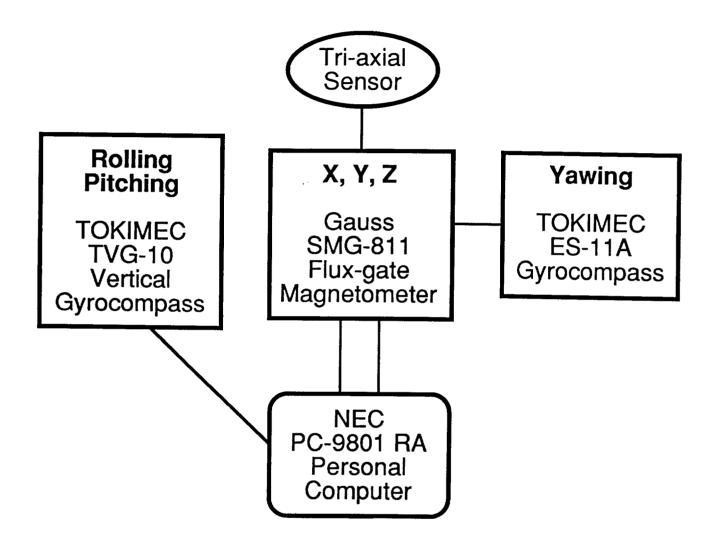
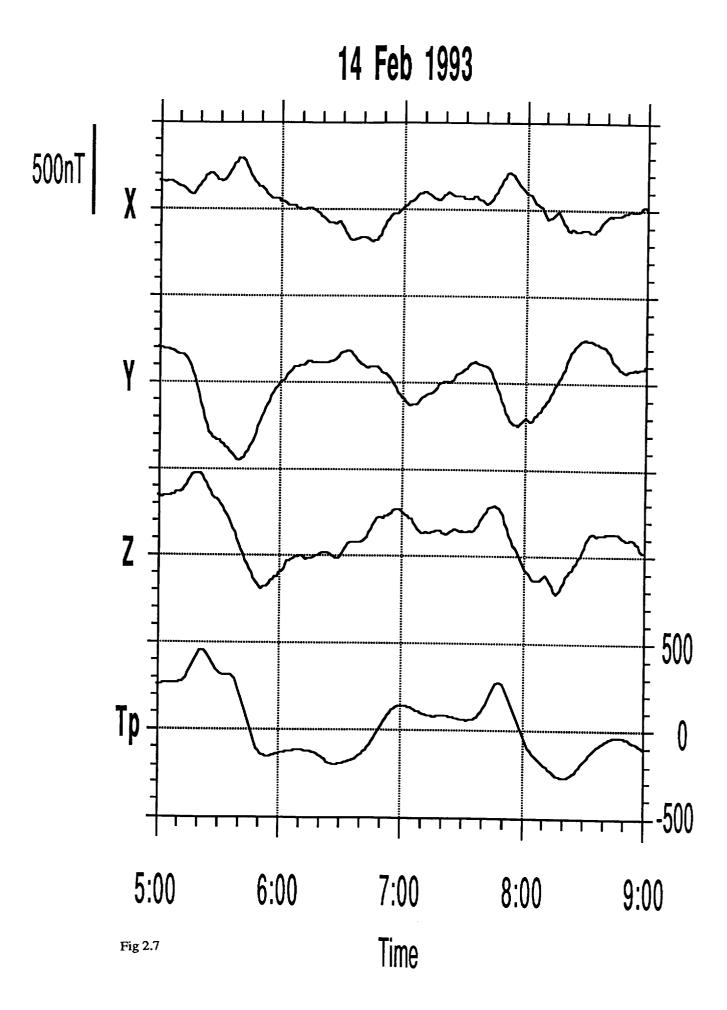


Fig 2.5





2.5 ²²²Rn- ²²⁶Ra Analysis of Water Samples (by Mark Rudnicki)

2.5.1 Introduction

Although not originally intended until cruise CD77, water samples were collected during ZAPS sledge run S14. Four 5 litre Niskin bottles were tripped within the neutrally buoyant plume at a depth of 2700m, and a further two above the plume at 2500m. On recovery, it was found that bottles 6 and 10 had misfired, resulting in the collection of one 10 litre sample R1 at 2700m and two five litre samples, R2 and R3, at 2700m and 2500m.

The three samples were analysed by the method of Mathieu et al. (1988). The radon gas is stripped from the sample and retained on activated charcoal at -70°C by bubbling and recirculating He carrier gas. The charcoal is then heated to 450°C to drive off the ²²²Rn gas into an evacuated plexiglass cell coated with an activated ZnS phosphor for alpha scintillation counting. Although it is standard practise to collect 15-20 litres of sea water for analysis, smaller volumes such as those collected here can be measured with greater signal to noise ratios and correspondingly greater errors. After stripping once for ²²²Rn, the samples were resealed and ²²²Rn allowed to ingrow due to decay of natural ²²⁶Ra. A repeat of the ²²²Rn analysis procedure after 7 or more days ingrowth allows measurement of the parent ²²⁶Ra activity. The difference between the measured ²²²Rn activity and the parent ²²⁶Ra activity, the 'unsupported ²²²Rn' (i.e. over and above that naturally produced in the water column) can be due to either ²²²Rn diffusion from sediment, from a hydrothermal source, or conversely due to particle scavenging removal of ²²⁶Ra. In the sparsely sedimented axial valley of the Mid-Atlantic Ridge, the presence of unsupported ²²²Rn is assigned to hydrothermal activity.

2.5.2 Results

Results of 222 Rn and 226 Ra analysis are presented in the table. The units are dpm/ 100 kg-disintegrations per minute per 100 kg of sea water

Sample	Depth (m)	Volume (litres)	²²² Rn dpm/100kg	²²⁶ Ra dpm/100kg
Rl	2700	11.0	26.3	33.6
R2	2700	5.5	31.9	55.7
R3	2500	5.5	40.8	53.6

The 222 Rn and 226 Ra backgrounds of sea water in the axial valley of the Mid-Atlantic Ridge are known from 26°N (Rudnicki and Elderfield, 1992) and are: 222 Rn= 33.5 dpm/100kg, 226 Ra= 36.4 dpm/100kg. Thus, the 222 Rn analyses lie within error (10%) of background sea water, providing a good test of new equipment for CD77.

References

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- M. D. Rudnicki and H. Elderfield, Helium, radon and manganese at the TAG and Snakepit hydrothermal vent fields, 26°N and 23°N, Mid-Atlantic Ridge, <u>Earth Planet. Sci. Lett.</u>, 113, 307-321, 1992.

2.6 Standard RVS Vessel Instrumentation and Underway Geophysics Gear

(by Dave Teare)

2.6.1 Gravity Meter

The Platform used with this system was a non-RVS (Research Vessel Services) unit and, as such, we had no history of its previous performance. An initial problem, due to a gyro change in Trinidad, caused the platform to oscillate. The original gyro was refitted and the system appeared to function properly.

2.6.2 Gravity Results

The gravity field at the survey area was observed on the RRS Charles Darwin by a S110 gravimeter with digital logging on loan from LaCoste and Romberg. This was in place of the usual meter which was being repaired. During the transit leg to the survey area one of the gyros in the stability platform caused serious problems and had to be replaced leaving little data from this section of the cruise. The gravimeter output continued to be noisier than perhaps expected and it was felt that this was partly due to a minor problem in the gyro and partly due to the nature of the cruise.

Raw gravity data was sampled every 10 seconds and and filtered in the gravimeter using a 5 minute running mean filter. This was then recorded both with a paper recorder and on the RVS computers (ABC system), before being processed with the navigation data by RVS Senior technician Gareth Knight.

The gravity was firstly averaged to 30 second values in order to be standard with the navigation and depth data. This 30 second interval gravity was then reduced to give Free Air Anomaly (FAA) using a correction for latitude and the EOTVOS correction for reducing the artificial gravity effects caused by variations in the ships course and speed.

Eotvos Correction (Worzel 1959)

```
dg = 7.487 \times S \times \sin(C) \times \cos(\text{lat x N}) + S^2 / 240.8 S = \text{speed made good (in knots)}, C = \text{course made good} International \ gravity \ formula \ (\text{Jacobs et al 1959}) g(\text{lat }) = 9.78031.8 \times (1 + 0.0053024 \times (\sin(\text{lat })^2) + 0.0000059 \times (\sin(2 \times \text{lat }))^2)
```

The EOTVOS corrections depend on good satellite coverage, which was generally available during CD76. Corrections can be made for all but the abrupt course changes. The gravimeter itself required 10 - 15 minutes for the gyros to stabilise after any major course changes. This results in local spikes (30 mgal) in the FAA which needed to be edited manually before any further work can be done. Part of the overall noisiness of the data may be explained by the nature of the cruise. Deep towed vehicles require slow ship speeds and frequent minor course corrections which is not ideal for gravity surveys. It is not coincidental that the quality of data improved on the transit leg to the Azores when the ship was moving faster and with fewer course alterations.

Drift in the gravimeter was monitored using a number of crossovers (fig. 2.8) which seem to indicate little instrument drift.

2.6.3 Underway Magnetics (by Anne Briais and Heather Sloan)

Magnetic data were collected using a surface towed proton precession magnetometer during the transits from a point northeast of Trinidad (out of the 200 nm Trinidad EEZ) to the survey area and from the survey area to a point southwest of the Azores (out of the 200 nm Azores EEZ), as well as during eight off-axis runs along lines

approximately parallel to the local tectonic flowlines or plate-spreading direction. The times and positions of these routes are listed below. The raw magnetic data exist as field measurements every six seconds in a file called magnet. The processed magnetic data exist in a file named promag90 which contains values every 30 seconds for the total magnetic field and the magnetic anomaly (using the 1990 IGRF) merged with the corrected GPS navigation.

The magnetic anomaly values were plotted as profiles along the shiptracks using the GMT mapping software (Wessel and Smith, 1991). Anomaly identifications and correlation were made using a model calculated by Sloan and Patriat (1992) with a constant spreading rate of 12.5 km/Ma and a magnetized layer thickness of 400m. Anomalies 0, 2, 3, 3a, 4, 4a and 5 correspond to ages 0, 1.89, 3.85, 5.69, 7.01, 8.69, and 10.10 Ma, respectively.

Profile		Start		End		
	time	lat N	long W	time	lat N	long W
M1 - M2	040 2240	26° 38.89'	44° 42.34'	041 0415	26° 32.49'	43° 36.19'
M3 - M4	041 0530	26° 32.08'	43° 37.78'	041 0930	26° 46.19'	44° 27.30'
M5 - M6	041 2309	26° 53.31'	44° 33.19'	042 0405	27° 05.46'	45° 31.03'
M7 - M8	042 0500	26° 59.70'	45° 29.93'	042 0930	26° 47.48'	44° 32.23'
M9 - M10	045 0450	28° 29.62'	43° 39.00'	045 0900	28° 21.10'	42° 57.65'
M11-M12	045 1023	28° 15.47'	42° 59.91'	045 1440	28° 25.08'	43° 42.51'
M13-M14	058 0130	29° 14.46'	43° 08.41'	058 0530	29° 22.67'	43° 45.88'
M15-M16	058 0612	29° 17.37'	43° 47.75'	058 0930	29° 10.93'	43° 10.44'

2.6.4 Simrad Echo Sounder

Two faults occurred on this system, both of which affected the printer. One was the printer itself not operating correctly and the other was caused by the Simrad stopping the printer. The first problem cleared itself after the printer was partially stripped down and cleaned, the second problem cleared after switching the Simrad 'off' and 'on' again.

2.6.5 3.5 kHz Echo Sounder

This system was not used because the bottom topography was so rough as to render it useless.

2.6.6 D.M.W. Clock

The year '2' digit was lost on the output signal thus giving a 1991 output; no spare board in the spares kit and no suitable I.C. found on board. Spares coming out from Barry to the Azores.

2.6.7 Winch Monitoring

For the Corel Dredge, wire-out rate and load cell sensors both had faults. These were traced to a faulty backplane connector and faulty chart recorder respectively.

2.6.8 General Observations/Recommendations

No major breakdowns in the standard RVS underway geophysical gear deployed during CD76 occurred, but the level of spares carried leaves something to be desired. The present winch monitoring system should be replaced with the type fitted to Discovery and Challenger.

2.7 The Oceano Acoustic Navigation System

(by Gary White and Andy Hill)

The Oceano Transponder net was deployed using four transponders in an average water depth of 3000 metres. A relay transponder was fitted to various towed vehicles and interrogated with the "V-fin" fish on a new 19-way tow cable. The usual relative calibration, iteration and absolute calibration of the 5 km square net was carried out during good weather.

The "V-fin" fish had several deployment problems: there was no proper arm to keep the fish clear of the side of the ship. This limits the manoeuvrability of the ship, making turns to port almost impossible. The basic shape of the "V-fin" fish should create a downforce to keep it level in the water. However, it tends to yaw violently in the water and sometimes comes dangerously close to the ship's propeller. This, coupled with the new thicker tow cable which has a very tight turn in the cable as it enters the fish, eventually resulted in the electrical cable to fail after one day's use. The failure, at the wire locked termination, had to be cut off, remade and reported with wire lock. This took 36 hours in all. There is no safety specification sheet or usage instructions on board for the wire lock moulding medium.

We recommend that the wire lock termination trailing arms need to be longer so that a less torturous route for the electrical cable can be used; the fish body shape needs to be reviewed and a more solid design adopted.

Otherwise the survey collected good data, although long TOBI runs were only navigated correctly by the Oceano System when both the ship and TOBI were within the net together.

