

1 RUNNING HEAD: DEEP OBSERVATION OF *SPHYRNA LEWINI*

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3 **Deep water observation of scalloped hammerhead *Sphyrna lewini* in the western Indian**

4 **Ocean off Tanzania**

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20 ABSTRACT

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22 *A scalloped hammerhead Sphyrna lewini was observed opportunistically from a remotely*
23 *operated vehicle 1 m off the seabed at 1042 m depth, during hydrocarbon exploration*
24 *activities in the Ruvuma basin off Tanzania. The observation, which occurred during night*
25 *hours, is the deepest accurately recorded for this species and the first deepwater record for*
26 *the Indian Ocean. The record adds support for occurrence in deep water during night hours*
27 *being a widespread and possibly common behaviour in this species, and further expands a*
28 *small but growing literature that meso- and bathypelagic environments may be of greater*
29 *importance to elasmobranchs previously considered to be primarily epipelagic..*

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31 KEYWORDS

32 Shark, elasmobranch, bathypelagic, Ruvuma Basin, vertical migration

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36 INTRODUCTION

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38 Knowledge of the spatial distribution of any marine organism is essential to understanding its
39 ecology. While the geographic range of many shark species is often (and increasingly) well
40 documented, their vertical distribution can be much less well understood due to the numerous
41 challenges in collecting accurate data. The geographic distribution of the scalloped
42 hammerhead *Sphyrna lewini* (Griffith & Smith, 1834) (n.b. notwithstanding unresolved
43 taxonomy, e.g. Zemplak *et al.*, 2009) is well known, and encompasses a range of habitats from
44 estuaries to the open ocean in tropical and warm temperate waters worldwide (Ebert *et al.*,
45 2013). However, the vertical distribution of *S. lewini* is not as well understood. Compagno *et*
46 *al.*, (2005) cite “surface to >275 m”, and while studies using tagging technology have
47 reported the species to greater depth, accurate depth recording has often been constrained by
48 the limitations of the tagging technology. Using ultrasonic transmitters on four individuals in
49 the Gulf of California, Klimley (1993) recorded repeated excursions to a maximum depth of
50 approximately 475 m. Also in the Gulf of California, Jorgensen *et al.*, (2009) recorded a
51 single *S. lewini* over 74 days diving to depths of at least 980 m with a pop-up satellite
52 archival tag (PSAT). Bessudo *et al.* (2011) recorded occasional night-time dives to
53 approximately 1000 m by a tagged *S. lewini*, in the tropical eastern Pacific. Most recently, an
54 individual female *S. lewini* fitted with a PSAT was recorded as making repeated night-time
55 dives >700 m (with 16 of these >900 m, reaching a maximum depth of 964 m) over a period
56 of 27 days in the Gulf of Mexico (Hoffmayer *et al.*, 2013).. These authors suggested that such
57 diving may be a common behaviour in *S. lewini*, but noted that more data would be required
58 to verify this. The current paper reports an incidental observation of a *S. lewini* individual
59 made from a remotely operated vehicle (ROV) that extends the accurately recorded depth
60 range of this species.

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62 METHODS

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64 Footage was collected opportunistically using Ocean ProHD video camera (1080i) mounted
65 on an Oceaneering International Millennium work class ROV (Mill 113) which was deployed
66 from the *Deepsea Metro I* drill-ship during routine drill-support operations at BG Group's
67 Jordari hydrocarbon exploration site, approximately 40 km off the coast of southern Tanzania
68 in the Ruvuma basin. The video was made available because of BG's involvement in the
69 collaborative SERPENT Project (Jones, 2009) (www.serpentproject.com), in which ROV
70 footage from the oil and gas industry is made available to marine scientists. Water column
71 parameters (temperature, salinity and depth) were collected during the dive with a datalogger
72 on the ROV. In addition temperature, salinity, and dissolved oxygen at a site 30 km distant
73 were recorded from a datalogger (RBR Model XR-420CTDmTi+pH+DO) fitted to the ROV
74 during a SERPENT offshore visit. The shark was identified as scalloped hammerhead shark
75 *Sphyrna lewini* based on a cephalic foil with a median and two smaller lateral indentations
76 and the relative size and shape of fins (Ebert *et al.*, 2013).