The Oceano System still causes the GPS navigation to lock up occasionally but did not cause any problems on this cruise. Overall the system worked within specification but the excessive time required to deploy and calibrate the system is a major drawback, especially as time on these cruises is at a premium. We believe that the system is too slow with its present computer hardware to be used satisfactorily in modern scientific research.

2.8 Dredge Summaries

All dredges were collected using the standard RVS basket plus pipe dredge, attached to the main dredge warp and towing winch.

Dredge 1

Target

Target

29° 10.25'N, 43° 10.25'W

Dredge 1 was aborted due incorrect ship positioning, no samples were recovered.

Dredge 2

29° 10.17'N, 43° 10.43'W - 29° 10.54'N, 43° 9.86'W

29° 10.25'N, 43° 10.25'W

Dredge 2 recovered 7 rocks, and 1 kg of assorted fragments, largely glass.

Dredge 3

29° 10.22'N, 43° 10.33'W - 29° 10.45'N, 43° 10.00'W

Target 29° 10.25'N, 43° 10.25'W

Dredge 3 recovered approx. 0.5kg of basalt fragments (~25% plagioclase phenocrysts)/ shards of glass

Dredge 4

29° 9.8'N, 43° 11.17'W - 29° 10.03'N, 43° 8.55'W

Target

29° 10.25'N, 43° 10.25'W

Dredge 4 recovered approximately 2kg ofglassy plagioclase sheet flow pillow lavas material.

Dredge 5

29° 9.96'N, 43° 10.29'W - 29° 10.76'N, 43° 8.87'W

Target

29° 10.25'N, 43° 10.25'W

Bag 1: Five pieces of 40 to 70cm size pillow basalt extrusions. Medium to dark grey basalt, showing some cores with vesicles of <1mm. Yellow/ brown alteration/ staining, internal layering. Glassy rinds. \approx 10% light cream white plagioclase phenocrysts up to 2mm diametre.

Bags 2 and 3: Lighter grey flow basalts, not as fresh, more weathering/ alteration. Hyaloclastic outer surfaces, included sediment is cream coloured. Two 20cm pieces in bag 2; 13 smaller pieces <5cm in bag 3.

Bag 4: Basaltic lava flow. Top surfaces of these are weathered orange- brown- black with finely spaced parallel striations.

Bag 5: Small bag of most fresh, black hard glasses from approx. 5kg mass collected.

Dredge 6

29° 10.6'N, 43° 11.63'W - 29° 10.4'N, 43° 10.45'W

Target

29° 10.25'N, 43° 10.25'W

 $Bag\ 1$: Approx. 8kg of glass fragments and chippings of basalts from bucket dredge of which one small bag of best samples was preserved.

Bags 2 and 3: 2 half filled nylon sacks of medium sized 10-20cm diameter chunks of largely pillow basalts (70%), some with chilled glassy rinds and occasional plagioclase <2cm megacrysts. Sheeted lava flow basalts (30%) with some showing layer interaction features such as tubes, drips, concave and convex surfaces. The best examples have been preserved.

Samples retained:

Bag 1: Glass shards from pipe dredge.

Bag 2: Glass shards from main dredge.

Bag 3 Three samples of plagiocloase phyric sheet flow, \sim 20cm thick with \sim 10mm plagioclase megacrysts.

Bag 4, 5: Plagioclase phyric pillow. (1+~8 samples)

Bag 6: Lava buds with vesicular cores.

Bags 7 and 8: Aphyric pillow basalt fragments.

Bag 9: Aphyric 10cm sheet flow basalt.

Also: pure glass fragments.

Dredge 7

29° 10.11'N, 43° 10.22W - 29° 9.8'N, 43° 9.8'W

Target

29° 10.25'N, 43° 10.25'W

acoustically navigated dredge deployment

 ${\it Bags\ 1}$ and 2 Decimetre sized frseh aphyric-plagioclase phyric glassy pillow basalt from micro-pillows.

Bag 3: 4 pieces of slightly palagonitised glassy pillow selvedges.

Dredge 8

29° 10.99'N, 43° 10.20'W -

Target

29° 10.99'N, 43° 10.20'W (acoustic navigated)

acoustically navigated dredge deployment

(Weak link failed, dredge choked with small catch)

Bag 1: Glassy pillow rinds. Black glass approx. 0.5cm thick, with one surface showing rust coloured weathering in places, easily fractured.

Bag 2: ~10cm basalt pillow fragments with glassy rinds and 0.5cm plagioclase phenocrysts.

Bag 3: \sim 10cm pillow fragments with glassy rinds, with smaller more numeroous plagioclase phenocrysts (1 by 2 mm)

Dredge 9

29° 10.1'N, 43° 8.2'W - 29° 10.33'N, 43° 10.55'W

Target

29°10.25', 43°10.25'W

Hand specimens:

Bags l and 2: Small fragments <2 cm black basaltic glass with palagonite surface weathering. Some with small millimetre size plagioclase phenocrysts.

Bag 3 and 5: Large fragments >3 cm in size of black basaltic glass with palagonite surface weathering showing millimetre scale plagioclase phenocrysts (<2%).

Bag 4: Biology-small shell fragments.

Bag 6: Non-glassy dark grey basalt approx. 10% plagioclase phyric. Sample shows tube like/flow feature morphology.

Bag 7: Black fine very fresh glass shards.

Bag 8: Two pieces of basaltic sheet flow approx. 10% plagioclase phyric (1 by 2 mm), with palagonitised glassy top surface. Bottom surface appears bulbous as if formed in a cavity.

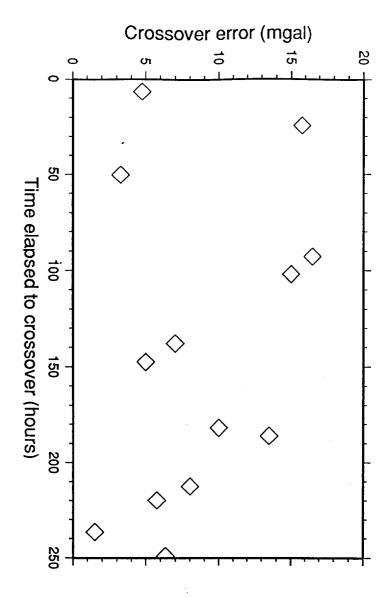


Fig 2.8

3 COMPUTING AND PROCESSING

3.1 Level A-B-C Computers

(by Gareth Knight)

During cruise CD76 the ABC computing network was used for both the processing of directly logged data and the transfer of TOBI image and instrumentation data. Data was sampled at six seconds for raw magnetic field, ten seconds for gravity meter data and thirty seconds for echo sounder depth. Navigation for the cruise was corrected to GPS position fixing the receiver output being at its maximum data rate of every two seconds. Acoustic navigation when available was recorded every twenty seconds. Data was processed to a final navigation interval of thirty seconds and subsequent calculations of magnetic anomaly, corrected depth and gravity anomaly were made also at a thirty second interval. Magnetic anomaly was calculated using the 1990 IGRF and echo sounder data corrected with Carter Area sound velocity corrections.

The gravity meter on loan from Lacoste-Romberg produced data which was far noisier than normally seen. It was felt that the stability of the servo mechanism for the meter was poor and that this was the root cause of the noise. The overall recording of low frequency gravity trends was however satisfactory and when gravity crossover points were taken these also appeared to be reasonable and free from meter drift.

For the first time a spare TOBI optical disk drive was successfully attached to one of the ships work stations. This enabled the logged image disks to be read onto a unix platform. Reduced resolution images were then stored onto back-up optical media after some initial processing. Previous attempts to install this device failed due to conflicts between its logical unit number and that of a standard SUN hard disk device sd3. On this occasion the drive was installed using the custom installation procedure to a diskless client workstation. This proved to be most useful as the drive was often moved between the Sun workstation and the TOBI replay system as the drive was the only device on the workstation this could easily be done. The public domain package GMT was installed for use on CD76. This took some time to achieve as the compilation from source relied upon a number of Makefile structures which were not correct. Eventually however the package was successfully installed.

The public domain image processing package PBMPLUS was also installed for use on CD76. The passage time to and from the working area was a great assistance in allowing the changes to the system to be made and the distributing of the very large amount of TOBI data transferred to the processing system.

Towards the end of the cruise three relatively small TOBI images of 300Kb were produced in Sun Raster image form and transferred to RVS using the satellite communication system. The images were loaded onto the communication system using the addmsg -b function which allows transfer of binary data. These images were then enlarged to A4 sized raster images back at RVS and dispatched by courier for the live interview given by the PSO on BBC television's Tomorrows World programme.

3.2 TOBI Image Processing

(by Nick Hayward)

The primary recording system for the TOBI is the IBM PS/2 used during deployment for immediate processing. The records generated are then stored in MS-DOS format on magneto-optical (MO) discs. For distribution purposes the raw TOBI data on MO disc was read, processed and stored as UNIX files using the RVS SUN workstations.

The data processing system was based primarily on the software written on CD65 by Scott Garland of Boise State University. The minor modifications necessary were due to the addition of the geochemical sensors to TOBI. In addition a byte swapping routine needed to be added in order to transfer data from IBM MS-DOS to SUN UNIX format.

The processing operation consisted of the following stages (programme name):

```
reading the data from disc (rtd2)
performing the byte swap (dd)
processing the TOBI records (ptd2)
writing image files (ptd2)
conversion of images to pbm format (side2pgm)
extracting magnetics and geochemical data (ptd2)
image processing (pbmplus)
image display (alv)
convert binary magnetics data to ascii for underway geophysics (rmag3)
```

RTD2

Rtd2 is based almost entirely on rtd, the programme written for CD65, modified only to take account of the new data in the data stream. It reads the MO disc and finds each 4 second TOBI record by matching a user supplied string to that heading each record. The string is usually the ship name (6 characters), in this case Charle. Since one MO disc holds about 12000 records (approx 13 hours), an amount too great to process in a single run, the processing is split into 3 sections of about 4000 records each. This is done using rtd2 by specifying the byte offset to start reading the disc, and the number of records to be read. Each 4 second record takes the form:

unit	offset:
char heading[48]	00000
int version	00048
int time	00050
int date	00052
struct position approx	00054
int magx[8]	00066
int magy[8]	00082
int magz[8]	00098
int roll[8]	00114
int pitch[8]	00130
int speed[8]	00146
int nephelometer[8]	00162 -not used this cruise, ie empty
int compass[8]	00178
int press[8]	00194
int altitude	00210
int water_path	00212
int temp[8]	00214
int trans[8]	00230
int zaps[8]	00246
byte empty[314]	00262
int port_sonar[4000]	00576
int starboard_sonar[4000]	08576
int profiler[4000]	16576
	24576 -total 4 second stream

PTD2

The data is then piped into a standard UNIX data processing routine, dd, which performs the byte swapping, before it is piped into ptd2., again based on a CD65 programme. Ptd2 reads the 4000 record file in the same manner as rtd2 (the header string is now hCrael), extracts the data from the geophysical and geochemical sensors into a binary file, slant range corrects the side scan sonar data and pipes this into an image conversion programme.

SIDE2PGM

Side2pgm converts the sonar data into a more portable image format called PGM (portable grey map). The PGM format is a simple two dimensional array of binary (8-bit) pixels and a small header containing the dimensions of the image. This simple format allows for easy manipulation and conversion and is recognised by many display packages. A limitation of this conversion process is that although the original side scan data is in 12 bit format the PGM library, PBMPlus, can only handle up to 8 bit precision - although most workstations can only display 8 bit samples. This loss in precision results in a 'darker' image, which can be corrected for by applying a histogram correction with the PGM software.

MKIMAGES2

The processing stream discussed above is held in a UNIX shell script, *mkimages2*, which processes a MO disc in 3 sections and also passes the finished PGM image on to short pipeline of *PBMPlus* applications in order to produce a small normalised image from a full TOBI PGM file, suitable for viewing on screen or printing for reference. Each 4000 records of TOBI data results in three files of output with the following name convention:

filetype_starttime_discid_surveyarea.extension giving
big_starttime_discid_cd76[ns][abc].pgm : the full tobi image file
small_starttime_discid_cd76[ns][abc].pgm : the condensed image file
mag_starttime_discid_cd76[ns][abc].dat : the binary magnetics file
[ns] indicates north or south bound tobi tracks in this survey
[abc] indicates 1st, 2nd or 3rd section of a disc

Occasionally other suffix characters are added at later stages and indicate a slightly different file. For example, in some parts of certain discs, problems were encountered in processing the 4000 records in one go and so it would be split in two - such as al and a2. In this case the full image file would be a concatenation of the 2 files with a white buffer in between to represent missing records, the added labels are m for the buffer and x for the combined file. The suffix ras indicates a raster file used for display purposes (see *PBMPlus*). The prefix med indicates an image which is physically large but has been desampled for viewing and thus not suitable as a source file for further image files.

PBMPLUS

This is a public domain image processing package written by Jef Poskanzer. It was designed to allow easy manipulation of a portable image format as well as conversion routines to convert between different formats. All the *PBMPlus* routines are easily pipelined to allow multiple operations before producing a final image and shell scripts were used for many of the most common pipelines, including those for cutting (*pnmcat*), rescaling (*pnmscale*) and contrast stretching the images (which was subsequently broadcast on BBC TV's "Tomorrows World" programme). The routine *pnmtorast* was used to convert all completed images into raster files for transfer to the display package *Alv*. For more information on *PBMPlus* consult the manual pages on the CD76 data exabyte tape.

ALV

The Alv package is another public domain image processing package and uses standard Sun raster format image files as storage. Since the images were in PGM format this package was only used for display purposes and of the 47 programmes in Alv only a few were used. These include programmes to display images on screen, interactively adjust contrast, brightness and magnification, and to print to a laserwriter.

Note: An alternative to *Alv* as the display package is *xloadimage*, a programme which takes as input PGM format images. This was not used since it requires the *xwindows* environment, which was unavailable on the RVS SUN workstations, but is included on the CD76 exabyte for completeness.

RMAG3 & RMAG2

These programmes required the most changes from the CD65 versions in order to cope with the added data produced by TOBI. Rmag3 is a command line based C programme which reads a binary TOBI magnetics file and converts the requested fields into ascii format. It includes all of the calibrations used on CD76 and hence gives the output (mostly) in SI units. Several of the calibrations were changed mid-cruise and the variations are held in the source code for mag3, and should be altered there. The calibrations for temperature and pressure were to be checked at the end of the cruise, and so rmag2 (with no calibrations in) has been included in the exabyte for completeness and as a basis for applying any new calibrations. The input from ptd2 for both rmag3 and rmag2 is of the form:

short time short date short magx[8] short magy[8] short magz[8] short roll[8] short pitch[8] short compass[8] short pressure[8] short altitude short temp[8] short trans[8] short zaps[8]

TOBI Exabyte

An exabyte tape was produced on board to distribute the SUN processed data to those cruise participants requiring digital images or the binary magnetics data, and includes all of the above software with the exception of *Alv*, as well as manual pages for almost everything.

The data on tape is the result of multiple tar backups which was necessary as there was insufficient disk storage on the RVS SUN system to do it any other way. Each tar archive was made with the command:-

tar cvf /dev/nrstl .

In order to restore the files on another system, the tape needs to be positioned using the mt command and the non rewind device (which may not be nrstl on the IOS system), before reading each archive other than the first one. For example:-

mt -f /dev/nrst1 fsf 3

will position the tape after the third archive so you can recover data from archive four.

The file phmplus.tar.Z is a compressed tar archive of the original PGM distribution software. To extract this software the following commands should be executed before compilation:

mkdir pbmplus cd pbmplus zcat pbmplus.tar.Z | tar xvf -

Compilation should be done after reading the ReadMe notes in PBMPlus, and using the instructions therein. Before accessing files with the Z suffix, these also need uncompressing using the uncompress filename command.

Listing of CD76 TAR Tapes

TAR1 big_043.0946 201 cd76na.pgm.Z big_043.0946_201_cd76nb.pgm.Z big_043.0946_201_cd76nc.pqm.Z big_043.2305_202_cd76na.pgm.Z big 043.2305 202 cd76nb.pgm.Z big_043.2305_202_cd76nc.pgm.Z big_044.1225_203_cd76na.pgm.Z big_044.1225_203_cd76nb.pgm.Z big_044.1225_203_cd76nc.pgm.Z small_043.0946_201_cd76na.pgm small_043.0946_201_cd76na.ras small_043.0946_201_cd76nb.pgm small_043.0946_201_cd76nb.ras small_043.0946_201_cd76nc.pgm small_043.0946_201_cd76nc.ras small_043.2305_202_cd76na.pgm small_043.2305_202_cd76na.ras small_043.2305_202_cd76nb.pqm small_043.2305_202_cd76nb.ras small_043.2305_202_cd76nc.pgm small_043.2305_202_cd76nc.ras small_044.1225_203_cd76na.pgm small_044.1225_203_cd76na.ras small_044.1225_203_cd76nb.pgm small_044.1225_203_cd76nb.ras small_044.1225_203_cd76nc.pgm small_044.1225_203_cd76nc.ras TAR2 biq_046_1153_205_cd76na.pgm.Z big_046_1153_205_cd76nb.pgm.Z big_046_1153_205_cd76nc.pgm.Z big_047.0112_206_cd76nal.pgm.Z big_047.0112_206_cd76na2.pgm.Z big_047.0112_206_cd76nam.pbm.Z big_047.0112_206_cd76nax.pgm.Z big_047.0112_206_cd76nb.pgm.Z big_047.0112_206_cd76nc.pgm.Z big_047.1431_207_cd76na.pgm.Z big_047.1431_207_cd76nb.pgm.Z big_047.1431_207_cd76nc.pgm.Z small_046.1153_205_cd76na.pgm small_046.1153_205_cd76na.ras small_046.1153_205_cd76nb.pgm small_046.1153_205_cd76nb.ras small_046.1153_205_cd76nc.pgm small_046.1153_205_cd76nc.ras small_047.0112_206_cd76na.pgm small_047.0112_206_cd76na.ras small_047.0112_206_cd76nax.pgm small_047.0112_206_cd76nax.ras small_047.0112_206_cd76nb.pgm small_047.0112_206_cd76nb.ras small_047.0112_206_cd76nc.pgm small_047.0112_206_cd76nc.ras small_047.1431_207_cd76na.pgm small_047.1431_207_cd76na.ras small_047.1431_207_cd76nb.pgm small_047.1431_207_cd76nb.ras small_047.1431_207_cd76nc.pgm small_047.1431_207_cd76nc.ras TAR3 big_048.0350 208 cd76na.pgm.Z big_048.0350_208_cd76nb.pgm.Z big_048.0350_208_cd76nc.pqm.Z big_048.1708_209_cd76sa.pgm.Z big_048.1708_209_cd76sb.pgm.Z

```
big_048.1708_209_cd76sc.pgm.Z
 big_049.0628 210 cd76sa.pgm.Z
 big_049.0628_210_cd76sb.pgm.Z
 big_049.0628_210_cd76sc.pgm.Z
 small_048.0350_208_cd76na.pgm
 small 048.0350 208 cd76na.ras
 small_048.0350_208_cd76nb.pgm
 small_048.0350_208_cd76nb.ras
 small_048.0350_208_cd76nc.pgm
 small 048.0350 208 cd76nc.ras
 small 048.1708_209_cd76sa.pgm
 small_048.1708_209_cd76sa.ras
 small_048.1708_209_cd76sb.pgm
 small_048.1708_209_cd76sb.ras
 small_048.1708_209_cd76sc.pqm
 small_048.1708_209_cd76sc.ras
 small_049.0628_210_cd76sa.pgm
 small_049.0628_210_cd76sa.ras
 small 049.0628 210 cd76sb.pgm
 small_049.0628_210_cd76sb.ras
 small_049.0628_210_cd76sc.pgm
 small_049.0628_210_cd76sc.ras
 TAR4
big_049.1930_211_cd76sa.pgm.Z
 big_049.1930_211_cd76sb.pgm.Z
 big_049.1930_211_cd76sc.pgm.Z
big_050.0922_212_cd76sa.pgm.Z
big_050.0922_212_cd76sb.pgm.Z
big_050.0922_212_cd76sc.pgm.Z
big_050.2240_213_cd76sa.pqm.Z
big_050.2240_213_cd76sb.pgm.Z
big_050.2240_213_cd76sc.pgm.Z
small_049.1930_211_cd76sa.pqm
small_049.1930_211_cd76sa.ras
small_049.1930_211_cd76sb.pgm
small_049.1930_211_cd76sb.ras
small_049.1930_211_cd76sc.pgm
small_049.1930_211_cd76sc.ras
small_050.0922_212_cd76sa.pgm
small_050.0922_212_cd76sa.ras
small_050.0922_212_cd76sb.pgm
small_050.0922_212_cd76sb.ras
small_050.0922_212_cd76sc.pgm
small_050.0922_212_cd76sc.ras
small_050.2240_213_cd76sa.pgm
small_050.2240_213_cd76sa.ras
small_050.2240_213 cd76sb.pgm
small 050.2240_213_cd76sb.ras
small 050.2240 213 cd76sc.pcm
small_050.2240_213_cd76sc.ras
big_051.1158_214_cd76sa.pgm.Z
big_051.1158_214_cd76sb.pgm.Z
big_051.1158_214_cd76sc.pgm.Z
big_052.0117_215_cd76sa.pgm.Z
big_052.0117_215_cd76sb.pqm.Z
big_052.0117_215_cd76sc.pgm.Z
big_052.1438_216_cd76sa.pgm.Z
big_052.1438_216_cd76sb.pgm.Z
big_052.1438_216_cd76sc.pqm.Z
small_051.1158_214_cd76sa.pgm
small_051.1158_214_cd76sa.ras
small_051.1158_214_cd76sb.pgm
small_051.1158_214_cd76sb.ras
small_051.1158_214_cd76sc.pgm
small_051.1158_214_cd76sc.ras
small_052.0117_215_cd76sa.pqm
small_052.0117 215 cd76sa.ras
small_052.0117_215_cd76sb.pgm
```

```
small_052.0117_215_cd76sb.ras
 small_052.0117_215_cd76sc.pgm
 small_052.0117_215_cd76sc.ras
 small_052.1438_216_cd76sa.pgm
 small_052.1438_216_cd76sa.ras
 small_052.1438_216_cd76sb.pgm
 small_052.1438_216_cd76sb.ras
 small_052.1438_216_cd76sc.pgm
 small_052.1438_216_cd76sc.ras
 big_043.0038_200_cd76na.pgm.Z
 big_043.0038_200_cd76nb.pgm.Z
 big_043.0038_200_cd76nc.pqm.Z
 big_045.2234_204_cd76na.pgm.Z
 big_045.2234_204_cd76nb.pgm.Z
 big_045.2234_204_cd76ncl.pgm.Z
 big_045.2234_204_cd76nc2.pgm.Z
 big_045.2234_204_cd76ncm.pbm.Z
 big_045.2234_204_cd76ncx.pgm.Z
 big_053.0400_217_cd76sa.pgm.Z
 big_053.0400_217_cd76sb.pgm.Z
 big_053.0400_217_cd76sc.pgm.Z
small_043.0038_200_cd76na.pgm
 small_043.0038_200_cd76na.ras
 small_043.0038_200_cd76nb.pgm
 small_043.0038_200_cd76nb.ras
small_043.0038_200_cd76nc.pgm
small_043.0038_200_cd76nc.ras
small_045.2234_204_cd76na.pgm
small_045.2234_204_cd76na.ras
small_045.2234_204_cd76nb.pgm
small_045.2234_204_cd76nb.ras
small_045.2234_204_cd76nc.pgm
small_045.2234_204_cd76nc.ras
small_045.2234_204_cd76ncx.pgm
small_045.2234_204_cd76ncx.ras
small_053.0400_217_cd76sa.pgm
small_053.0400_217_cd76sa.ras
small_053.0400_217_cd76sb.pgm
small_053.0400_217_cd76sb.ras
small_053.0400_217_cd76sc.pgm
small_053.0400_217_cd76sc.ras
big_053.1720_218_cd76hsa1.pgm.Z
big_053.1720_218_cd76hsa2.pgm.Z
big_053.1720_218_cd76hsam.pbm.Z
big_053.1720_218_cd76hsax.pgm.Z
big_053.1720_218_cd76hsb.pgm.Z
big_053.1720_218_cd76hsc.pgm.Z
big_064.2350_219_cd76hsa.pgm.Z
big_064.2350_219_cd76hsb.pgm.Z
small_053.1720_218_cd76hsax.pgm
small_053.1720_218_cd76hsax.ras
small_053.1720_218_cd76hsb.pgm
small_053.1720_218_cd76hsb.ras
small_053.1720_218_cd76hsc.pgm
small_053.1720_218_cd76hsc.ras
small_064.2350_219_cd76hsa.pgm
small_064.2350_219_cd76hsa.ras
small_064.2350_219_cd76hsb.pgm
small\_064.2350\_219\_cd76hsb.ras
in directory CD76:
Enlargments
Magnetics
Small.pgm
Small.ras
in directory CD76/Enlargments:
big_213b_calderal.pgm.Z
med_213b_calderala.ras.Z
```

```
med_213b_calderalb.ras.Z
  med_213b_calderalc.ras.Z
  in directory CD76/Magnetics:
  mag_043.0038_200_cd76na.dat
  mag_043.0038_200_cd76nb.dat
  mag_043.0038_200_cd76nc.dat
  mag_043.0946_201_cd76na.dat
  mag_043.0946_201_cd76nb.dat
mag_043.0946_201_cd76nc.dat
  mag_043.2305_202_cd76na.dat
  mag_043.2305_202_cd76nb.dat
  mag_043.2305_202_cd76nc.dat
mag_044.1225_203_cd76na.dat
  mag_044.1225_203_cd76nb.dat
  mag_044.1225_203_cd76nc.dat
  mag_045.2234_204_cd76na.dat
  mag_045.2234_204_cd76nb.dat
  mag_045.2234_204_cd76ncl.dat
  mag_045.2234_204_cd76nc2.dat
  mag_046.1153_205_cd76na.dat
  mag_046.1153 205 cd76nb.dat
 mag_046.1153_205_cd76nc.dat
 mag_047.0112_206 cd76nal.dat
 mag_047.0112_206_cd76na2.dat
 mag_047.0112_206_cd76nb.dat
 mag_047.0112_206_cd76nc.dat
 mag_047.1431_207_cd76na.dat
 mag_047.1431_207_cd76nb.dat
 mag_047.1431_207_cd76nc.dat
mag_048.0350_208_cd76na.dat
 mag_048.0350_208_cd76nb.dat
 mag_048.0350_208_cd76nc.dat
 mag_048.1708_209_cd76sa.dat
 mag_048.1708_209_cd76sb.dat
 mag_048.1708_209_cd76sc.dat
 mag_049.0628_210_cd76sa.dat
 mag_049.0628_210_cd76sb.dat
 mag_049.0628_210_cd76sc.dat
 mag_049.1930_211_cd76sa.dat
 mag_049.1930_211_cd76sb.dat
 mag_049.1930_211_cd76sc.dat
mag_050.0922_212_cd76sa.dat
mag_050.0922_212_cd76sb.dat
mag_050.0922_212_cd76sc.dat
mag_050.2240_213_cd76sa.dat
mag_050.2240_213_cd76sb.dat
mag_050.2240_213_cd76sc.dat
mag_051.1158_214_cd76sa.dat
mag_051.1158_214_cd76sb.dat
mag_051.1158_214_cd76sc.dat
mag_052.0117_215 cd76sa.dat
mag_052.0117_215_cd76sb.dat
mag_052.0117_215_cd76sc.dat
mag_052.1438_216_cd76sa.dat
mag_052.1438_216_cd76sb.dat
mag_052.1438_216_cd76sc.dat
mag_053.0400_217_cd76sa.dat
mag_053.0400_217_cd76sb.dat
mag_053.0400_217_cd76sc.dat
mag_053.1720_218_cd76hsal.dat
mag_053.1720_218_cd76hsa2.dat
mag_053.1720_218_cd76hsb.dat
mag_053.1720_218_cd76hsc.dat
mag_064.2350_219_cd76hsa.dat
mag_064.2350_219_cd76hsb.dat
in directory CD76/Small.pgm:
-duplicates of the small.pgm files in TAR 1-6
in directory CD76/Small.ras:
-duplicates of the small ras files in TAR 1-6
```

```
in directory darwin:
 man
 in directory darwin/bin:
 Makefile2
                                     - a makefile for tobi processing programmes
 itd2.c
                                     - an indexing programme for tobi data, not used on this cruise
 mkimages2
 pbmplus.tar.Z
 pgmmag
                                     - a shellscript for producing enlargements, and viewing in Alv
pgmvu2
                                     - a shellscript for viewing tobi images using Alv
ptd2
ptd2.c
rmag2
rmag2.c
rmag3
rmag3.c
rtd2
rtd2.c
side2pgm
side2pgm.c
xloadimage
in directory darwin/man:
manl
man2
man3
man5
in directory darwin/man/man1:
-all PBMPlus process manual pages
in directory darwin/man/man2:
itd2.2
mkimages2.2
ptd2.2
rmag2.2
rmag3.2
rtd2.2
side2pgm.2
in directory darwin/man/man3:
-all PBMPlus library manual pages
in directory darwin/man/man5:
```