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78 RESULTS

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80 The video clip (59 s in length) commenced at 0030 hours local time on 27th September 2012,
81 after the ROV had been working in view of the seabed for over 3.5 hours. Figure 1 presents
82 still images extracted from video footage (Supplementary Material 1), and shows an
83 individual *Sphyrna lewini* swimming just above the seabed at 1043 m depth, making three
84 sharp turns at 5, 20 and 30 seconds into the clip. On each of these occasions it turned back
85 and re-entered the area of seabed illuminated by the lights of the ROV. After 43 seconds the
86 individual left the frame, still swimming close to the seabed, and it was not observed after
87 this. Although no claspers were clearly visible sex could not be confidently determined, and

88 from the scale of nearby seabed markers the total length of the shark was estimated at
89 approximately 1.5 m. Water column temperature was 5.9 °C and salinity was 35. Based on
90 similar temperature and salinity profiles at both the observation site and the site 30 km distant
91 it is estimated that dissolved oxygen would also be similar and approximately 1-1.5 ml l⁻¹
92 (Figure 2). Similar video surveys at other sites near this observation recorded the following
93 biota in low abundance: xenophyophores, sponges, molluscs (cirrate octopods and squid),
94 suprabenthic crustaceans, echinoderms and fishes including grenadiers (Macrouridae), cusk
95 eels and relatives (Ophidiiformes) and cutthroat eels (Synphobranchiidae).

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98 DISCUSSION

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100 Although it cannot be assumed that the single individual we observed at depth originated
101 from surface waters (and therefore represents deep diving behaviour), our report from 1042 m
102 exceeds the previous accurately recorded depth maximum of 964 m for this species
103 (Hoffmayer *et al.*, 2013). It also exceeds the depth of “at least 980 m” (and probably not
104 exceeding 1500 m) recorded by Jorgensen *et al.* (2009), who were not able to report more
105 accurate depths due to limitations of the pressure sensors on the tags used. . The current
106 observation is also the first deepwater record for this species in the Indian Ocean. A further
107 SERPENT observation of *S. lewini* at a near-bottom depth of around 580 m in the Indian
108 Ocean off Western Australia is also of interest (Jones *et al.*, 2009). These records of *S. lewini*,
109 together with those of whale sharks (e.g. Brunnschweiler *et al.*, 2008) and devil rays
110 (Thorrold *et al.*, 2014) add weight to the idea that meso- and bathypelagic environments may
111 be of greater importance than previously thought to taxa traditionally considered as
112 epipelagic.

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114 The current observation was made during the hours of darkness. Although the significance of
115 our single incident should not be overstated, it may add further evidence to previous studies
116 of *S. lewini* that have recorded deep dives almost exclusively during night-time and/or
117 evening twilight Bessudo *et al.* (2011), Hoffmayer *et al.* (2013), and Hoyos-Pallida *et al.*,
118 (2014).

119

120 Water column profiles show that this *S. lewini* individual was recorded in cold (6 °C) waters
121 consistent with the classification of 'hypoxic' (<5.5 mg l⁻¹, equivalent to approximately 3.85
122 ml l⁻¹; n.b. it should be noted that the entire water column deeper than approximately 75 m
123 would also be hypoxic according to these criteria, a result consistent with other studies
124 reporting low oxygen concentrations in the tropical Indian Ocean e.g. Schlitzer, 2000) in
125 experimental work on three shark species, including *Sphyrna tiburo* (L. 1758), a congener of
126 *S. lewini* (Carlson & Parsons 2001;). Both factors are likely to present *S. lewini* with
127 significant physiological challenges, although experimental work has suggested that *S. tiburo*
128 is physiologically able to tolerate moderate levels of hypoxia (Carlson and Parsons, 2003).
129 While endothermy as an adaptation to cold have been reported in other elasmobranch taxa
130 (notably lamnid sharks and mobulid rays), it has not been for hammerhead sharks (Bernal *et*
131 *al.*, 2012), and therefore time at this depth is likely limited. Nevertheless, tolerance of this
132 environment, even for short times, presumably provides benefits; although the purpose
133 remains unclear. It has been suggested that diving of *S. lewini* into cold and potentially
134 anoxic water could be to exploit deepwater prey less accessible to other pelagic competitors
135 (Jorgensen *et al.*, 2009; Hoffmayer *et al.*, 2013), and video footage from nearby areas to our
136 observation showed the presence of likely *S. lewini* prey items (cephalopods and fishes).
137 Most recently, Hoyos-Pallida *et al.*, (2014) suggested that a single *S. lewini* juvenile female