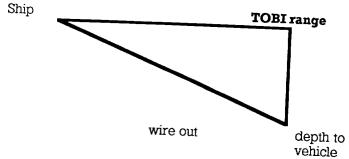
-all PBMPlus image format manual pages

4 TOBI MOSAICING AND NAVIGATION

4.1 TOBI MOSAIC

First stage:

TOBI position relative to the ship's position was estimated every 15 min by a range calculation involving a simple trigonometric relation between the length of the wire out and the depth to the vehicle.



Each ship postion and subsequently each TOBI position were plotted on a 1:50000 Sea Beam bathymetry map from the C2912 survey (Sempéré et al., 1990), TOBI positions being estimated by using the calculated range and the water depth measured from the vehicle's altitude and depth meter and cross-referencing this with the depth given on the bathymetry chart.

Mosaic base charts were prepared by tracing straight synthetic TOBI track lines to fit as many plotted TOBI positions as possible and projecting these position on to the lines at every half hour. The distance between the projected half hour positions was measured and then used in production/replay of TOBI images at a scale of 1:50000. Using these measured distances the speed over the ground along a straight line was calculated and the sidescan images anamorphosed to convert from a time to a distance plot. Taking the half hour time marks as a first guide the images were matched as closely as possible to the bathymetry, cutting the swaths to accommodate course changes where necessary. Where the swaths overlap, images were spliced by trimming away the "shadowed" portions at the edge of the swaths. Wherever substantial gaps or overlaps occured along track, the distance between half hour time marks was re-measured.

Second stage:

The side scan images were replayed correcting for the re-measured distance portions of the swaths. The turns were separately anamorphosed by expanding the outside of the turn and compressing the inside. Fitting the side scan images with the bathymetry was then accomplished and a more complete image achieved.

Digital mosaic:

Digital mosaicing can be completed at IOS using MIPS/WHIPS packages. Merging of some of the images with the bathymetry will then be possible.

Appendix 1: Cruise Log

4-Feb	Date		Time (GMT)	Event
(10.25kHz) echosounders deployed 6-Feb 037 13:05 Cravimeter down, platform stability problems: Switched off and under repair 1st Figure 8 manoeuvre for 3-component magnetometer calibration GFS data unstable 19:30 PES no printed display, under repair PES down PES link back up, poor signal 7-Feb 038 03:00 PES down Res down, not pinging- under repair PES link down, not pinging- under repair 8-Feb 039 9-Feb 040 14:30 Gravimeter down 17:30 Gravimeter down 18:30 Magnetometer and echosounders on deck WASP leade deployment, sledge in water- run 1 WASP sledge on deck, after successful test run Magnetometer and Echosounders back in water Off-axis magnetics run M1-M2-M3-M4 including 2nd Figure 8 manoeuvre for 3- component magnetometer calibration 10-Feb 041 10:04 Arriving at TOBI deployment site, T1 Magnetometer on deck 11:25 Cable test passed, Depressor weight in water 2/RFs sensor failure, TOBI to be recovered 13:30 TOBI on deck, ship turning and returning to T1 Off-axis magnetics run M5-M6-M7-M8, whilst ZAPS is tested and repaired 15:22 TOBI and ZAPS ready, magnetics run cut short, return to T1 16:15 Magnetometer on deck 16:30 TOBI in water continued problems with ZAPS Many resulting test deployments fail to remedy the problematic ZAPS sensor for the next day Magnetometer in water for off-axis magnetics run M9-M10-M11-M12 11-Feb 042 09:25 Arrival at T1, magnetometer being recovered TOBI in water 17:20 TOBI in water 17:20 TOBI in water 18:20 TOBI in water 18:20 TOBI in water 18:20 TOBI in water 19:20 TOBI in	4-Feb	035	10:00	Depart Port of Spain, Trinidad In transit to waypoint W1
Switched off and under repair 15:00	5-Feb	036	23:50	
15:00	6-Feb	037	13:05	Gravimeter down, platform stability problems: Switched off and under repair
19:30 PES no printed display, under repair PES link back up, poor signal 7-Feb 038 03:00 PES down Gravimeter repaired and working PES link down, not pinging- under repair PES link down, not pinging- under repair PES link down, not pinging- under repair PES back up 9-Feb 039 07:30 PES back up 9-Feb 040 14:30 Gravimeter down Gravimeter back up 18:30 Magnetometer and echosounders on deck up. 18:30 Magnetometer and echosounders on deck up. 19:15 WASP test deployment, sledge in water- run 1 WASP sledge on deck, after successful test run Magnetometer and Echosounders back in water Off-axis magnetics run M1-M2-M3-M4 including 2nd Figure 8 maneouvre for 3-component magnetometer calibration 10-Feb 041 10:04 Arriving at TOBI deployment site, T1 Magnetometer on deck TOBI in water 12:34 ZAPS sensor failure, TOBI to be recovered 13:30 TOBI on deck, ship turning and returning to T1 Off-axis magnetics run M5-M6-M7-M8, whilst ZAPS is tested and repaired 15:22 TOBI and ZAPS ready, magnetics run cut short, return to T1 Magnetometer on deck TOBI in water, continued problems with ZAPS Magnetometer in water for off-axis magnetics run M9-M10-M11-M12. 11-Feb 042 09:25 Arrival at T1, magnetometer being recovered 12:20 TOBI logging started Interference on TOBI images, 5.5Hz related to nephelometer flash light			15:00	1st Figure 8 manoeuvre for 3-component magnetometer calibration
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Magnetometer in water for off-axis magnetics run M9-M10-M11-M12 11-Feb 042 09:25 Arrival at T1, magnetometer being recovered 11:20 TOBI in water 12:20 TOBI logging started Interference on TOBI images, 5.5Hz related to nephelometer flash light TOBI pressure gauge malfunctioning				the problematic 7APS sensor for the post day
11-Feb 042 09:25 Arrival at T1, magnetometer being recovered 11:20 TOBI in water 12:20 TOBI logging started Interference on TOBI images, 5.5Hz related to nephelometer flash light TOBI pressure gauge malfunctioning			23:09	Magnetometer in water for off-axis magnetics
11:20 TOBI in water 12:20 TOBI logging started 14:00 Interference on TOBI images, 5.5Hz related to nephelometer flash light TOBI pressure gauge malfunctioning				run M9-M10-M11-M12
11:20 TOBI in water 12:20 TOBI logging started 14:00 Interference on TOBI images, 5.5Hz related to nephelometer flash light TOBI pressure gauge malfunctioning	ll-Feb	042	09:25	Arrival at T1, magnetometer being recovered
12:20 TOBI logging started 14:00 Interference on TOBI images, 5.5Hz related to nephelometer flash light TOBI pressure gauge malfunctioning			11:20	TOBI in water
14:00 Interference on TOBI images, 5.5Hz related to nephelometer flash light TOBI pressure gauge malfunctioning				TOBI logging started
nephelometer flash light TOBI pressure gauge malfunctioning			14:00	Interference on TOBI images, 5.5Hz related to
TOBI pressure gauge malfunctioning				nephelometer flash light
15:35 TOBI at 300m altitude				TOBI pressure gauge malfunctioning
			15:35	TOBI at 300m altitude

		16.00	Hauling TODI back up to your de
		16:00	Hauling TOBI back up to remedy pressure gauge and interference problems
		18:34	TOBI on deck
12-Feb	043	00:06	TOBI in water at T1, temperature sensor not connected
		00:37	TOBI logging restarted, aim to fly TOBI at around 300m
		05:42	T2 waypoint reached
		07:30	T3 waypoint reached
		12:25	TOBI scrapes bottom, 300m pinnacle not on
		12.00	charts
		13:00	T4 waypoint reached
13-Feb	044	00:13	TS waypoint reached
	• • • • • • • • • • • • • • • • • • • •	06:15	T6 waypoint reached
		15:15	T7 waypoint reached
		19:40	T8 waypoint reached
		23:12	T9 waypoint reached
		23:45	Noise on TOBI images, variable speed and
		20.10	pitch consistent with 1kt tail current
14-Feb	045	00:07	TOBI transmitter turned on/off in an attempt to
			remedy noise problems
		00:11	Everything off, cable/power short circuit?
		00:22	TOBI logging stopped, TOBI being recovered
		04:09	TOBI on deck
		04:30	Off-axis magnetics run M13-M14-M15-M16,
			magnetometer in water includes 3rd Figure 8
			for 3-component magnetometer calibration
		15:00	Magnetometer on deck
		16:00	TOBI umbilical cable replaced, temperature
			sensor replaced and connected
		18:57	TOBI deployed at waypoint T8, retracing path
			of previous day's poor imagery
			ZAPS recharged and recalibrated during time
			spent repairing TOBI
15-Feb	046	00:32	T9 waypoint reached on the 2nd pass
		08:45	T10 waypoint reached
		14:30	Tll waypoint reached
		20:15	Magnetometer in water
10.71	.		
16-Feb	047	06:00	T12 waypoint reached
		07:45	T13 waypoint reached
		13:15	T14 waypoint reached
		18:55	T15 waypoint reached
17-Feb	048	19:30	T16 waypoint reached
		22:00	T17 waypoint reached
18-Feb	049	05:15	T18 waypoint reached
		14:30	T19 waypoint reached
		19:15	T20 waypoint reached
19-Feb	050	01.20	
19-Len	050	01:35	T21 waypoint reached
		12:15	T22 waypoint reached
		22:45	T23 waypoint reached
20-Feb	051	06:00	T24 waypoint reached
		13:15	T25 waypoint reached
		18:50	T26 waypoint reached
		23:40	T27 waypoint reached

21-Feb	052	10:30	T28 waypoint reached
		16:30	T29 waypoint reached
		20:30	T30 waypoint reached
22-Feb	053	05:15	T31 waypoint reached
		11:15	T32 waypoint reached
		16:30	Magnetometer off and being recovered in
			preparation for TOBI recovery
		19:01	TOBI on deck, end of scheduled survey
		19:05	Magnetometer in water
		10.00	Analysis of TOBI physical data suggests
			location of a possible hydrothermal plume
			around Station 1
			Resulting transit to Station 1 follows, via
			gravimetry way points T33, G1-G7, S1
			gravitienty way points 135, G1-G1, 51
23-Feb	054	15:00	Arrived at station S1
		16:00	Magnetometer on deck
		16:46	ZAPS sledge deployment
		22:17	ZAPS sledge on deck
		22:37	Arrived on station S2
		22:50	ZAPS sledge in water
		20.00	En o sieage in water
24-Feb	055	01:00	Positive signals from ZAPS/ transmissometer/
		01.00	nephelometer indicating plume at about
			2390m
		01:40	
		04:43	In vicinity of hydrothermal plume. ZAPS sledge on deck
		05:13	ZAPS sledge deployment at S3
		08:12	Recovery of ZAPS sledge
		10:53	Arrived at station S4
		11:20	ZAPS sledge deployment
		17:58	ZAPS sledge on deck
		18:17	Arrived at station S5
		18:22	ZAPS sledge deployment
		23:40	ZAPS sledge on deck
		20.10	211 b steage off deck
25-Feb	056	00:10	Arrived at station S6
		00:20	ZAPS sledge deployment
		02:31	ZAPS sledge on deck
		03:40	ZAPS sledge deployment
		07:00	Drifting with 7APS glodge to station 97
		08:43	Drifting with ZAPS sledge to station S7 ZAPS sledge on deck
		08:49	ZAPS sledge deployment at S7
		12:30	Drifting with 7ADS aladge to station 50
		14:00	Drifting with ZAPS sledge to station S8
		16:30	Drifting with ZAPS sledge to station S9 ZAPS sledge on deck
		17:05	
		20:30	ZAPS sledge deployment at S9 Problems with ZAPS
		21:30	
		21.50	Simrad 10.25kHz off to check interferences
		21:45	with ZAPS sledge signals
		22:20	Simrad back on ZAPS blown out
		23:10	
		20.10	ZAPS sledge on deck
26-Feb	057	00:05	Traverging from S0 to C10.
	501	00.00	Traversing from S9 to S10: watching Simrad
		00:35	topography to locate ridge crest
		00:46	Station S10 located at 29° 08.6'N, 43° 10.75'W
		UF. UU	ZAPS sledge deployment at S10 (without ZAPS sensor)
		08:30	ZAPS sledge on deck
		08:33	Arrived at S11
		00.00	THITACK OF DIT

		08:33 12:30 13:05	ZAPS sledge deployment ZAPS sledge on deck Arrived at S12
		13:05 20:30	ZAPS sledge deployment ZAPS sledge on deck Sledge operations suspended due to bad
			weather
27-Feb	058	00:30	Start of magnetics run
		09:10	Last magnetics waypoint
		09:52	Magnetometer on deck
		10:10	Steaming to \$13
		10:26	ZAPS sledge deployment at S13
		18:01	Bottom temperature anomaly found at 29° 10.25'N, 43° 10.25'W
		23:00	ZAPS sledge on deck
28-Feb	059	00:00	Start of dredging: dredge D1 abandoned due to ship overshooting target
		00:31	Dredge D2 deployed target 29° 10.25'N, 43° 10.25'W
		08:00	Dredge on board
		08:20	Dredge D3 deployed target as D2
		11:07	Dredge D3 off bottom and being recovered
		14:15	Dredge D4 deployed
		16:26	Dredge D4 on deck
			Dredge D5 deployed-target is line running
			NNE to 29° 10.25'N, 43° 10.25'W
		20:50	Dredge D5 on deck
l-Mar	060	00:10	Acoustic net deployment:
			Deployment of transponder 1 [29° 09.25'N, 43° 11.70'W, water depth 3150m]
		01:15	Deployment of transponder 2 [29° 11.50′N, 43° 10.90′W, water depth 3075m]
		02:30	Deployment of transponder 3 [29° 10.40'N, 43° 08.70'W, water depth 3275m]
		03:36	Deployment of transponder 4 [29° 08.50°N, 43° 10.70°W, water depth 3025m] Start of acoustic navigation GPS tie lines
		10:50	End of acoustic navigation GPS tie lines
		11:03	Dredge D6 deployed
		13:59	Dredge D6 off bottom
			Restart of acoustic navigation GPS tie lines
		22:30	Finished acoustic navigation GPS tie lines
2-Mar	061	01:36	ZAPS sledge deployment at \$14
		08:00	Sledge cannot see transponder net when near bottom
		09:31	Firing 5 litre Niskin bottles Nos. 1,2,4,6 at 2700m
		09:39	Firing 5 litre Niskin bottles Nos. 8,10 at 2500m
		11:09	ZAPS sledge on deck- water sampled for radon analysis
		12:38	WASP sledge deployment with transponder 200m up cable- run 2
		17:25	WASP on deck
		18:45	Dredge D7 deployed with pinger 200m up on cable
		23:45	Dredge D7 on deck

3-Mar	062	02:45 11:23 11:30 19:45 23:52	WASP deployed- run 3 WASP on deck Weather worsening Dredge D8 deployed Dredge D8 on deck
4-Mar	063	01:40 11:10 13:10 17:30	WASP deployed- run 4 WASP on deck WASP deployed- run 5 WASP on deck- sulfides discovered on top of WASP frame, thought to be related to large transmissometer spike during run 4, 063-04:17 (demolition of chimney?)
		19:30 22:32	Trial dip of JBP (Jason's birthday plunger) at 29° 10.156'N, 43° 10.263'W
		22.02	Recovery of JBP- watchkeeper notes "Thing on deck- nothing"
5-Mar	064	00:20 02:00	Dredge D9 deployed Dredge D9 on deck- cancelled due to bad weather
		11:20	TOBI deployed, attempting to image hydrothermal vent field
		12:50	TOBI logging started
		14:30	Chaos watch starts TOBI position logging
		18:10	TOBI images area of hydrothermal activity
6-Mar	065	01:40	Start of TOBI vehicle recovery
		02:53	TOBI wire not laying properly: wire out= 3000m
		05:59	TOBI on deck, wire problem not resolved
		06:30	Start acoustic net recovery
		12:40	Acoustic net recovery completed
		13:58 18:32	Dredge 9 in the water
		19:25	Dredge 9 on deck Magnetometer in water
		10.20	Transit to the Azores
7-Mar	066		
8-Mar	067		Conducting cable payed out and respooled
9-Mar	068		
10-Mar	069		
ll-Mar	070		

Appendix 2: CD76 Waypoints

Way 1	Point	Position						
				tude	N	Long	itude	w
W	71	WASP-Test	26°	40.00	יכ	44°	43.20	,
M		Magnetics	26°	38.89		44°	42.34	
M			26°	32.49	9'	43°	36.19	
M	3		26°	32.08	3'	43°	37.78	
M	4		26°	46.19	ı*	44°	27.30	
M	5		26°	53.31	•	44°	33.19	
M	6		27°	05.46		45°	31.03'	
M	7		26°	59.70		45°	29.93	
M	8		26°	47.48		44°	32.23	
M			28°	29.62		43°		
M			28°	21.10		43°	39.00	
M			28°	15.47			57.65	
M			28°	25.08		42°	59.91'	
M:			29°			43°	42.51'	
Mi			29°	14.46		43°	08.41'	
M:				22.67		43°	45.88'	
M			29° 29°	17.37		43°	47.75'	
1411	10		29-	10.93	1	43°	10.44'	
TI		lst TOBI track	26°	48.00	, 4	44°	34.00'	
T2				00.00		44°	29.10'	
ТЗ				05.70		44°	27.50	
T4				15.20		44°	18.30'	
T5				39.40		44°	09.50	
T6				49.30		44°	00.90	
T7		•		06.80		43°	57.00'	
Т8				15.00		43°	51.10	
Т9				22.90		43°	44.20'	
Tle				37.85		43°	44.20	
Tl				43.75		43°		
Tl				55.90		43°	29.70'	
TI				10.65'			13.40'	
T14				20.70		43°	10.40'	
T15				20.10 24.60'		43°	06.90'	
TIE		End 1st track		24.00 06.00'		42° 42°	55.30'	
							43.60'	
T17 T18		Start 2nd track		05.40		42°	40.80'	
TIS				51.10'		42°	46.60'	
T20				30.85		42°	51.15'	
T21				22.40		42°	53.75'	
T22				17.80		43°	07.25	
T23				55.95		43°	10.35'	
T24				41.30		43°	29.25'	
T25				35.82		43°	38.50'	
				21.40'		43°	41.60'	
T26				13.85		43°	48.95'	
T27				06.25		43°	55.00'	
T28				46.75'		43°	59.35'	
T29				37.80		44°	07.10	
T30				29.95'	1	44°	10.25'	
T31				14.00'		44°	15.35'	
T32 T33		71 10 1: :		04.30		44°	24.60'	
1033	5	End 2nd track	26° 4	16.00		44°	31.50'	

G1 G2 G3 G4 G5 G6 G7	Gravimetry	27° 27° 27° 28° 28° 29°	16.00' 26.00' 56.00' 58.00' 39.00' 57.00' 01.00'	44° 44° 43° 43° 43° 43°	03.00' 20.00' 10.00' 50.00' 16.00' 22.00' 06.00'
S1 S2 S3 S4 S5 S6 S7 S8 S9 S10 S11 S12 S13 S14	ZAPS sledge	29° 29° 29° 29° 29° 29° 29° 29° 29°	08.20' 08.40' 08.58' 09.45' 10.35' 08.40' 09.02' 09.30' 08.15' 08.60' 07.80' 10.40' 10.65' 10.25'	43° 43° 43° 43° 43° 43° 43° 43° 43° 43°	11.05' 12.06' 12.30' 10.90' 11.00' 11.20' 10.91' 11.30' 11.25' 10.75' 11.00' 10.40' 10.15' 10.25'

Appendix 3: TOBI Navigation Log

Jul: Day			robi at. N		'OBI 1. W	Water	TOBI	TOBI
(dd			g. min.)	Lo ı (de	g. min.)	Depth (m)	Altitude	Depth
							(m)	(m)
43	4:30	20		44	29.56	3503	451	3954
43 43	5:00	27		44	29.50	3412	504	3916
43	5:30 6:00	27		44	28.80	3320	601	3921
43	6:30	27 27		44	28.38	3263	395	3658
43	7:00	27		44 44	28.12 27.82	3326 3387	345	3671
43	7:30	27		44	27.47	3465	259 235	3646
43	8:00	27		44	26.65	255	235	3700
43	8:30	27		44	25.82	333		
43	9:00	27		44	25.00	3271	301	3572
43	9:30	27		44	24.30	3160	263	3423
43	10:00	27		44	23.64	3068	405	3473
43	10:30	27	10.80	44	22.50	3114	233	3347
43	11:00	27	11.75	44	21.85	3025	314	3339
43	11:30	27		44	21.31	3252	324	3576
43	12:00	27	13.26	44	20.54	3469	208	3677
43 43	12:35	27	14.48	44	19.64	3360	455	3815
43 43	13:00 13:30	27 27	15.15 16.00	44	19.53	3531	311	3842
43	14:00	27	16.64	44 44	18.32 18.12	3574	370	3944
43	14:15	27	17.23	44	17.90	3559 3606	453 510	4012
43	14:45	27	18.14	44	17.52	3444	519 582	4125 4026
43	15:00	27	18.72	44	17.18	3456	549	4025
43	15:15	27	19.20	44	16.90	3475	608	4083
43	15:30	27	19.90	44	16.70	3516	703	4219
43	15:45	27	20.40	44	16.40	3487	500	3987
43	16:00	27	20.90	44	16.20	3413	504	3917
43	16:15	27	21.00	44	16.30	3350	586	3936
43	16:30	27	22.30	44	15.80	3310	514	3824
43 43	16:45 17:00	27	22.80	44	15.45	3289	378	3667
43 43	17:10	27 27	23.55 23.80	44	15.45	3317	394	3711
43	17:15	27	24.00	44 44	15.40 15.30	3323	251	3574
43	17:30	27	24.00	44 44	14.95	3321 3217	214	3535
43	17:45	27	25.70	44	14.50	3127	200	3417
43	18:00	27	26.25	44	14.30	3094	311 303	3438
43	18:15		27.00	44	14.10	3085	267	3397 3352
43	18:30	27	27.62		13.92	3048	166	3214
43	18:45	27	28.15		13.62	2984	322	3306
43	19:00		28.90	44	13.40	2987	336	3323
43	19:15	27	29.35		13.20	3060	329	3389
43	19:30		29.90		13.15	3070	356	3426
43	19:45	27	30.45		12.85	3084	311	3395
43 43	20:00	27	31.00		12.75	3087	314	3401
43 43	20:15 20:30	27	31.50		12.50	3083	227	3310
43 43	20:30	27 27	32.15		12.40	2991	252	3243
43	20.45		32.60 33.20		12.10 11.95	3029	315	3344
43	21:15	27	33.60		11.60	3129 3215	260	3389
43	21:30	27	34.10		11.45	3221	43 356	3558
43	21:45	27	34.70		11.25	3272	318	3577 3590
			•				010	0000