138 tagged in the Gulf of California visited deeper waters (up to 250 m) to increase foraging
139 success and as part of an ontogenetic migration from coastal to offshore waters.

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220 Figure Legends

221

222 **Fig. 1.** Stills from the video of *Sphyrna lewini*: A) Cropped image of the shark as it passed
223 close to the ROV, B) full screen view as the shark swims out of shot close to one of the
224 marker buoys at the seabed.

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226 **Fig. 2.** Water column temperature and salinity at the observation site (red) and temperature,
227 salinity and oxygen profiles at a nearby site.

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231 Figures:

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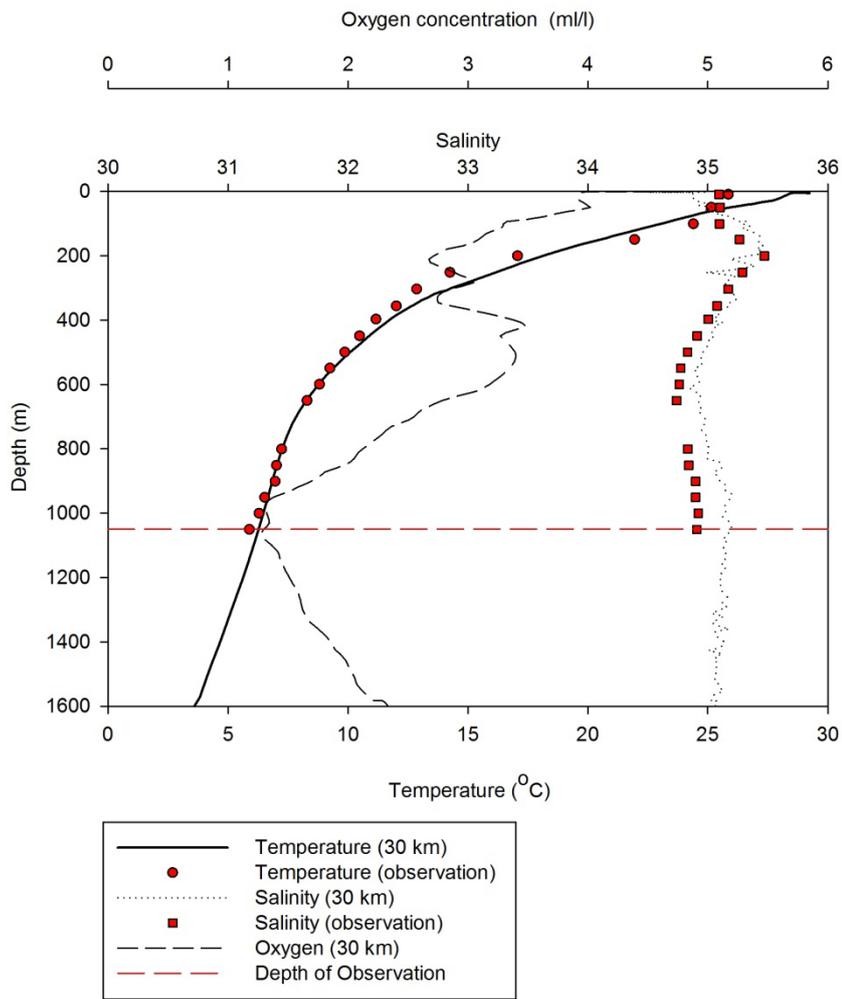
233 Figure 1:



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236 Figure 2:



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240 Appendix:

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242 Video is available for download at: <http://www.serpentproject.com/pubsuppmat1.php>

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