43 43 43 43 43 44 44 44 44 44 44 44	21:45 22:00 22:15 22:30 22:45 23:00 23:15 23:30 0:00 0:15 0:30 0:45 1:00 1:15 1:30 1:45	27 27 27 27 27 27 27 27 27 27 27 27	35.00 35.50 35.50 35.60 37.00 37.50 38.00 38.35 39.00 39.32 39.66 40.13 40.42 40.80 41.28	44 44 44 44 44 44 44 44 44 44 44 44	11.25 11.10 10.85 10.80 10.60 10.45 10.40 10.25 9.97 9.82 9.75 9.42 9.05 8.75 8.15 7.77 7.50	3272 3293 3323 3294 3350 3338 3378 3469 3448 3501 3532 3566 3581 3592 3632 3632 3634 3461	318 279 230 309 340 385 286 270 251 245 275 170 204 260 262 367 383	3590 3572 3553 3603 3690 3723 3664 3739 3699 3746 3807 3736 3785 3852 3894 3901 3844
44	2:00	27	42.03	44	7.15	3444	265	3709
44 44	2:15 2:30	27 27		44	6.80	3270	326	3596
44	2:45	27		44 44	6.35 6.05	3181 3133	512 518	3693 3651
44	3:00	27	43.82	44	5.75	3102	371	3473
44	3:15	27		44	5.30	3184	251	3435
44 44	3:30 3:45	27 27		44 44	5.00 4.70	3199 3245	285	3484
44	4:00	27		44	4.30	3344	391 392	3636 3736
44	4:15	27	45.60	44	4.10	3452	333	3785
44	4:30	27		44	3.70	3506	315	3821
44 44	4:45 5:00	27 27		44	3.40	3444	380	3824
44	5:15	27		44 44	3.10 2.50	3381 3353	514 553	3895
44	5:30	27		44	2.20	3371	437	3906 3808
44	5:45	27	48.20	44	1.70	3261	234	3495
44	6:00	27		44	1.50	3111	410	3521
44 44	6:15 6:30	27 27		44 44	0.90 0.80	3014	400	3414
44	6:45	27		44	0.60	2887 2757	367 340	3254 3097
44	7:00	27	51.10	44	0.50	2734	528	3262
44	7:15	27	51.70	44	0.40	2755	483	3238
44 44	7:30 7:45	27		44	0.30	2785	271	3056
44	8:00		52.70 53.30	44 44	0.25 0.05	2798 2810	270 341	3068
44	8:15	27		44	0.05	2869	205	3151 3074
44	8:30	27	54.50	44	0.00	2904	196	3100
44	8:45	27	55.00	43	59.70	2855	164	3019
44 44	9:00 9:15	27 27	55.60 56.15	43 43	59.60 59.20	2789	379	3168
44	9:30	27	56.60	43 43	59.20 59.30	2832 2887	360 325	3192
44	9:45	27	57.01	43	59.30	2930	319	3212 3249
44	10:00	27	57.45	43	59.15	2965	308	3273
44	10:15	27	57.88	43	59.05	3089	228	3317
44 44	10:30 10:45	27 27	58.32 58.84	43 43	58.97 58.85	3103	239	3342
44	11:00	27		43	58.80	3107 3167	239 315	3346 3482
44	11:15	27	59. 70	43	58.71	3225	254	3479
44	11:30	28	0.22	43	58.59	3295	180	3475
44 44	11:45 12:00	28 28	0.58	43	58.48	3278	230	3508
77	12.00	40	0.98	43	58.49	3336	165	3501

44 44 44 44 44 44 44 44 44 44 44 44 44	12:15 12:30 12:50 13:00 13:15 13:30 13:45 14:00 14:15 14:30 14:45 15:00 15:15 15:30 15:45 16:00 16:15 16:30 17:45 18:00 17:15 17:30 17:45 18:00 18:15 18:30 18:45 19:00 19:15 19:30 20:45	28 1.62 28 2.12 28 2.65 28 2.85 28 3.35 28 3.78 28 4.27 28 4.62 28 5.02 28 5.48 28 5.87 28 6.17 28 6.70 28 7.20 28 7.60 28 8.30 28 8.30 28 8.30 28 10.00 28 10.20 28 10.20 28 11.20 28 11.70 28 12.30 28 12.70 28 13.80 28 14.20 28 14.65 28 15.15 28 15.70 28 16.10 28 16.40 28 16.80	43 43 43 43 43 43 43 43 43 43 43 43 43 4	58.50 58.28 58.08 58.00 57.86 57.75 57.65 57.50 57.40 57.15 57.08 57.00 56.70 56.40 56.30 56.30 56.30 56.40 56.30 56.30 55.70 55.50 54.60 54.50 54.50 54.50 54.50 54.50 54.50 53.70 53	3297 3173 3117 3078 3085 3105 3072 3181 3239 3264 3409 3519 3458 3458 3453 3352 3309 3379 3385 3285 3214 3245 3278 32904 3180 3101 2933 2904 2877 2916 2935 2938 2868 2881 2887	253 379 486 575 494 509 622 350 318 365 290 202 160 299 333 373 325 329 366 325 321 272 236 315 245 323 320 330 311 367 257 336 367 373	3550 3552 3603 3653 3653 3614 3694 3531 3629 3721 3618 3732 3685 3682 3704 3714 3651 3539 3566 3550 3486 3550 3425 3224 3227 3227 3227 3227 3227 3227 3204 3248 3260
44 44	21:00 21:15	28 17.25 28 17.55	43 43	49.60 49.30	2992 3055	379 328	3371 3383
44 44	21:30 21:45	28 18.00 28 18.40	43 43	48.90 48.55	3092 3035	224 327	3316 3362
44 44	22:00 22:15	28 18.75 28 19.20	43 43	48.35 47.95	3043 3156	44 218	3387 3374
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47 47	16:15 16:30		23.15 23.29	42 42	59.83 59.46	2087 2229	532 497	2619
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47 47	17:45 18:00		23.80 23.91	42 42	57.53 57.10	3163 3166	275 319	3438 3485
47	18:30	29	24.25	42	56.25	3317	418	3735
47 47	18:45 19:00		24.48 24.96	42 42	55.80 55.42	3384 3263	240 314	3624
47	19:15	29	25.45	42	55.20	3120	614	3577 3734
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48 9:30 29 50.00 42 48.20 2588 385 29 48 9:45 29 50.60 42 48.05 2570 272 28 48 10:00 29 50.90 42 47.90 2569 331 29 48 10:15 20 10.15 20 10.15 20 10.15 20 10.15	47 48 48 48 48 48 48 48 48 48 48 48 48 48	9:45 10:00	999999999999999999999999999999999999999	30.20 30.75 31.25 31.25 32.30 32.56 33.32 33.31 34.20 33.35 35.35 36.55 37.42 38.72 38.72 38.72 38.72 40.02 40.72 41.15 42.90 43.27 43.80 44.32 44.65 47.10 48.50 48.50 49.60 50.60	42 42	48.05 47.90	2570 2569	272 331	362 363 363 363 363 363 363 363
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49 13:00 29 33.80 42 50.40 3285 338 36. 49 13:15 29 33.27 42 50.54 3326 235 35 49 13:30 29 32.68 42 50.62 3294 273 35 49 13:45 29 32.20 42 50.60 3274 333 36 49 14:00 29 31.80 42 50.89 3241 345 35 49 14:15 29 31.26 42 50.90 3280 310 35 49 14:30 29 30.80 42 50.99 3306 337 36 49 14:45 29 30.35 42 51.17 3364 320 36 49 15:00 29 29.90 42 51.30 3374 265 36 49 15:15 29 29.35 42 51.60 3117 371 34 49 15:45 29 28.82 42 <td>49 49</td> <td>12:15 12:30</td> <td>29 29</td> <td>35.12 34.70</td> <td>42 42</td> <td>50.17 50.23</td> <td>3146 3188</td> <td>415 362 379</td> <td>3535 3508 3567</td>	49 49	12:15 12:30	29 29	35.12 34.70	42 42	50.17 50.23	3146 3188	415 362 379	3535 3508 3567
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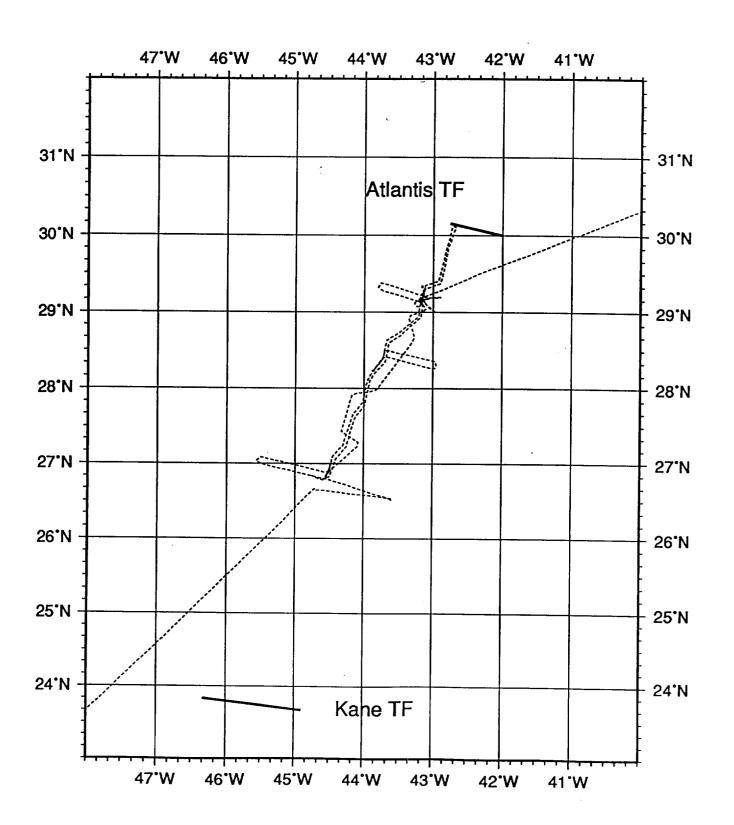
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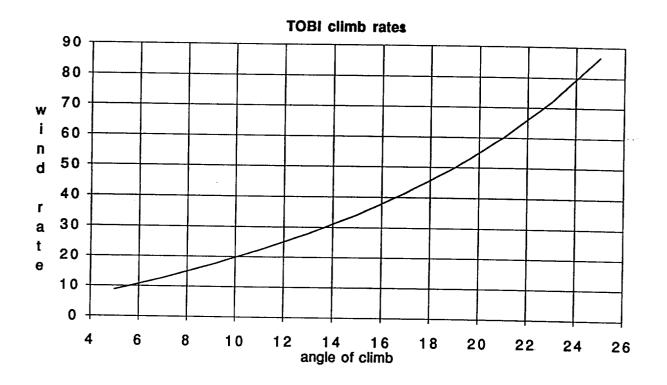
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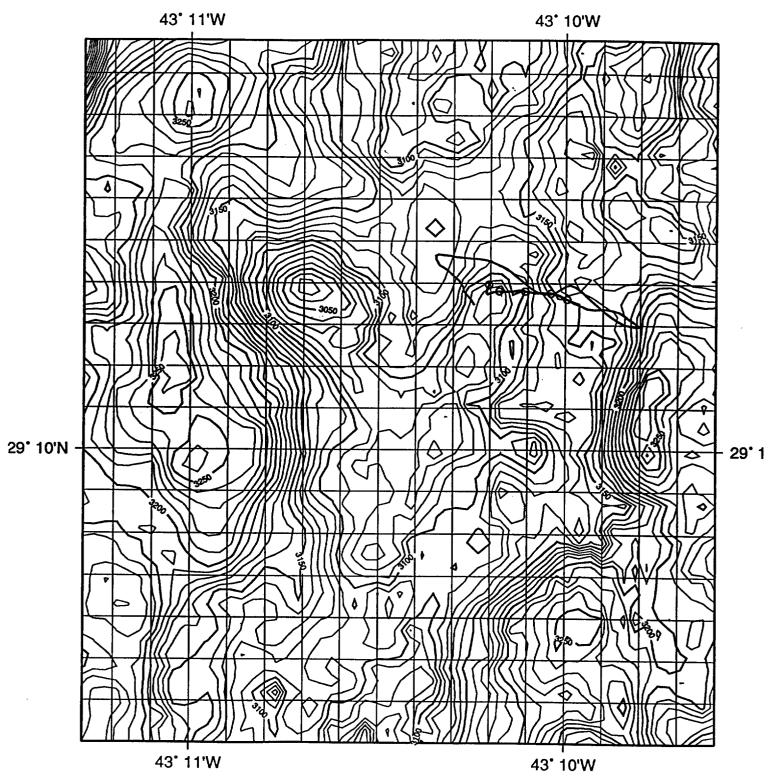
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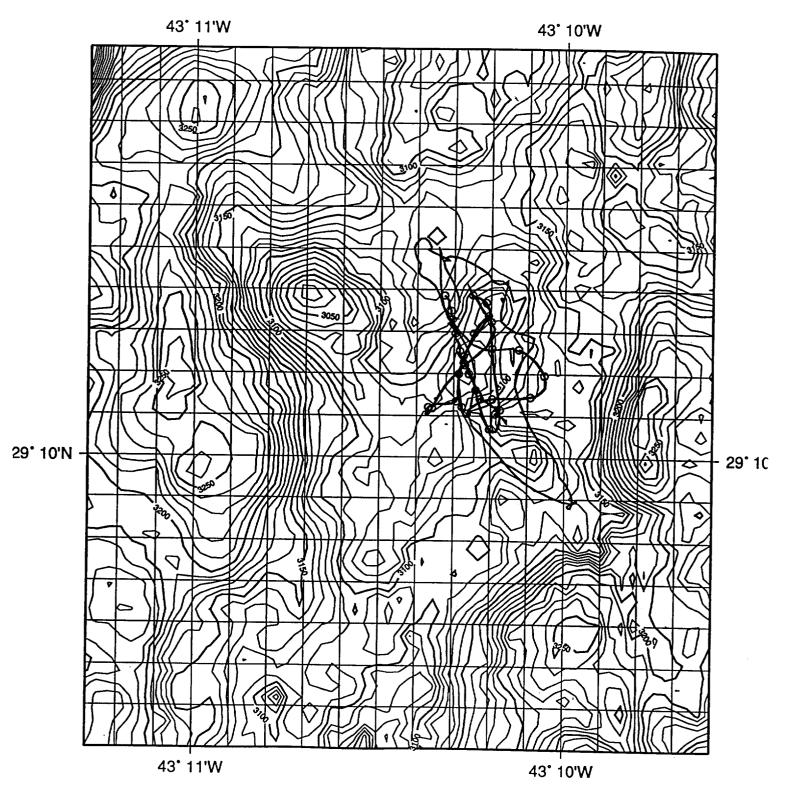
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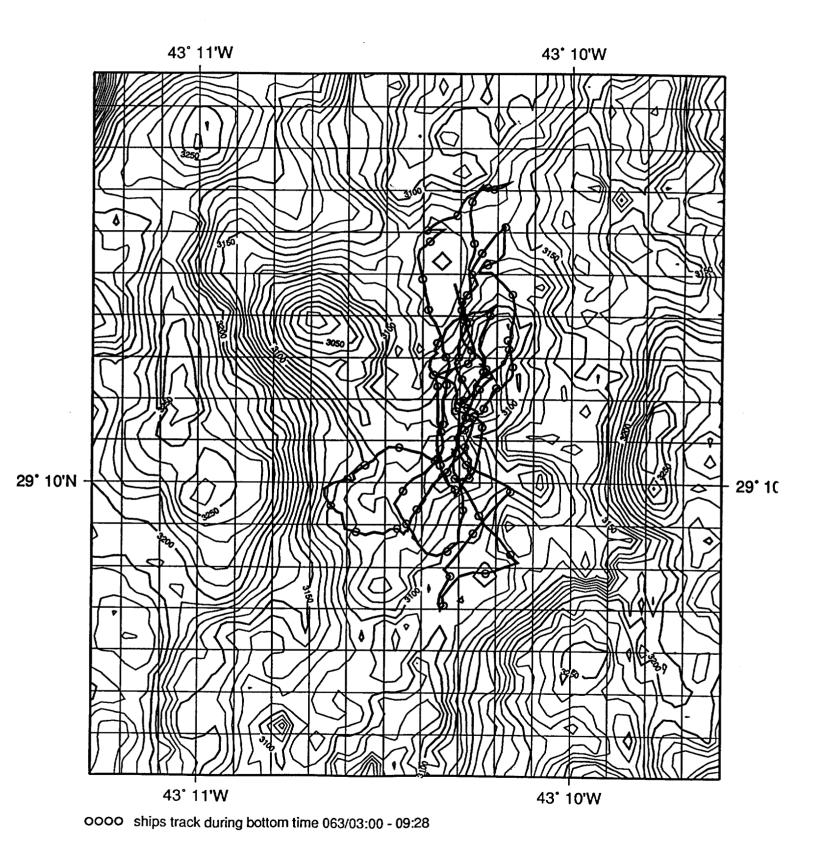


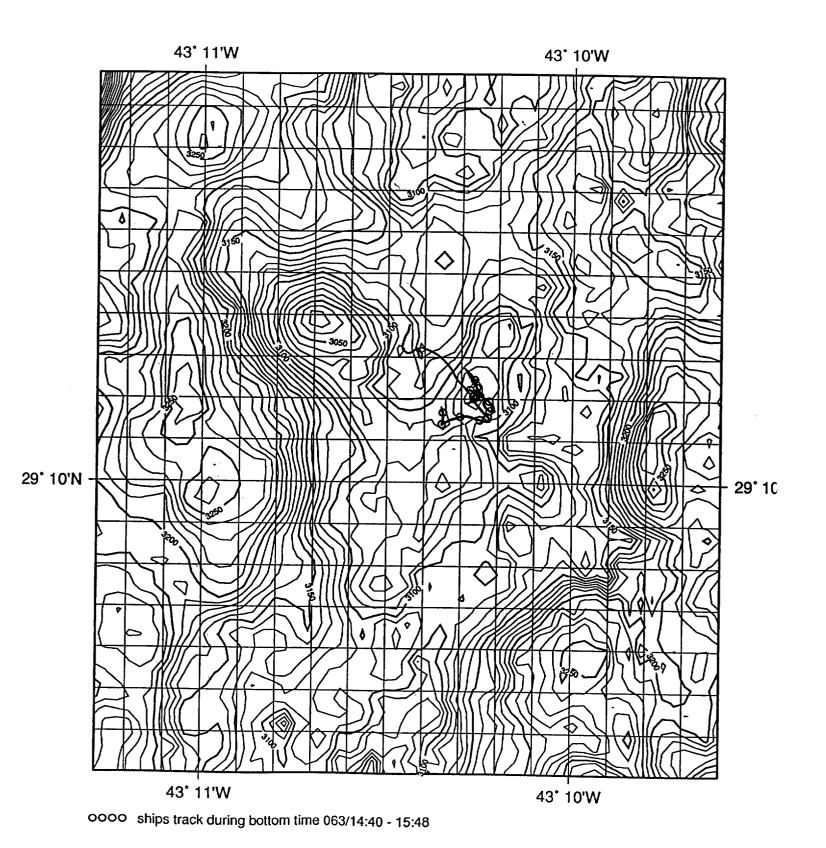


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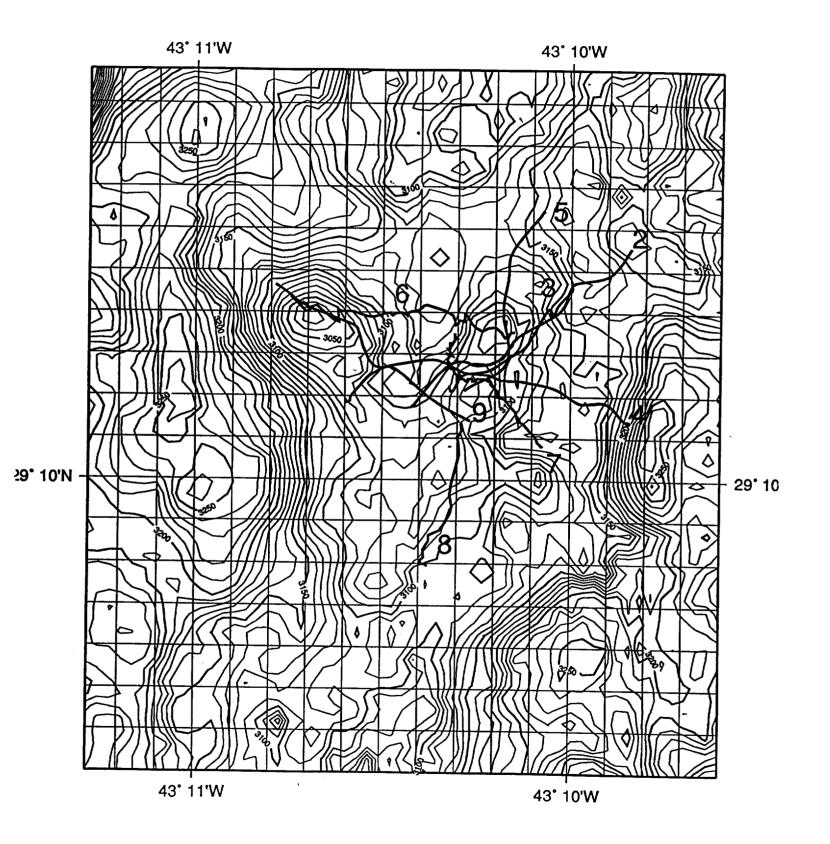


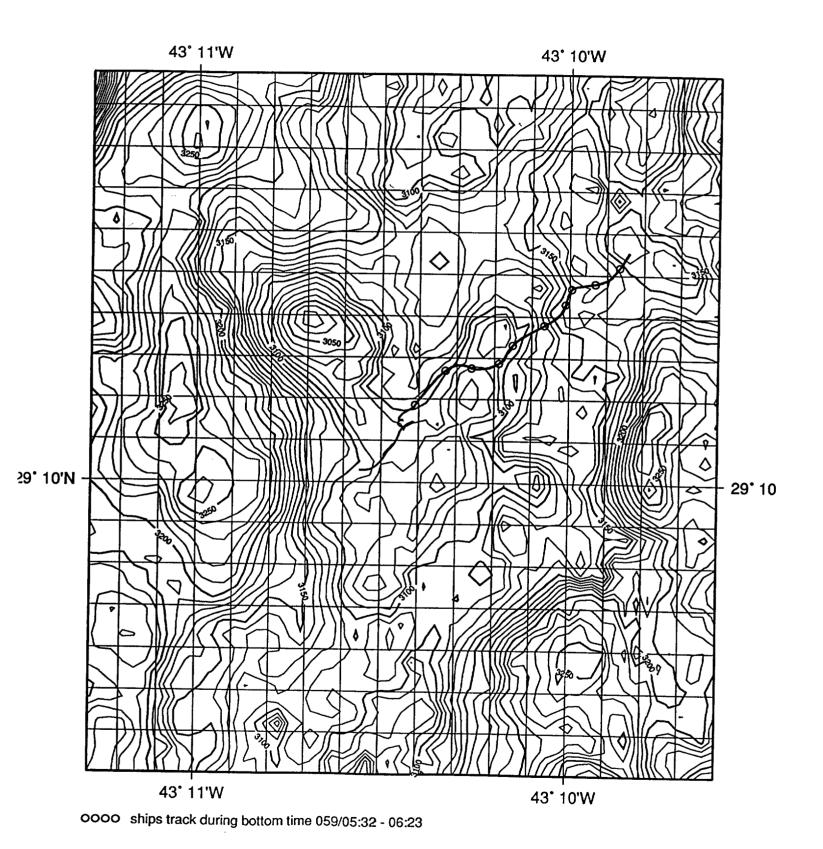
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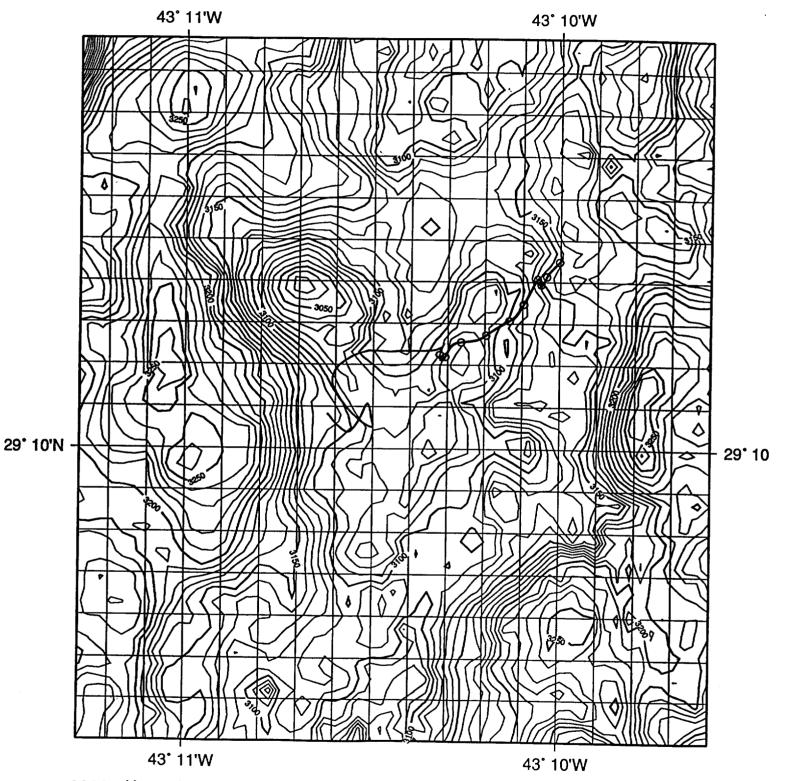




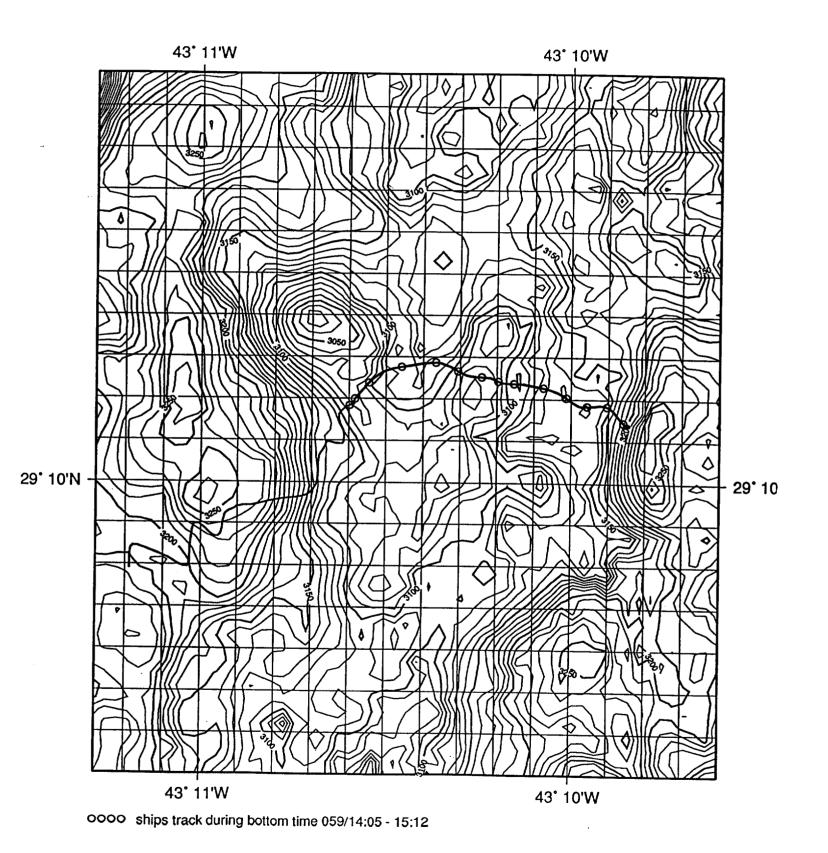
CD-76 Dredge-Tracks

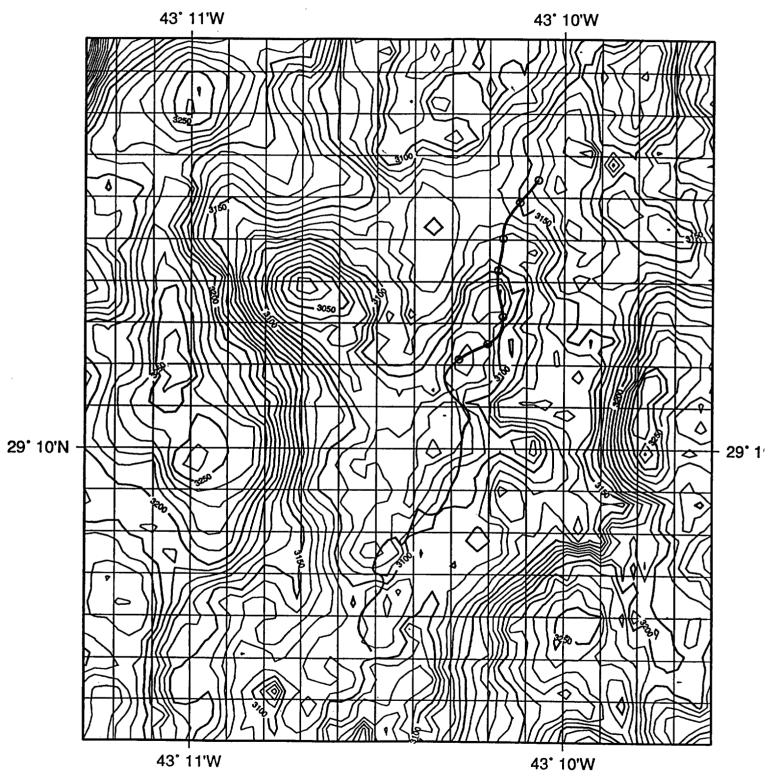




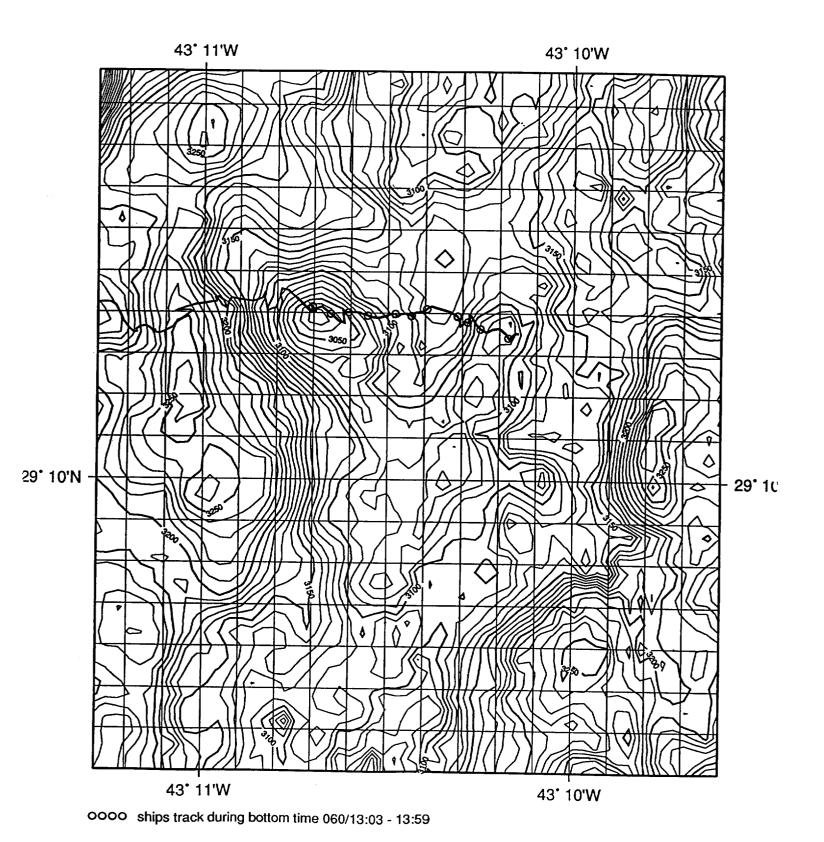


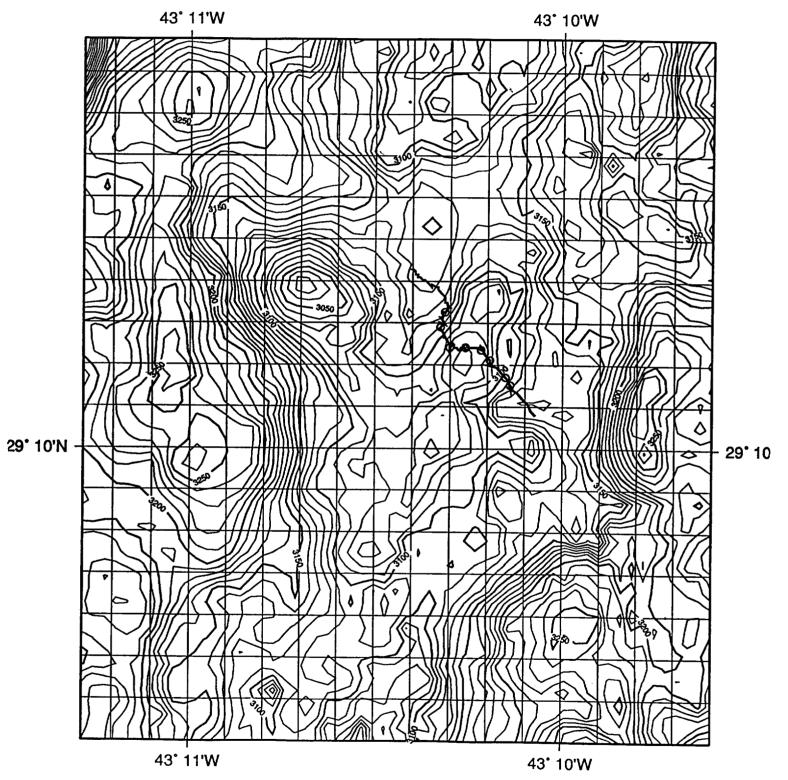
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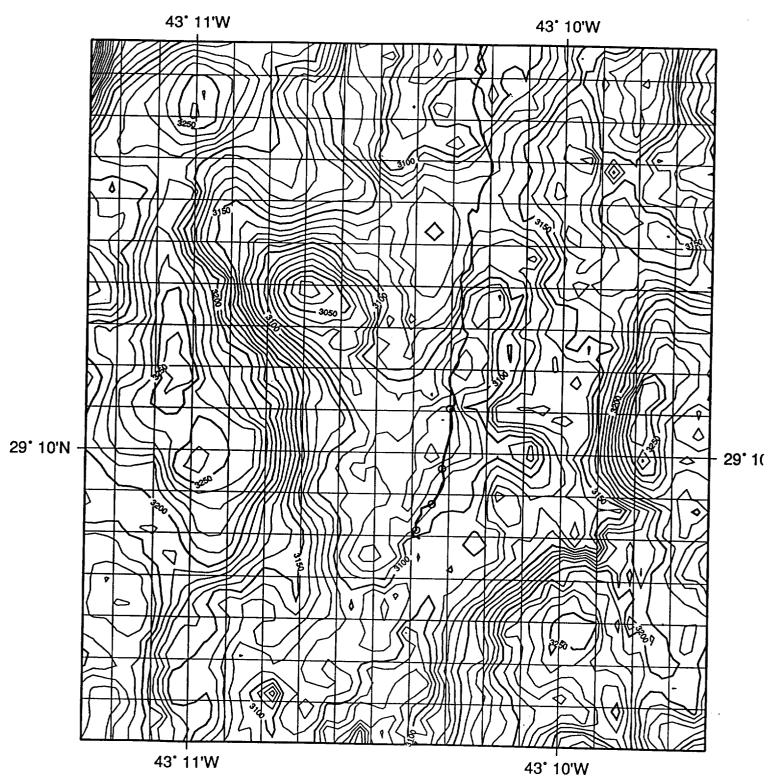


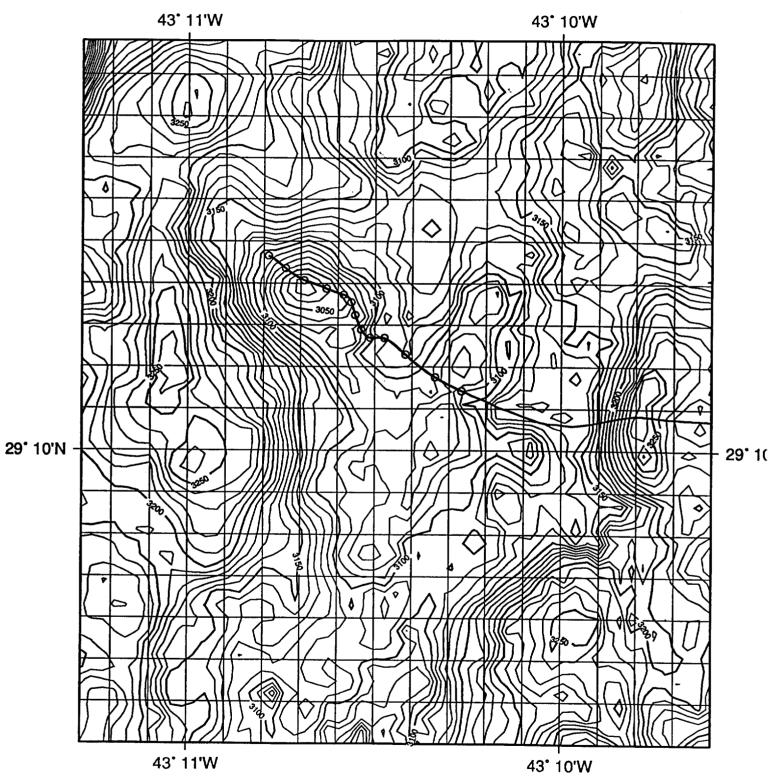
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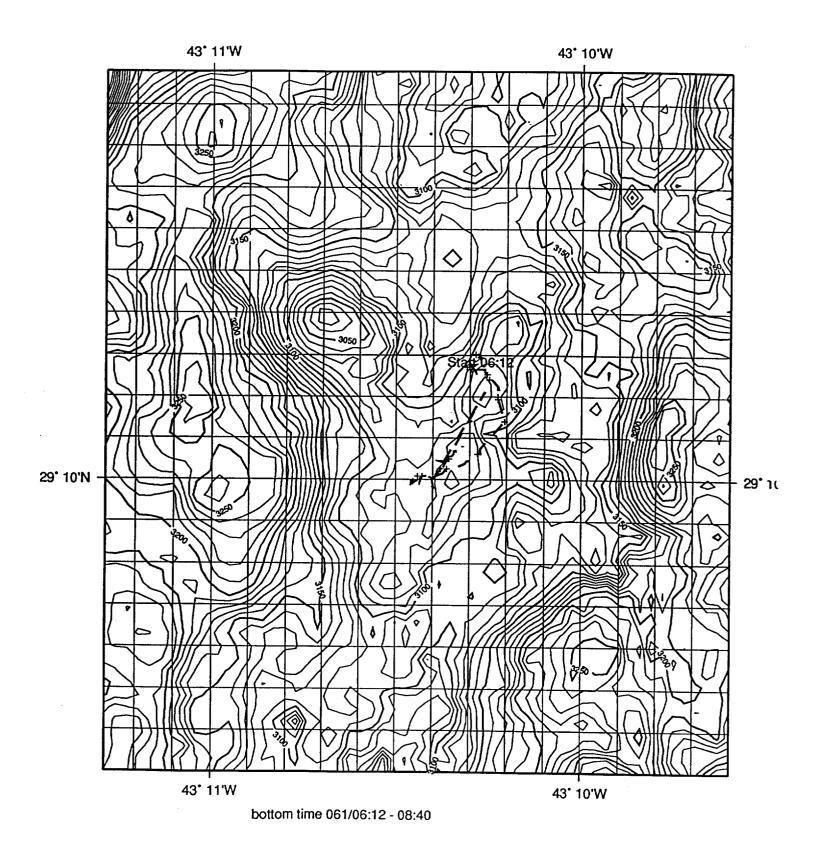


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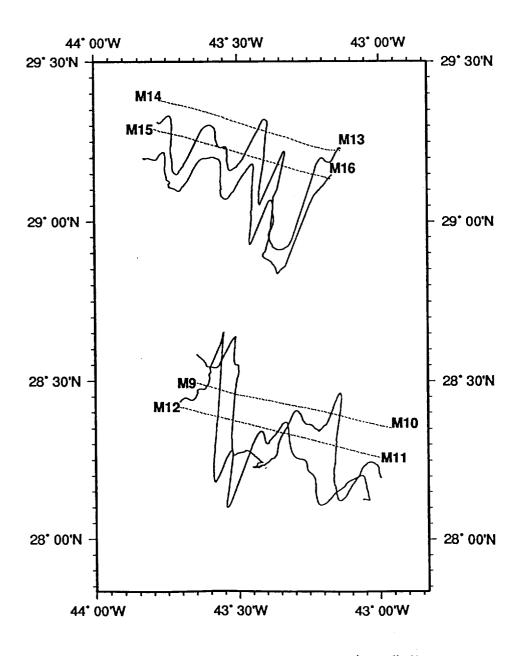




Track ZAPS-Sled No.14



magnetic profiles (200nT/cm)



Appendix5/1

magnetic profiles (200nT/cm)

